## Monte Carlo Tree Search for Simultaneous Ascending Auctions

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## 13 juillet 2022

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**SPCOM 2022** 

## **Motivations**

#### Bidding efficiently in Simultaneous Ascending Auctions is a hot topic

- SAA has become the privilege mechanism used for spectrum auctions since its introduction in 1994 by the FCC in US
- SAA has recently been used in many countries for 5G licences (Germany [Bundesnetzagentur, 2022], Italy [European 5G Observatory, 2018], etc)
- Paul Milgrom and Robert Wilson received the Nobel Prize in Economy in 2020 mainly for their contribution to SAA (mechanism design) [Milgrom, 2000]

#### Gap in literature regarding how to bid efficiently in SAA

- Auction theory or exact game resolution methods are unable to compute the optimal bidding strategies due to the high complexity of the game.
- Strategical issues have always been studied separately generally in specific contexts and simplified versions of SAA [Goeree and Lien, 2014, Zheng, 2012, Brusco and Lopomo, 2002]

 $\Rightarrow$  We propose a tree-search approach to the bidder strategy problem **tackling** simultaneously two strategical issues : *exposure* and *own price effect*.

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## Outline



## 2 Bidding strategies

3 Monte Carlo Tree Search

#### 4 Numerical Results

### 5 Conclusion

## Simultaneous Ascending Auctions (SAA)

#### Brief Presentation of SAA [Milgrom, 2000, Cramton et al., 2006]

- It is an auction mechanism where *m* indivisible goods are sold via **separate and concurrent English auctions** between *n* bidders
- Bidding occurs in multiple rounds
- At each round :
  - Bidders submit their bids simultaneously, *activity rules* may constrain bidders to play (avoid wait-and-see strategy)
  - For every item *j* : The bidder having placed the highest bid becomes its temporary winner (ties randomly broken) and its bid price *P<sub>j</sub>* is set to the highest bid
  - The temporary winner and bid price of each item is revealed, the minimal admissible bid for the next round is  $P_j + \varepsilon$  ( $\varepsilon$  bid increment)
- Until : no new bids are submitted during a round on any object (*closing rule*)
- After closing : the objects are sold at the bid prices to the corresponding winners

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## Deterministic SAA with complete information

#### Brief Presentation of d-SAA with complete information

- Bidders take turns bidding (no more simultaneity and stochasticity)
- Temporary winner and bid price P<sub>j</sub> are announced after each turn
- New bids are constrained to be P<sub>j</sub> + ε (discrete action space)[Goeree and Lien, 2014, Wellman et al., 2008]
- The value function of the bidders are common knowledge [Szentes and Rosenthal, 2003a, Szentes and Rosenthal, 2003b]

 $\Rightarrow$  d-SAA is a sequential deterministic game with perfect and complete information

#### Game complexities [Van Den Herik et al., 2002]

Ex : 5G auction in Italy in 2018, m = 12 items, n = 5 bidders, R = 171 rounds

- State space complexity :  $\sum_{i'=0}^{n-1} (1 + \sum_{i=0}^{n-1} (R i i')^+)^m \mathbf{1}_{\{R \ge i'\}}$  (ex : 10<sup>35</sup>)
- Game tree complexity  $:>2^{m(n-1)\lfloor \frac{R}{n}\rfloor}$  (ex : 10<sup>491</sup>)

## Comparison of SAA and d-SAA extensive form

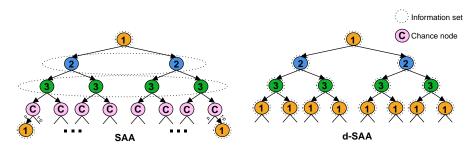


Figure – Comparison of SAA and d-SAA extensive form

 $\Rightarrow$  Conception of simpler tree-search algorithms in d-SAA

## Utility and value functions

#### Value functions

Each player *i* is defined by its value function  $v_i$  which respects the following properties :

- Normalisation :  $v_i(\emptyset) = 0$ ; Finite :  $\forall X, v_i(X) < +\infty$
- Free disposal :  $\forall X, Y, X \subset Y$  implies  $v_i(X) \leq v_i(Y)$  [Milgrom, 2000]

#### **Complements and substitutes**

• A set of goods X exhibits complementarities with a disjoint set of goods Y if v(X + Y) > v(X) + v(Y)

• A set of goods X exhibits substitutabilities with a disjoint set of goods Y if v(X + Y) < v(X) + v(Y)

#### Utility function

At the end of the auction, if player i wins the set of goods X and the bid price vector is P, then its utility is :

$$\sigma_i(X, P) = v_i(X) - \sum_{j \in X} P_j$$

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## Exposure problem

#### Definition

The exposure problem refers to the possibility that, by bidding on a set of complementary goods, a bidder ends up paying more than its valuation for the subset it actually wins as the goods have become too expensive

#### Example 1

	$v(\{1\})$	v({2})	$v(\{1,2\})$
Player 1	12	12	12
Player 2	0	0	20

- A rational strategy for player 1 is :
  - To pass its turn if currently winning an item or the bid price of both items is greater than  $12 \varepsilon$  (e.g.  $\varepsilon = 1$ )
  - To bid on the cheapest item otherwise
- Given the fact that player 1 plays rationally, if player 2 bids on an item, player 2 will end up exposed as it will not be able to acquire both items for a price inferior to 22

 $\Rightarrow$  No efficient bidding strategy is known to avoid this problem in the general case

## Own price effect

#### Definitions

- Own price effect : Each bid on an item increases its price and decreases the utility of bidders willing to acquire it. Each bidder has its *own effect* on the prices [Weber, 1997]
- **Demand reduction strategy** [Weber, 1997, Ausubel et al., 2014] : Reduce demand to keep prices low and coordinate on a split of the items (this is a *collusion* [Brusco and Lopomo, 2002])

#### Example 2 ( $\varepsilon = 1$ )

	$v(\{1\})$	v({2})	$v(\{1,2\})$
Player 1	10	10	20
Player 2	10	10	20

- If players don't form a collusion, the final bid price of each item will be 10. Both players end up with a utility of 0.
- If players form a collusion, then they both acquire an item for a price of  $\varepsilon = 1$  and end up with a utility of 9.

## Outline

Simultaneous Ascending Auctions (SAA)

## 2 Bidding strategies

3 Monte Carlo Tree Search

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## Point price prediction bidding

Point-price prediction bidding (PP) [Wellman et al., 2008]

• A point-price prediction bidder (PP) computes the subset of goods

$$X^* = rgmax_X \sigma(X, 
ho(\mathcal{B}))$$

breaking ties in favour of smaller subsets and lower-numbered goods.

- The bidder bids  $P_j + \varepsilon$  on all items j that it is not currently winning in  $X^*$ .
- The function  $\rho : \mathcal{B} \to \mathbf{R}_{+}{}^{m}$  maps the bidder's information state  $\mathcal{B}$  to an estimation of the final price vector  $\rho(\mathcal{B})$ .
- $\rho$  may use only the initial estimation of the final price vector  $\rho(\mathcal{B}_0)$  :

$$\rho_j(\mathcal{B}) = \begin{cases} \max(\rho_j(\mathcal{B}_0), P_j) & \text{if winning good } j \\ \max(\rho_j(\mathcal{B}_0), P_j + \varepsilon) & \text{otherwise} \end{cases}$$

#### Straightforward Bidding (SB) [Milgrom, 2000]

The Straightforward Bidding strategy (SB) corresponds to a PP with null initial estimation of the final price vector ( $\rho(B_0) = 0$ )

## Predicting the final price vector

#### Walrasian equilibrium

- $D_i(p) = \operatorname{argmax}_X \sigma(X, p)$  is the demand set of bidder *i* at price *p*
- A Walrasian equilibrium is a price vector p and an allocation  $(X_1, ..., X_n)$  such that  $X_i \in D_i(p)$  for every bidder i and all items are allocated (market clearance)
- Walrasian equilibrium doesn't always exist (ex : Example 1)

### Expected Price equilibrium (EPE) [Wellman et al., 2008]

• EPE : Tâtonnement process used to find a Walrasian equilibrium if it exists.

 $p(t+1) = p(t) + \alpha(t)(x(p(t)) - 1)$  (x the demand function)

• Problem : Does not take in account the auction's mechanism

#### Self-Confirming Point Price Prediction [Wellman et al., 2008]

A Self-Confirming Point Price Prediction is a price vector p such that, if all bidders play PP with initial estimation  $\rho(\mathcal{B}_0) = p$ , the final price vector is equal to p. It does not always exist (ex : Example 1).

## Outline

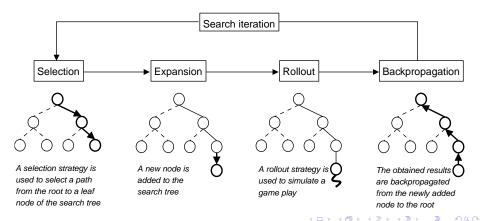
- Simultaneous Ascending Auctions (SAA)
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Monte Carlo Tree Search

## Monte Carlo Tree Search (MCTS)

#### Search Tree

As it is impossible to explore the whole game tree, only a small portion of it is explored. In MCTS, it is constructed iteratively.



## MCTS

#### Success and theoretical guarantees in two-player zero-sum deterministic games

- **Theoretical guarantees**: It has been shown that the probability of playing a suboptimal action with the MCTS variant *Upper Confidence bounds applied to Trees* (UCT) converges to zero at polynomial rate as the number of search iterations grows to infinity [Kocsis and Szepesvári, 2006].
- Great success in various games such as Go [Coulom, 2006, Lee et al., 2009] or Othello [Robles et al., 2011].
- In March 2016, the algorithm **AlphaGo** beats the world champion of Go 4-1 [Silver et al., 2016]

 $\Rightarrow$  d-SAA is a n-player non-zero sum game. No theoretical guarantees regarding MCTS exist for such games. We use the MCTS-*max*<sup>n</sup> which is the most popular variant for such games [Nijssen, 2013].

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Image: A matrix and a matrix

## Selection phase

#### Selection index

We use a penalised variant of UCT. At parent node y, our selection strategy chooses the child x with the highest score  $q_x$ :

$$q_{x} = \frac{r_{x}}{n_{x}} + \max(b_{x} - a_{x}, \varepsilon) \sqrt{\frac{2\log(n_{y})}{n_{x}}} - no\_object(x) - risky\_move(x)$$
(1)

where

- r<sub>x</sub> is the sum of rewards found in the subtree with root x
- n<sub>x</sub> is the number of visits of child node x
- n<sub>y</sub> is the number of visits of parent node y
- ε is the bid increment
- $a_x$  is the estimated lower bound of the reward support found in the subtree with root x
- *b<sub>x</sub>* is the estimated higher bound of the reward support found in the subtree with root *x*

## Selection : First penalty term

#### Penalty term no \_object

- **Objective** : Discourage bidders to pass their turn if they have got nothing to lose by bidding on an additional item.
- A player i' will no longer bid on an item j if  $\forall X \in S_{-j}, P_j \ge v_{i'}(X + \{j\}) v_{i'}(X)$
- $\Pi_j^i = \max_{i' \in \{1,...,n\} \setminus \{i\}} \max_{X \in S_{-j}} v_{i'}(X + \{j\}) v_{i'}(X)$  is the minimal price from which item j is considered as undesired by all opponents of i.
- Let P<sup>x</sup> be the price vector at child node x, i the player bidding at parent node y and X<sup>i</sup><sub>x</sub> the set of goods temporarily won by player i at x

$$no\_object(x) = \begin{cases} \max_{j \in \{1,...,m\} \setminus X_x^i} (v_i(X_x^i + \{j\}) - v_i(X_x^i) - P_j - \varepsilon)^+ \\ \text{if } \{j' \in X_x^i, P_x^{j'} < \Pi_{j'}^i\} = \emptyset \\ 0 \quad \text{otherwise} \end{cases}$$
(2)

## Selection : Second penalty term

#### Penalty term risky move

- **Objective** : Deter players from bidding on sets of goods which might lead to exposure.
- A set of goods X is said to lead to exposure at price vector p if  $\exists Y \subseteq X, \sigma_i(Y, p) < 0$
- Let  $P^x$  be the price vector at child node x, r the root player, i the player bidding at parent node y and  $X_x^i$  the set of goods temporarily won by player i at node x

 $risky\_move(x) = \begin{cases} \lambda^r v_i(\{1,...,m\}) & \text{if } X_x^i \text{ can lead to exposure for } i = r \text{ at price } P^x \\ \lambda^o v_i(\{1,...,m\}) & \text{if } X_x^i \text{ can lead to exposure for } i \neq r \text{ at price } P^x \\ 0 & \text{otherwise} \end{cases}$ 

- $\lambda^r$  and  $\lambda^o$  have opposite effects on the algorithm's risk aversion
  - $\lambda^r$  controls the risk aversion of the root player
  - $\lambda^o$  controls the risk aversion of the root player's opponents

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## Rollout phase

- The default rollout strategy is to play randomly. However, in d-SAA, it leads to absurd outcomes with potentially very high prices.
- Our rollout strategy is PP with a new method to estimate the final price vector  $\rho(\mathcal{B}_0)$

$$p(t+1) = \frac{1}{t+1}f(p(t)) + (1 - \frac{1}{t+1})p(t)$$

where f(p) is the final price vector obtained when all players play PP with initial prediction p

- p(t) always converges when m = n = 2 and items exhibit complementarities
- We conjecture the convergence in the general case

#### Rollout algorithm :

- Compute the limit  $P^*$  of p(t).
- Set ρ(B<sub>0</sub>) = P\* + η where η is a random variable which follows a bounded uniform distribution (introduce diversity and improve sampling)
- Simulate PP with this estimation.

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## Simulation settings

- MCTS settings :  $\lambda_r = \lambda_o = 0.07$  (grid-search)
- We compare to SB [Milgrom, 2000], EPE [Wellman et al., 2008], SCPD [Wellman et al., 2008], UCB (with no selection penalties) and MCTS<sup>np</sup> with no selection penalties
- Each algorithm is given a maximum of 30 seconds CPU thinking time.

## Test experiment : Exposure

	$v(\{1\})$	v({2})	$v(\{1,2\})$
Player 1	12	12	12
Player 2	0	0	20

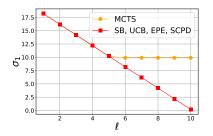
**Table** – Example 1

- MCTS, MCTS<sup>np</sup>, UCB and EPE suggest player 2 not to bid and, hence, avoids exposure.
- SB and SCPD expose player 2 by inciting player 2 to bid on both items
- MCTS is able to avoid obvious exposure.

## Test experiment : Own price effect

	$v(\{1\})$	v({2})	$v(\{1,2\})$
Player 1	h	h	2 <i>h</i>
Player 2	$\ell$	$\ell$	2\ell

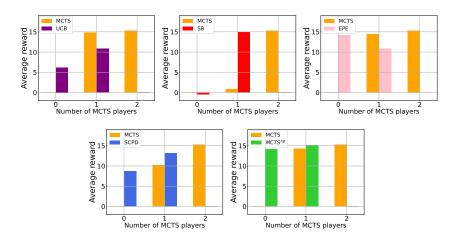
- $0 \le \ell \le h$  and  $\varepsilon$  infinitesimal
- If  $h \leq 2(h \ell)$ , Player 1 should bid on both items until Player 2 drops out
- If  $h \ge 2(h \ell)$ , Player 1 should form a collusion with Player 2 by conceding an item
- Player 2 optimal strategy is to bid on the cheapest item if its bid price is lower than  $\ell \varepsilon$  and is currently winning no items and pass otherwise



**Figure** – Evolution of player 1's utility  $\sigma_1$  in Test experiment [Brusco and Lopomo, 2002]  $(h = 10, \varepsilon = 0.1)$  given that player 2 plays optimally

Numerical Results

## Extensive Experiments : Utility $(n = 2, m = 7, \varepsilon = 1)$



 $\Rightarrow$  (MCTS,MCTS) is the only pure Nash equilibrium of the Normal form game in expected payoff with six strategies

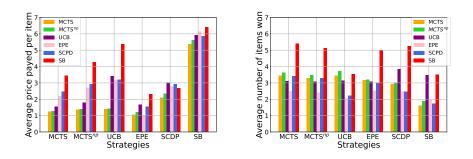
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Numerical Results

# Extensive Experiments : Own Price Effect $(n = 2, m = 7, \varepsilon = 1)$



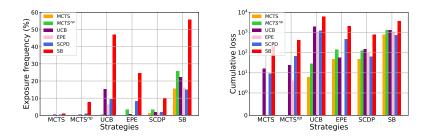
MCTS obtains the lowest average price per item won against every strategy

MCTS is fairly competitive in terms of number of acquired items

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Numerical Results

# Extensive Experiments : Exposure $(n = 2, m = 7, \varepsilon = 1)$



- (MCTS,MCTS) never suffers from exposure
- MCTS has very low exposure frequency against every strategy, except SB
- MCTS is less exposed and has lower losses than MCTS<sup>np</sup> against other strategies

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## Conclusion and future works

#### Conclusion

- First algorithm to tackle **simultaneously** the *exposure problem* and *own price effect* in a simplified version of SAA
- MCTS : a promising approach to derive auction strategies in SAA

#### **Complementary works**

- Our algorithm is easily extended to budget constraints
- Algorithm remains efficient and robust to significant errors in the valuation estimates

#### Future work

- Increase in the number of players
- Adding simultaneity and incomplete information to our SAA model

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## Thank you for your attention !

Image: Image:

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