

### E9 203 Compressed Sensing & Sparse SP.

Last time:

- OMP, properties
- Thresholding based algos:
  - Basic thresholding.

Today:

- More thresholding based algos
- Reweighting-based algos

Recall notation:  $\mathbf{z} \in \mathbb{C}^n$

$L_1(\mathbf{z}) = \text{Index set of } n \text{ largest absolute entries of } \mathbf{z}$ .

$H_k(\mathbf{z}) = \mathbf{z}_{L_k(\mathbf{z})}$  = Best  $k$ -term approx of  $\mathbf{z}$ .

Basic Thresholding:

$$\begin{aligned} S^k &= L_k(A^H \mathbf{y}) \\ x^k &= \arg \min_{\mathbf{z} \in \mathbb{C}^n} \{ \| \mathbf{y} - A \mathbf{z} \|_2, \text{ supp}(\mathbf{z}) \subseteq S^k \}. \end{aligned}$$

Iterative Hard Thresholding Algo:

$$\text{Consider: } \underbrace{A^H A \mathbf{z}}_{\mathbf{z}^0} = A^H \mathbf{y}$$

$$\text{Fixed-point eqn: } \mathbf{z} = (I - A^H A) \mathbf{z} + A^H \mathbf{y}$$

$$\text{Fixed-point iteration: } \mathbf{x}^{(n+1)} = \underbrace{(I - A^H A) \mathbf{x}^{(n)}}_{\text{Iterative hard thresholding.}} A^H \mathbf{y}$$

Init:  $\mathbf{x}^{(0)} = 0$

$$\text{Iterate: } \begin{aligned} S^{(n+1)} &= L_k(\mathbf{x}^{(n)} + A^H(\mathbf{y} - A \mathbf{x}^{(n)})) \\ \mathbf{x}^{(n+1)} &= \arg \min_{\mathbf{z} \in \mathbb{C}^n} \{ \| \mathbf{y} - A \mathbf{z} \|_2, \text{ supp}(\mathbf{z}) \subseteq S^{(n+1)} \} \end{aligned}$$

Until a stopping criterion is met at  $\bar{n}$

Output  $\mathbf{x}^k = \mathbf{x}^{(\bar{n})}$

Hard thresholding pursuit:

Init:  $\mathbf{x}^{(0)} = 0$

$$\text{Iterate: } \begin{aligned} S^{(n+1)} &= L_k(\mathbf{x}^{(n)} + A^H(\mathbf{y} - A \mathbf{x}^{(n)})) \\ \mathbf{x}^{(n+1)} &= \arg \min_{\mathbf{z} \in \mathbb{C}^n} \{ \| \mathbf{y} - A \mathbf{z} \|_2, \text{ supp}(\mathbf{z}) \subseteq S^{(n+1)} \} \end{aligned}$$

Until a stopping criterion is met at  $\bar{n}$

Output  $\mathbf{x}^k = \mathbf{x}^{(\bar{n})}$

Compressive Sampling Matching Pursuit (CoSaMP):

Init:  $\mathbf{x}^{(0)} = 0$

$$\text{Iterate: } \begin{aligned} \mathcal{U}^{(n+1)} &= \text{supp}(\mathbf{x}^{(n)}) \cup L_2(A^H(\mathbf{y} - A \mathbf{x}^{(n)})) \\ \mathbf{x}^{(n+1)} &= \arg \min_{\mathbf{z} \in \mathbb{C}^n} \{ \| \mathbf{y} - A \mathbf{z} \|_2, \text{ supp}(\mathbf{z}) \subseteq \mathcal{U}^{(n+1)} \} \end{aligned}$$

$$\mathbf{x}^{(n+1)} = H_{\mathcal{U}^{(n+1)}}(\mathbf{x}^{(n)})$$

Until a stopping criterion is met at  $\bar{n}$ .

Output  $\mathbf{x}^k = \mathbf{x}^{(\bar{n})}$

Matching Pursuit:

$$\mathbf{x}^{(n+1)} = \mathbf{x}^{(n)} + t e_j, \quad t \in \mathbb{C}, \quad j \in [N]$$

choose to min  $\| \mathbf{y} - A \mathbf{x}^{(n)} \|_2$

$$\Rightarrow j = \arg \max_{j \in [N]} |(A^H(\mathbf{y} - A \mathbf{x}^{(n)}))_j|$$

$$t = (A^H(\mathbf{y} - A \mathbf{x}^{(n)}))_j$$

Subspace pursuit:

Init:  $\mathbf{x}^{(0)} = 0, \quad S^0 = \{\emptyset\}$

$$\text{Iterate: } \mathcal{U}^{(n+1)} = S^n \cup L_2(A^H(\mathbf{y} - A \mathbf{x}^{(n)}))$$

$$\mathbf{x}^{(n+1)} = \arg \min_{\mathbf{z} \in \mathbb{C}^n} \{ \| \mathbf{y} - A \mathbf{z} \|_2, \text{ supp}(\mathbf{z}) \subseteq \mathcal{U}^{(n+1)} \}$$

$$\begin{cases} S^{(n+1)} = L_k(\mathbf{x}^{(n+1)}) \\ \mathcal{U}^{(n+1)} = \arg \min_{\mathbf{z} \in \mathbb{C}^n} \{ \| \mathbf{y} - A \mathbf{z} \|_2, \text{ supp}(\mathbf{z}) \subseteq S^{(n+1)} \} \end{cases}$$

Until a stopping criterion is met at  $\bar{n}$ .

Output  $\mathbf{x}^k = \mathbf{x}^{(\bar{n})}$

Soft thresholding pursuit: (When  $\mathbf{x}$  is unknown):

Threshold  $\tau, \quad z_j$  real valued

$$A_\tau(z_j) = \begin{cases} \text{sgn}(z_j)(|z_j| - \tau) & \text{if } |z_j| \geq \tau \\ 0 & \text{else.} \end{cases}$$

Criteria for selecting algorithms:

1. Min. # meas. for recovery.

2. Speed

Low sparsity: OMP is fast

BT, MP are fast

CoSaMP, HTP are fast

$\ell_1$ -min depends on which algo is used to solve  $(P_{\ell_1})$

Chambolle & Pock's primal-dual algo

- Run-time roughly indep of  $A$

Homotopy based methods

- Adds support one by one

- Works better for small  $A$

3. Exploiting the structure of  $A$  / fast vector-matrix mult.

4. Numerical precision demanded by the algo.

5. Robustness to noise or when  $\mathbf{x}$  is not exactly sparse.

6. Parameters that need to be hand-tuned.

Weighted  $\ell_1$ -norm minimization

$W \in \mathbb{R}^{n \times n}$  diagonal, non-negative

$$\min_{\mathbf{z} \in \mathbb{C}^n} \| W \mathbf{z} \|_1 \text{ s.t. } A \mathbf{z} = \mathbf{y}$$

- Reweighting based algo

- Incorporating prior knowledge.

Has an optimal basic feasible soln. (col. of  $A$ )

correct supp of the soln. are  $L_1^+$

Let  $\mathbf{q} \in W^\dagger \mathbf{z}, \quad \mathbf{z} = W \mathbf{q}$

$$\min_{\mathbf{q} \in \mathbb{C}^n} \| \mathbf{q} \|_1 \text{ s.t. } (A W) \mathbf{q} = \mathbf{y}$$

$\Rightarrow \mathbf{x}_0 = W \mathbf{q}_0$  is a BFS if  $\mathbf{q}_0$  is a BFS.

-  $\rightarrow \mathbf{x}_0 \rightarrow \dots \rightarrow \mathbf{x}_m$  (regularizers).

General diversity measure:

$$\min_{\mathbf{z} \in \mathbb{C}^N} g(\mathbf{z}) \text{ s.t. } A\mathbf{z} = \mathbf{y}.$$

$$g(\mathbf{z}) = \sum_{i=1}^N g_i(|z_i|) \quad \text{separable fn.}$$

often  $g_i(\cdot) = g(\cdot)$  for simplicity

$g_i(z_i)$  is monotonically ↑;  $g_i(z)$  is bounded.

$$g(x) = |x|^p, p > 0$$

$$g(x) = \log|x|.$$

Recall: (Real-valued case): reformulate l1 min as an LP:  
 $\mathbf{z} = \mathbf{z}_+ - \mathbf{z}_-, z_+ \geq 0, z_- \geq 0, \mathbf{w} = \begin{bmatrix} z_+ \\ z_- \end{bmatrix} \in \mathbb{R}^{2N}$

Result: (P<sub>G1</sub>) and (P<sub>G2</sub>) below are equivalent, in the sense that  $\exists$  a 1-1 mapping betw their local minima.

Further, the objective fns are equal at corresponding local minima.

$$(P_{G1}): \min_{\mathbf{z} \in \mathbb{R}^N} J(\mathbf{z}) = \sum_{i=1}^N g_i(z_i) \text{ s.t. } A\mathbf{z} = \mathbf{y}$$

$$(P_{G2}): \min_{\mathbf{w} \in \mathbb{R}^{2N}} J(\mathbf{w}) = \sum_{i=1}^N \{g_i(z_{+,i}) + g_i(z_{-,i}) - g_i(0)\}$$

$$\text{s.t. } [A \ -A] \begin{bmatrix} z_+ \\ z_- \end{bmatrix} = \mathbf{y}; \mathbf{w} = \begin{bmatrix} z_+ \\ z_- \end{bmatrix} \geq 0.$$

We will focus on (P<sub>G2</sub>).

-  $g(x)$  is strictly concave

$$- [A \ -A] \begin{bmatrix} z_+ \\ z_- \end{bmatrix} = \mathbf{y}: \text{convex set } K \quad \text{convex polygon.}$$

Extreme pts: Ones that cannot be written as a convex linear combination of distinct pts.  $\in K$ .