Journal Watch IEEE Transactions on Wireless Communications, October 2018

Sai Subramanyam Thoota

SPC Lab, Department of ECE Indian Institute of Science

November 3, 2018

(Sai Subramanyam Thoota, ECE, IISc)

IEEE TWC, October 2018

November 3, 2018 1 / 11

Image: A mathematical states and a mathem

Joint Unicast and Multi-Group Multicast Transmission in Massive MIMO Systems - Meysam Sadeghi et al.

Goal

• To maximize the weighted spectral efficiency of the unicast user terminals (UT) and minimum spectral efficiency (SE) of the multicast UTs

Contributions

- Closed form expressions for the achievable SE of each unicast and multicast UTs in the system
- Formulate the problem of maximizing the SSE of the unicast UTs and the max-min fairness (MMF) problem for the multicast UTs
- MMF and SSE problems are coupled in a conflicting manner. Hence, a multiobjective optimization problem (MOOP) is formulated for the joint unicast and multicast transmission
- Derive the pareto boundary of the MOOP analytically

System Model

- Single cell with N antenna base station (BS)
- U single antenna unicast UTs and G multicasting groups (group g contains K_g single antenna UTs)
- Block fading channel model
- Orthogonal pilots for unicast UTs and multicast groups (one pilot per group)

イロト 不得 とくほ とくほ とうほう

- MMSE channel estimation
 - No pilot contamination of unicast UT channels
 - For multicast UTs, the channel estimates are equivalent up to a scalar coefficient
- Achievable spectral Efficiencies for MRT and ZF precoding

$$\mathrm{SINR}_{m,un}^{\mathrm{MRT}} = \frac{N p_m^{dl} \vartheta_m}{1 + \beta_m (P_{un} + P_{mu})}$$

$$\mathrm{SINR}_{jk,mu}^{\mathrm{MRT}} = \frac{Nq_j^{dl}\xi_{jk}}{1 + \eta_{jk}(P_{mu} + P_{un})}$$

$$\mathrm{SINR}_{m,un}^{\mathrm{ZF}} = \frac{(N-G-U)\rho_m^{dl}\vartheta_m}{1+(\beta_m-\vartheta_m)(P_{un}+P_{mu})}$$

$$\mathrm{SINR}_{jk,mu}^{\mathrm{ZF}} = \frac{(N-G-U)q_j^{dl}\xi_{jk}}{1+(\eta_{jk}-\xi_{jk})(P_{un}+P_{mu})}.$$

Optimal Resource Allocation

$$\begin{aligned} \mathcal{P}1: & \underset{\{q_j^{dl}\}, \{q_{jk}^{qp}\}, \tau}{\text{maximize}} & \underset{j \in \mathcal{G}, k \in \mathcal{K}_j}{\min} \operatorname{SE}_{jk, mu}^{\dagger} \\ & \text{s.t.} & \sum_{j=1}^{G} q_j^{dl} \leq P - P_{un} \\ & 0 \leq q_j^{dl} \\ & 0 \leq \tau q_{jk}^{up} \leq E_{jk} \\ & \tau \in \{U + G, \dots, T\} \end{aligned}$$

$$\mathcal{P}2: \underset{\{p_m^{dl}\}, \{p_m^{u}\}, \tau}{\text{maximize}} \sum_{m=1}^{U} \alpha_m \text{SE}_{m,un}^{\dagger}$$

s.t.
$$\sum_{m=1}^{U} p_m^{dl} \leq P - P_{mu}$$
$$0 \leq p_m^{dl}$$
$$0 \leq \tau p_m^{up} \leq E_m$$
$$\tau \in \{U + G, \dots, T\}$$

• Theorems to prove that, at the optimal point, all the multicast UTs attain the same SE

IEEE TWC, October 2018

- \bullet Solutions to $\mathcal{P}1$ and $\mathcal{P}2$ are coupled in a conflicting manner
- To balance the two objectives, a MOOP is formulated

$$\mathcal{M}: \max_{\mathbf{x}} [O_{mu}(\mathbf{x}), O_{un}(\mathbf{x})]^T$$

s.t. $\mathbf{x} \in \mathcal{X}$

where

$$\begin{aligned} \mathcal{X} = & \left\{ \left(\{q_j^{dl}\}, \{q_{jk}^{up}\}, \{p_m^{dl}\}, \{p_m^{up}\}, \tau \right) \ | \ 0 \le q_j^{dl}, 0 \le \tau q_{jk}^{up} \le E_{jk}, 0 \le p_m^{dl}, \ 0 \le \tau p_m^{up} \le E_m, \\ & P_{un} + P_{mu} \le P, \tau \in \{U + G, \dots, T\} \right\}. \end{aligned}$$

• Pareto boundary (System designer can choose any point based on the requirement)

Theorem

The MOOP (45) of the considered joint unicast and multi-group multicast massive MIMO system with either MRT or ZF precoding, does not have any weak Pareto optimal points and its strong Pareto boundary is analytically described by

$$\mathcal{B}_{s} = \bigg\{ (O_{mu}^{*}(P_{un}), O_{un}^{*}(P_{mu})) \mid P_{mu} + P_{un} = P, 0 \le P_{mu} \le P, 0 \le P_{un} \le P \bigg\}.$$

Moreover, $(O_{mu}^{s}(P_{un}), O_{un}^{s}(P_{mu})) \in B_s$ is achieved when $(q_j^{dl*}, q_{jk}^{up*}, p_m^{dl*}, p_{up*}^{up*}, \tau^*)$ are obtained either from Theorems 1 and 3 for MRT precoding, or from Theorems 2 and 4 for ZF precoding.

Low-Complexity Statistically Robust Precoder/Detector Computation for Massive MIMO Systems - Mahdi Nouri Boroujerdi et al.

Goal

• To design the precoder/detector in a massive MIMO system without the knowledge of the channel statistics

Contributions

- Proposed a novel technique for designing precoding/detection matrices in a massive MIMO system based on the randomized Kaczmarz algorithm (KA)
- Extension of the randomized KA (used to solve the overdetermined (OD) set of linear equations (SLE)) to solve the underdetermined (UD) SLE and used it for massive MIMO applications
- Theoretical performance analysis
- Comparison of the performance with techniques based on random matrix theory and approximate message passing via numerical simulations
 - Comparable performance with low complexity
 - No knowledge of channel statistics

Problem Statement

• To reduce the complexity of the detector/precoder computation in the massive MIMO system

• Kaczmarz Algorithm to solve Aw = b

Algorithm 1 Kaczmarz Algorithm

1: Initialize \mathbf{w}^0 .

2: for
$$t = 0, 1, \dots, T - 1$$
 do

- 3: Pick a row r(t) of **A** denoted by the row vector $\mathbf{a}_{r(t)}^{\mathsf{H}}$. \triangleright In [27], each row *i* of the matrix **A** is selected randomly with the probability $\frac{\|\mathbf{a}_i\|^2}{\|\mathbf{A}\|^2}$.
 - Update \mathbf{w}^t as $\mathbf{w}^{t+1} = \mathbf{w}^t + \frac{b_{r(t)} \langle \mathbf{a}_{r(t)}, \mathbf{w}^t \rangle}{\|\mathbf{a}_{r(t)}\|^2} \mathbf{a}_{r(t)}$.

 \triangleright After the update, $\langle \mathbf{a}_{r(t)}, \mathbf{w}^{t+1} \rangle = b_{r(t)}$, and r(t)-th equation is fulfilled.

5: end for

4:

• Each Kaczmarz update obeys the minimum energy perturbation principle

• At each iteration *t*, KA finds the closest vector **w** to the current solution **w**^{*t*} that satisfies the slected equation

$$\mathbf{w}^{t+1} = \arg\min_{\mathbf{w}} ||\mathbf{w} - \mathbf{w}^t||^2 \quad \text{s.t} < \mathbf{a}_{r(t)}, \mathbf{w} >= b_{r(t)}$$
(1)

Unified Mathematical Framework:

- Unified approach to analyze the performance of all variants of KA studied in this paper
- Convergence rate of KA depends on the choice of the probability distribution with which we choose the rows in each iteration
- Optimal probability distribution depends on the average gain of the matrix A (more details in the paper). But solving this is an SDP, whose complexity is of the same order as computing the precoder/detector matrices directly
- Suboptimal probability distribution chosen as $p_i = ||\mathbf{a}_i||^2 / ||\mathbf{A}||_F^2$
 - $\bullet\,$ Convergence rate depends on the normalized minimum gain of the matrix ${\bf A}$ along the subspace spanned by the columns of ${\bf A}^H$

$$\kappa_{\mathcal{X}}(\mathbf{A}) = \min_{\mathbf{x} \in \mathcal{X}, \mathbf{x} \neq 0} \frac{\|\mathbf{A}\mathbf{x}\|^2}{\|\mathbf{A}\|_{\mathcal{F}}^2 \|\mathbf{x}\|^2}$$
$$\mathbb{E}[\|\mathbf{x}^t - \mathbf{x}^*\|^2] \le (1 - \kappa_{\mathcal{X}}(\mathbf{A}))^t \|\mathbf{x}^0 - \mathbf{x}^*\|^2$$

Kaczmarz Algorithm for MMSE/ZF Detection:

- ℓ_2 regularized least squares cost function $||Qw y||^2 + \xi ||w||^2$ can be written as $||Bw y_0||^2$, where $B = [Q; \sqrt{\xi} I_K]$ and $y_0 = [y; 0]$
- Inconsistent equations due to noise in the observations. Randomized KA will result in residual errors. To avoid that:

$$\widehat{\mathbf{y}}_{0} = \mathbf{B}\widehat{\mathbf{s}} \stackrel{(i)}{=} \mathbf{B}(\mathbf{B}^{\mathsf{H}}\mathbf{B})^{-1}\mathbf{B}^{\mathsf{H}}\mathbf{y}_{0} = \mathbf{B}(\mathbf{B}^{\mathsf{H}}\mathbf{B})^{-1}\mathbf{Q}^{\mathsf{H}}\mathbf{y}$$
$$\mathbf{B}^{\mathsf{H}}\widehat{\mathbf{y}}_{0} = (\mathbf{B}^{\mathsf{H}}\mathbf{B})(\mathbf{B}^{\mathsf{H}}\mathbf{B})^{-1}\mathbf{Q}^{\mathsf{H}}\mathbf{y} = \mathbf{Q}^{\mathsf{H}}\mathbf{y}, \qquad (21)$$

 \bullet Solve the OD SLE $B\hat{s}=\hat{y_0}$ to get the estimate \hat{s}

< ロ > < 同 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

Downlink Performance of Superimposed Pilots in Massive MIMO Systems - Karthik Upadhya et al.

Goal

• To investigate the downlink throughtput performance of a massive MIMO system that employs superimposed pilots (SP)¹ for channel estimation

Contributions

- Closed-form expressions for the DL achievable rate when the LS channel estimates obtained from SP are employed in a matched filter (MF) precoder at the base station (BS)
- Relationship between staggered pilots and SP and derived the DL rate for the former scheme
- Derived expressions for the NMSE and compared it against the Bayesian-CRLB
- Hybrid system design (UEs transmit both regular pilots and SP) for the DL by minimizing the UL and DL interference

System Model: TDD, L cells, K single-antenna users per cell, BS with M antennas

Uplink

$$\boldsymbol{Y}_{j} = \sum_{\ell=0}^{L-1} \sum_{k=0}^{K-1} \sqrt{\mu_{\ell k}} \boldsymbol{h}_{j \ell k} \boldsymbol{s}_{\ell k}^{T} + \boldsymbol{W}_{j}$$

Downlink

$$\widehat{d}_{jm} = \sqrt{\gamma} \sum_{\ell=0}^{L-1} \boldsymbol{h}_{\ell jm}^{H} \sum_{k=0}^{K-1} \sqrt{\nu_{\ell k}} \boldsymbol{g}_{\ell k} d_{\ell k} + w_{jm}$$

¹Both pilots and data transmitted together

< ロ > < 同 > < 回 > < 回 >

- Effect of pilot contamination on the downlink
 - Regular Pilots (Orthogonal pilots+non overlapping data)
 - Both the LS channel estimate NMSE and DL SINR (with MF precoding) doesn't depend asymptotically on the number of BS antennas (M)
 - Superimposed Pilots (Orthogonal pilots+overlapping data during the whole frame)
 - With an optimized pilot and data power allocation, NMSE reduces proportional to √M and if cell reuse factor is more than that of the RP case, then the DL SINR is higher than that of DL SINR with RP (asymptotically)
 - Staggered Pilots (Orthogonal pilots+overlapping data only for the pilot duration)
 - Can achieve the asymptotic DL performance of RP with a reuse factor of SP with an overhead equivalent to that of RP (with a reuse factor of RP)
 - UL spectral efficiency of RP
- Hybrid System
 - RP outperforms SP when the UEs are close to the BS
 - Two sets of users that transmit RP and SP
 - Assumption is that users in RP and SP groups do not interfere with each other (Interference cancellation of RP users needs to be done if this assumption does not hold)
 - Optimization problem to partition the users into RP and SP groups (to minimize the UL and DL interference)
 - · Greedy algorithm from an earlier reference extended to solve this problem

< ロ > < 同 > < 回 > < 回 >

Other Interesting Papers

- Distributed Precoding Systems in Multi-Gateway Multibeam Satellites: Regularization and Coarse Beamforming
- Sum-Rate Maximization Methods for Wirelessly Powered Communication Networks in Interference Channels
- Bandwidth and Energy-Aware Resource Allocation for Cloud Radio Access Networks
- A NOMA Scheme for a Two-User MISO Downlink Channel With Unknown CSIT
- An Efficient Uplink Multi-Connectivity Scheme for 5G Millimeter-Wave Control Plane Applications
- Interference Coordination for 3-D Beamforming-Based HetNet Exploiting Statistical Channel-State Information
- Achievable Rate With 1-Bit Quantization and Oversampling Using Continuous Phase Modulation-Based Sequences

< ロ > < 同 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >