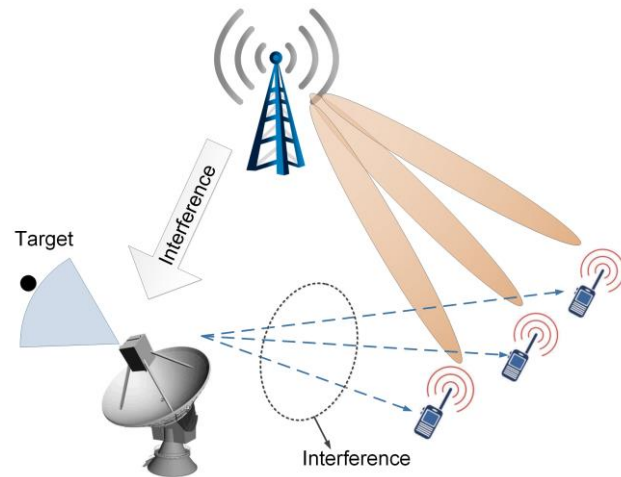


# Integrated Sensing and Communications: Signalling, Applications and Trade-offs

**Christos Masouros**

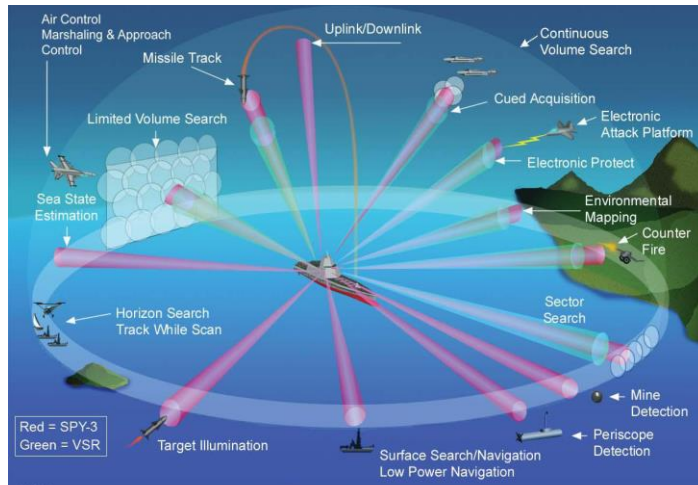
Professor of Wireless Communications and Signal Processing  
Dept. of Electronic & Electrical Engineering  
University College London  
[c.masouros@ucl.ac.uk](mailto:c.masouros@ucl.ac.uk)





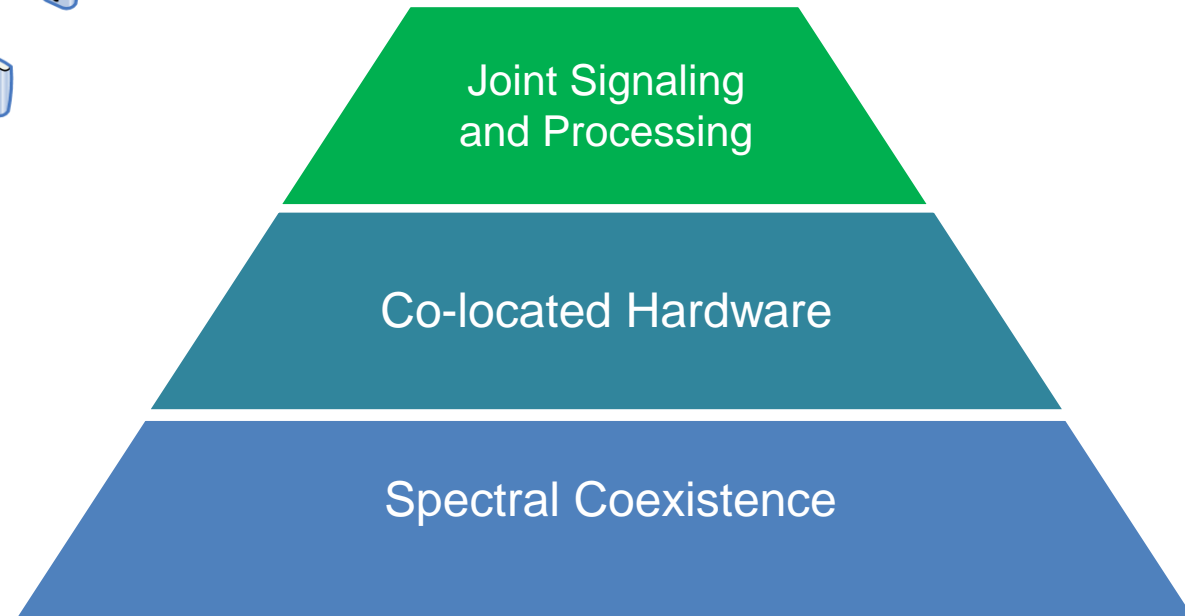
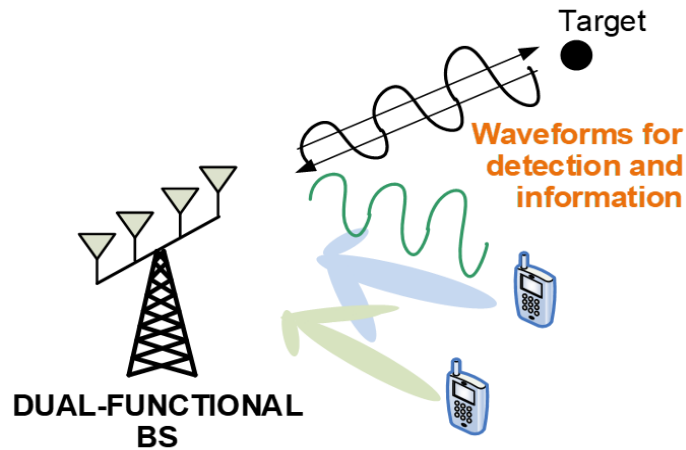
## Spectral Coexistence

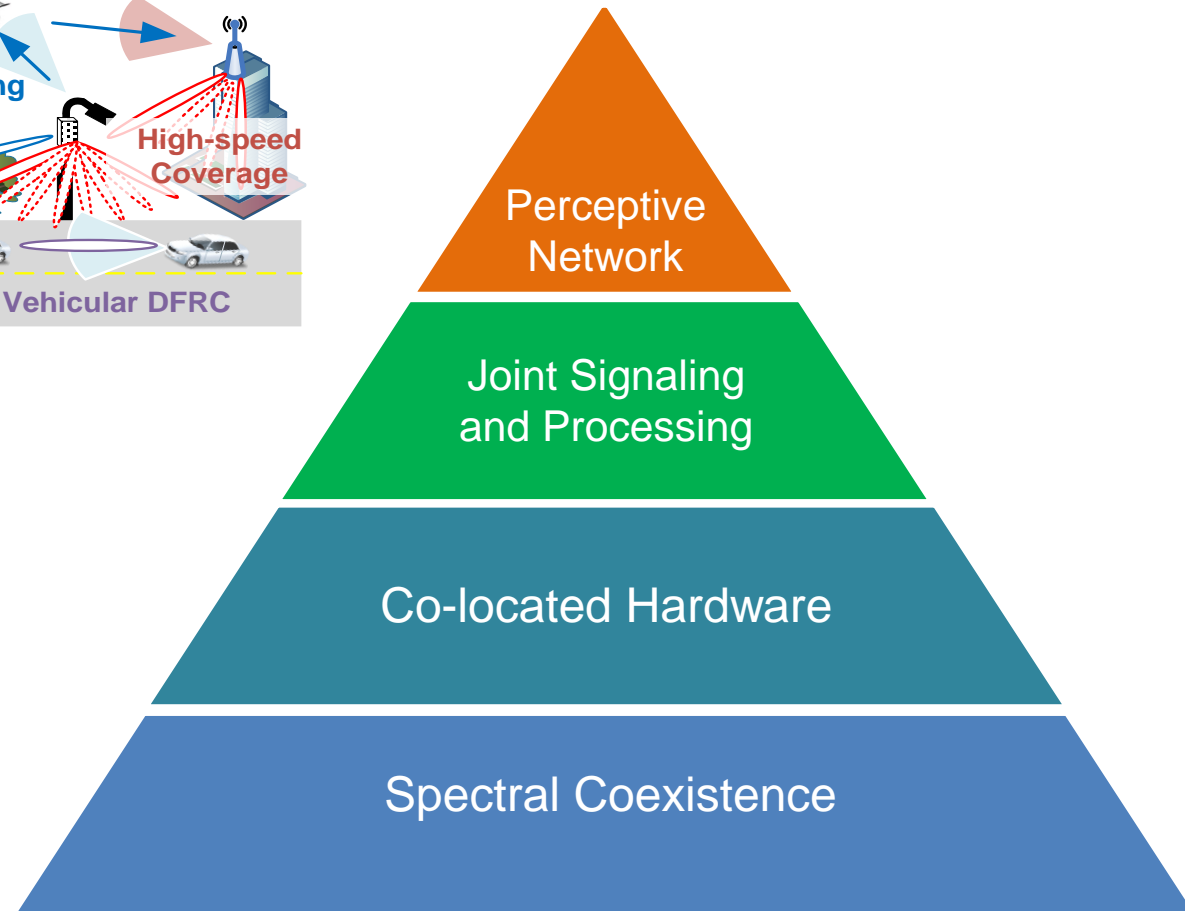
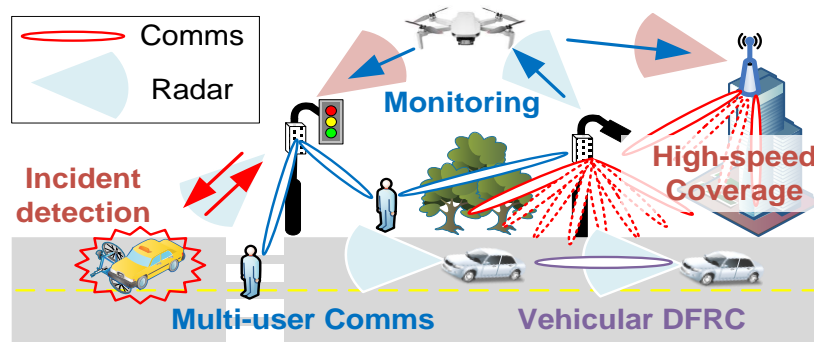
F. Liu, Y. Cui, C. Masouros, J. Xu, T. X. Han, A. Hassanien, Y. Eldar, S. Buzzi, "Integrated Sensing and Communications: Towards Future Dual-functional Wireless Networks", IEEE Journal on Sel. Areas Comms., *in press*



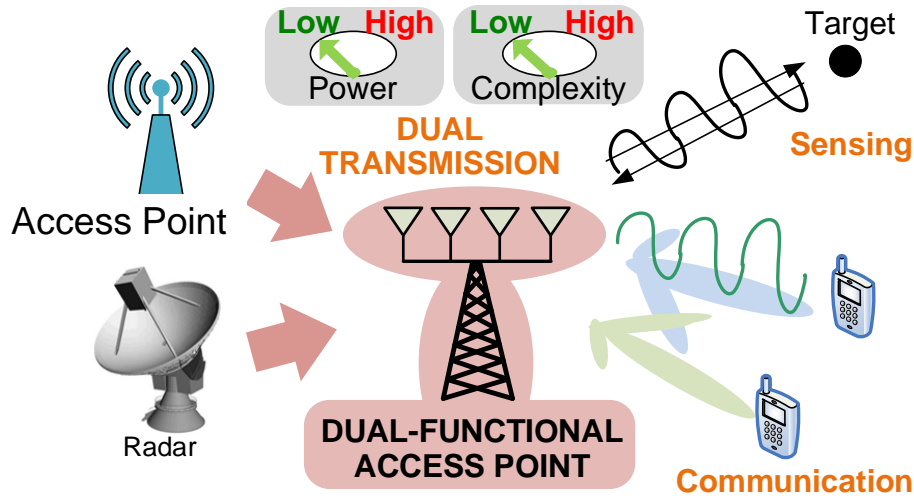
Co-located Hardware

Spectral Coexistence

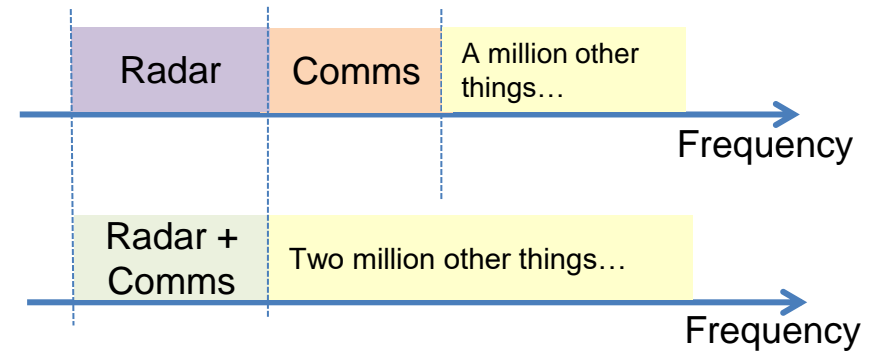




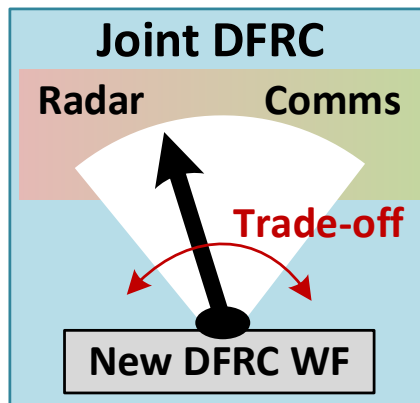
## Hardware Gain



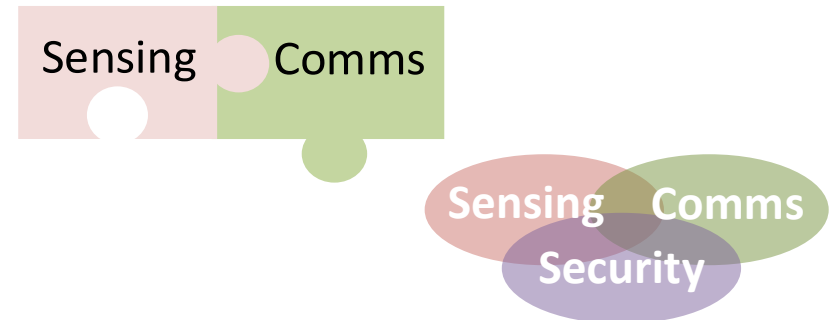
## Spectrum Gain



## Scalable Trade-offs

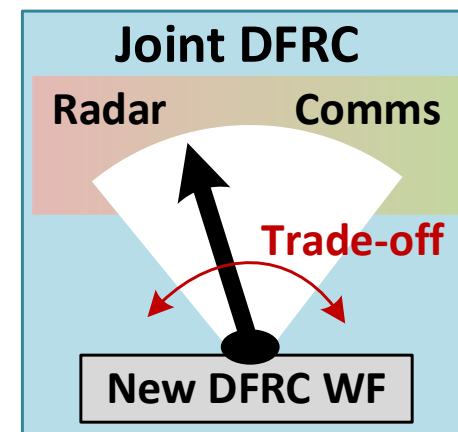
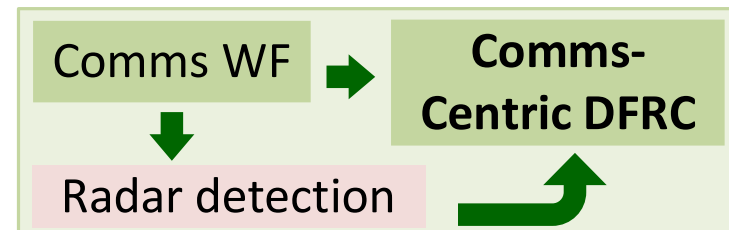
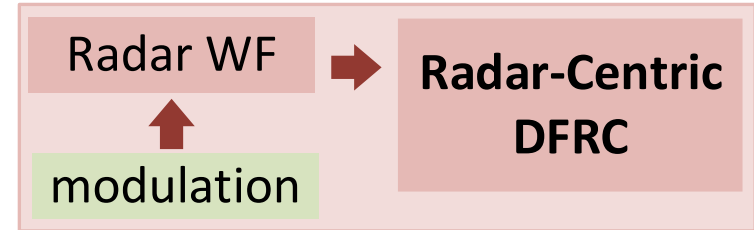


## Synergies – Mutual Benefits



# DFRC Technologies

- Radar-centric design
  - Pulse Interval Modulation (PIM)
  - Radar beampattern sidelobe signalling
  - Index Modulation (IM) using radar waveforms
  - ...
- Comms-centric design
  - OFDM based DFRC
  - IEEE 802.11ad based DFRC
  - ...
- **Jointly optimized design**
  - Radar-centric joint design
  - Weighted Comms-Radar optimization
  - ...



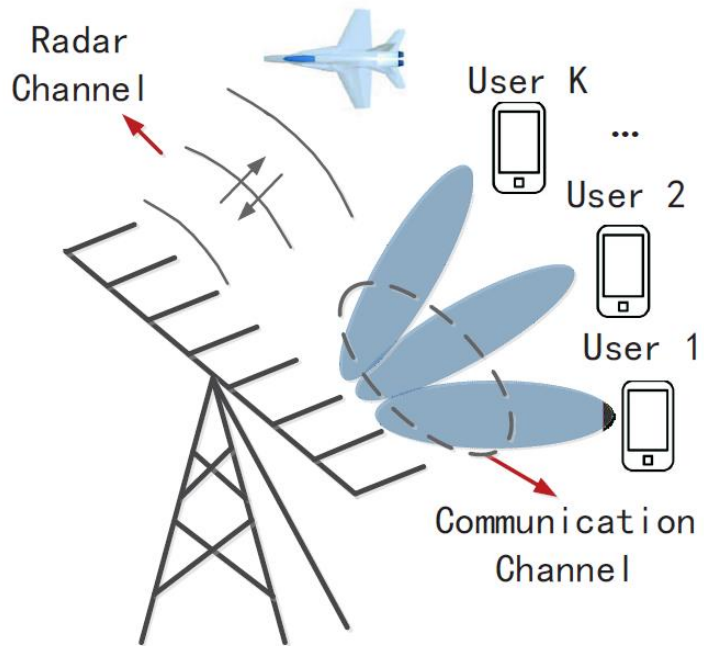
# Outline

- Motivation
- Technical highlights
  - Weighted-optimization based DFRC
  - Security for DFRC
  - Sensing-Assisted Communications



## Weighted optimization

$$\mathbf{Y} = \mathbf{H}\mathbf{X} + \mathbf{Z} = \mathbf{S} + \underbrace{(\mathbf{H}\mathbf{X} - \mathbf{S})}_{\text{MUI}} + \mathbf{Z}$$

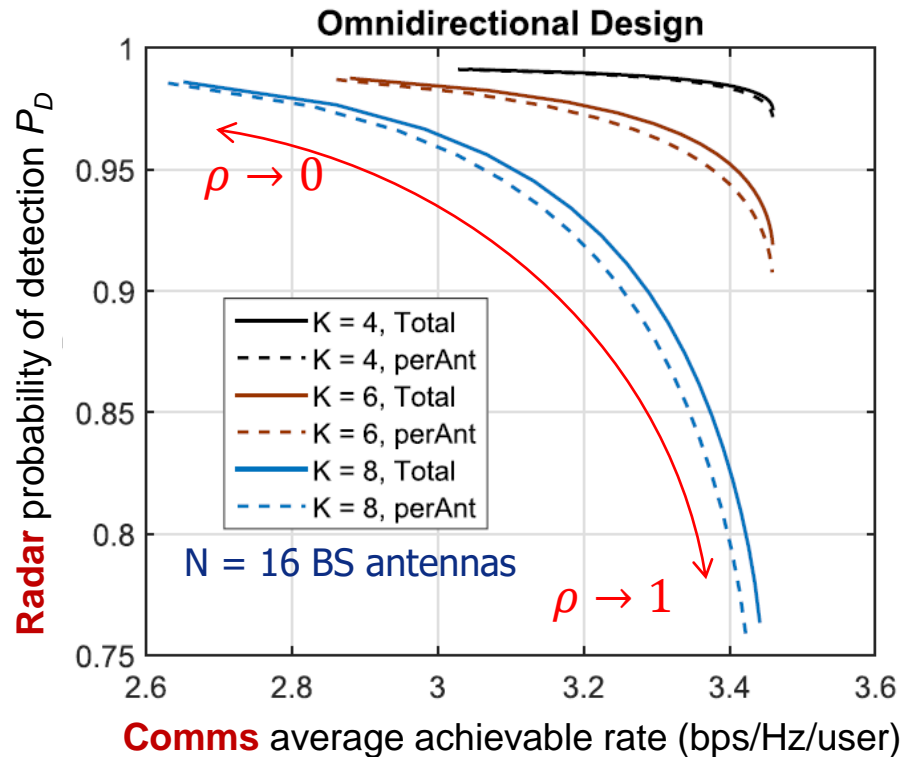


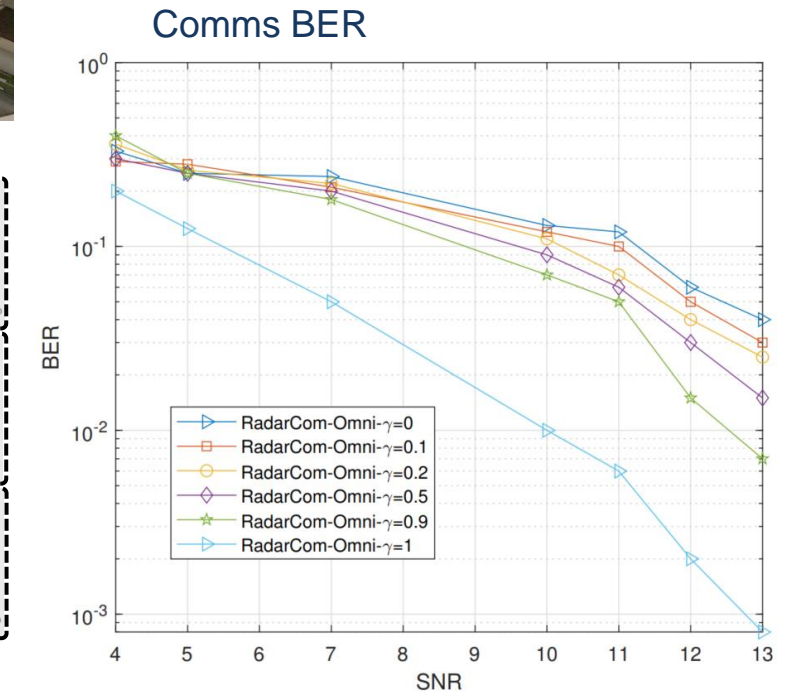
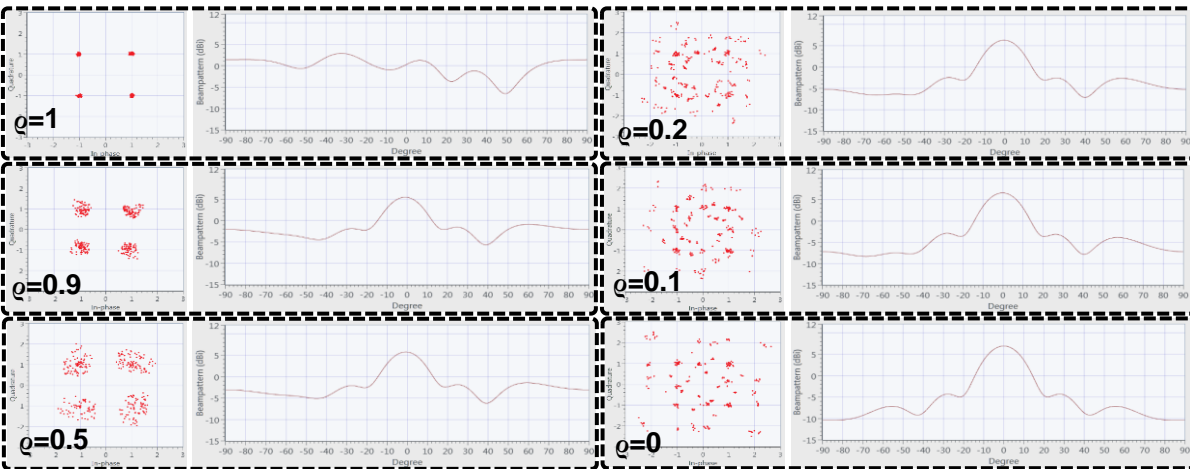
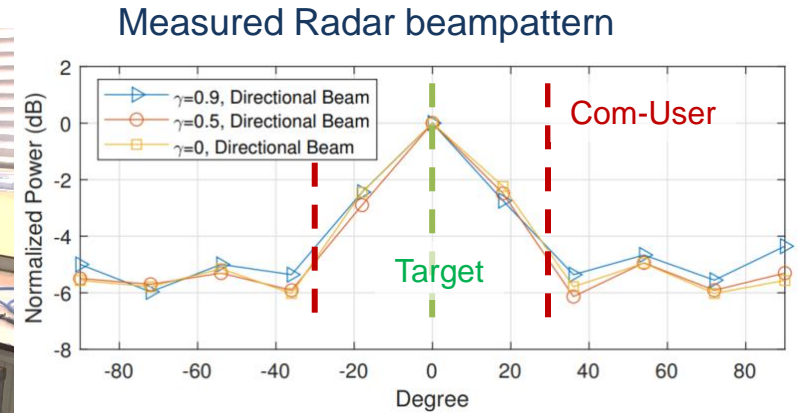
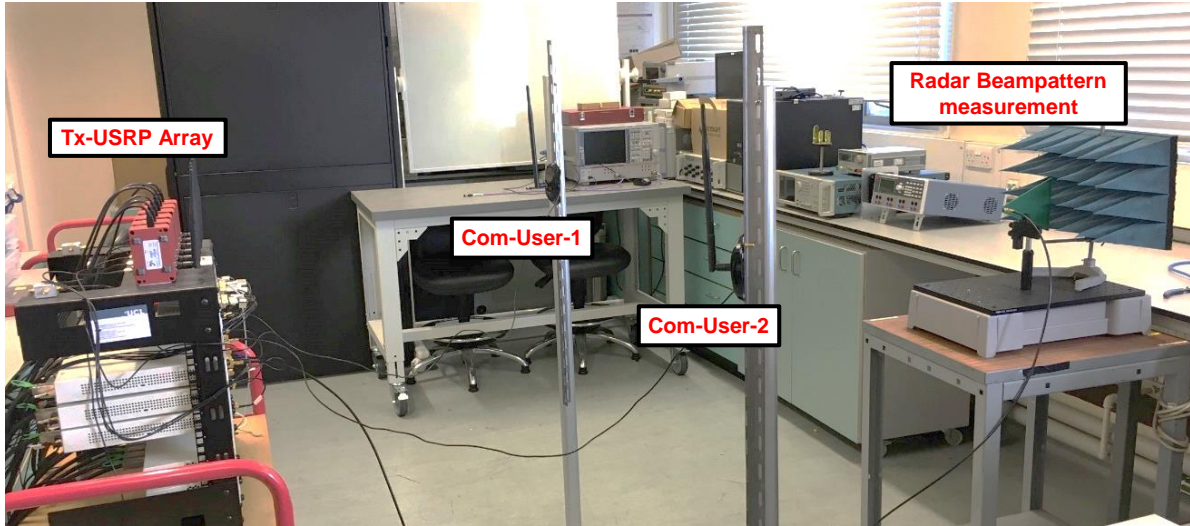
↑  $\rho$  - Comms priority  
↓  $\rho$  - Radar priority

$$\min_{\mathbf{X}} \rho \|\mathbf{H}\mathbf{X} - \mathbf{S}\|_F^2 + (1 - \rho) \|\mathbf{X} - \underline{\mathbf{X}}_0\|_F^2$$

$$s.t. \frac{1}{L} \|\mathbf{X}\|_F^2 = P_T,$$

Ideal radar waveform





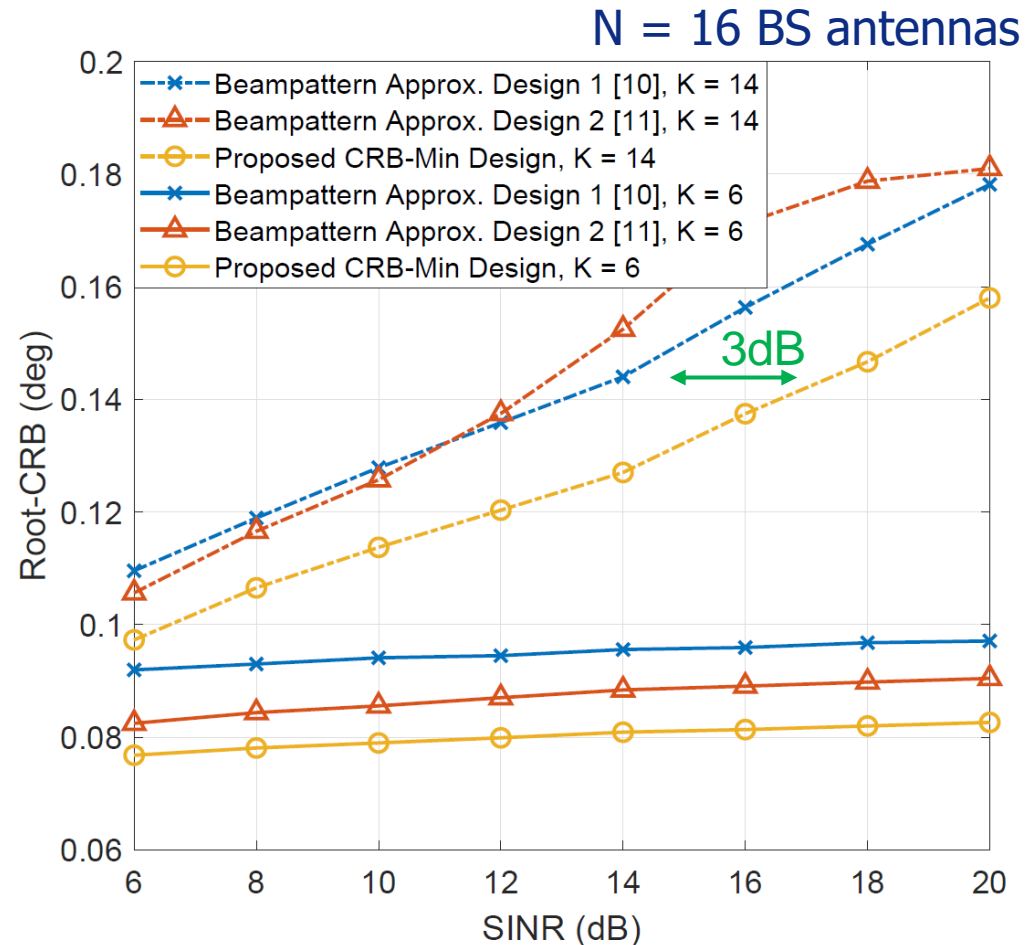
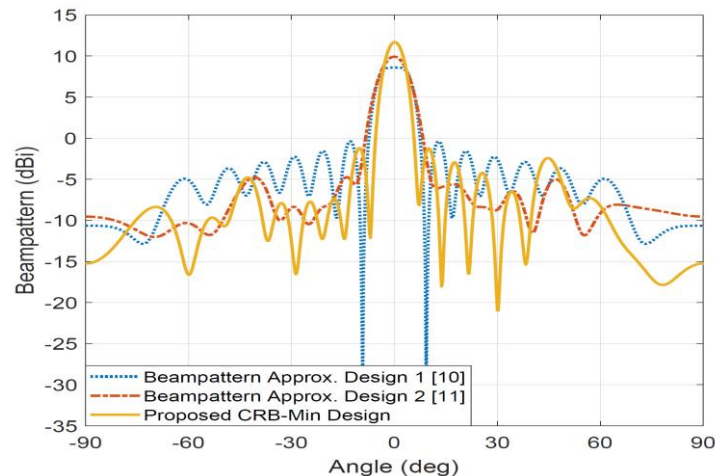
# We can do better than Radar waveform approximation

Minimize CRB directly:

$$\min_{\mathbf{W}_D} \text{CRB}(\theta)$$

$$\text{s.t. } \gamma_k \geq \Gamma_k, \forall k,$$

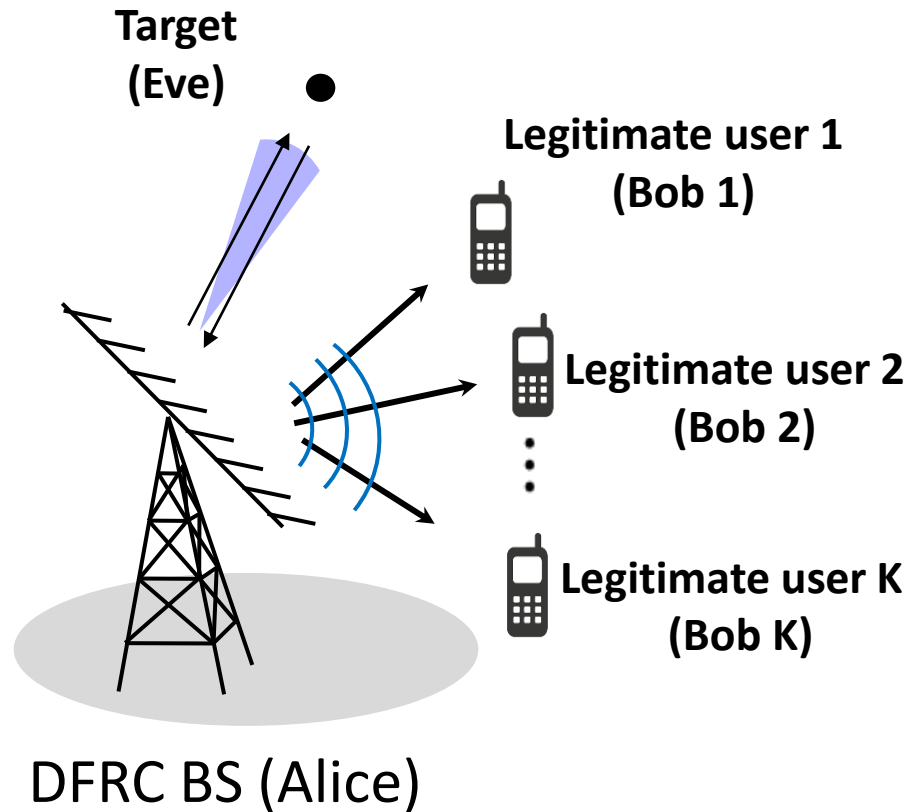
$$\|\mathbf{W}_D\|_F^2 \leq P_T,$$



~3-4dB gains in bottom-line CRB performance

# **Dual-functional Radar-Communication Subject to Security threats?**

## Radar + Information: Subject to Security Threats



Target can be:

- Enemy aircraft
- Malicious UAV
- Non-cooperative car
- ...

Malicious target can:

- Detect Data intended for LUs – unique to DFRC
- Infer critical radar info (location, ID, ..., ...)

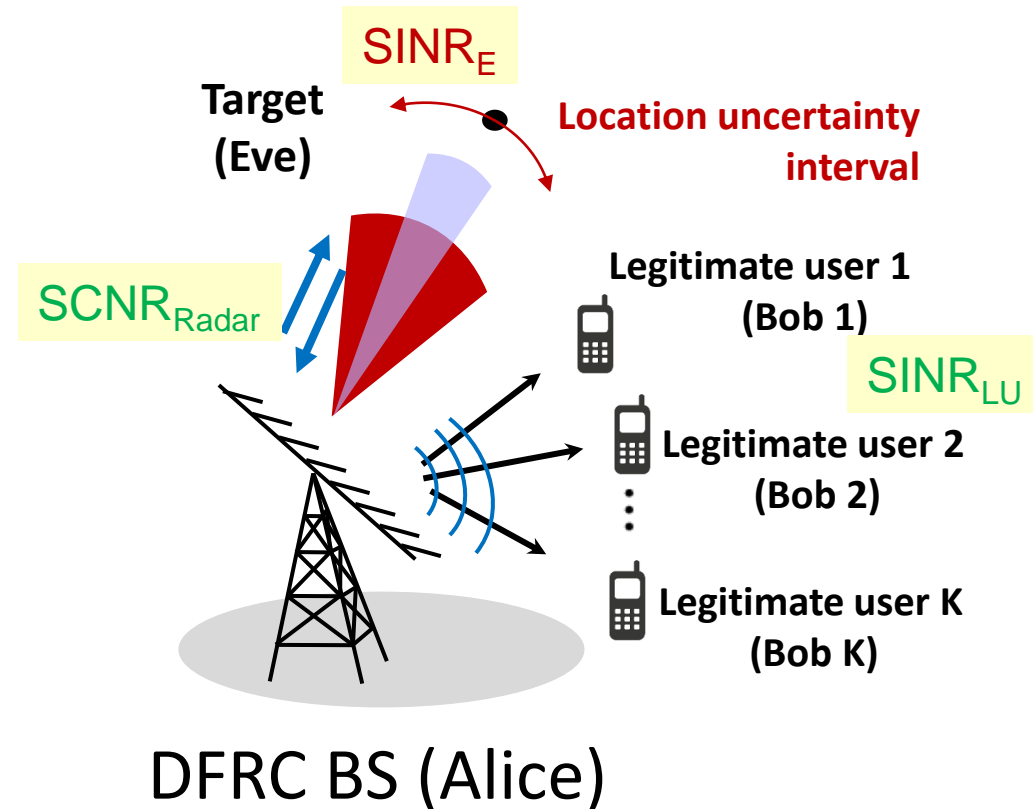
- Need for PHY security guarantees over the Radar beamwidth
- Secure Beamforming / Artificial Noise

# Unique Sensing Performance vs Security Trade-offs

- ↑ Power towards the direction of target
- ↓ Useful signal power ( $SINR_E$ ) towards the target
- ↑  $SINR_{LU}$  towards the users

Apply PHY Sec approaches

- Secure BF
- AN, Jamming
- Cooperative Security
- ...



## Secure DFRC BF - Perfect CSI, Target Uncertainty

### Secure Beamformer

$$\min_{\mathbf{W}_i, \mathbf{R}_X} \sum_{\theta_m \in \Phi} \frac{|\alpha|^2 \mathbf{a}^H(\theta_m) \sum_{i=1}^K \mathbf{W}_i \mathbf{a}(\theta_m)}{|\alpha|^2 \mathbf{a}^H(\theta_m) \mathbf{R}_N \mathbf{a}(\theta_m) + \sigma^2}$$

$$s.t. \quad \mathbf{a}^H(\theta_0) \mathbf{R}_X \mathbf{a}(\theta_0) - \mathbf{a}^H(\theta_m) \mathbf{R}_X \mathbf{a}(\theta_m) \geq \gamma_s, \quad \forall \theta_m \in \Omega$$

$$\mathbf{a}^H(\theta_k) \mathbf{R}_X \mathbf{a}(\theta_k) \leq (1 + \alpha) \mathbf{a}^H(\theta_0) \mathbf{R}_X \mathbf{a}(\theta_0), \quad \forall \theta_k \in \Phi$$

$$(1 - \alpha) \mathbf{a}^H(\theta_0) \mathbf{R}_X \mathbf{a}(\theta_0) \leq \mathbf{a}^H(\theta_k) \mathbf{R}_X \mathbf{a}(\theta_k), \quad \forall \theta_k \in \Phi$$

$$\text{SINR}_i \geq \gamma_b, \forall i,$$

$$\text{tr}(\mathbf{R}_X) = P_0,$$

$$\mathbf{W}_i = \mathbf{W}_i^H, \mathbf{W}_i \succeq 0, \forall i,$$

$$\text{rank}(\mathbf{W}_i) = 1, \forall i,$$

$$\mathbf{R}_N = \mathbf{R}_N^H, \mathbf{R}_N \succeq 0,$$

Fractional Programming + SDR

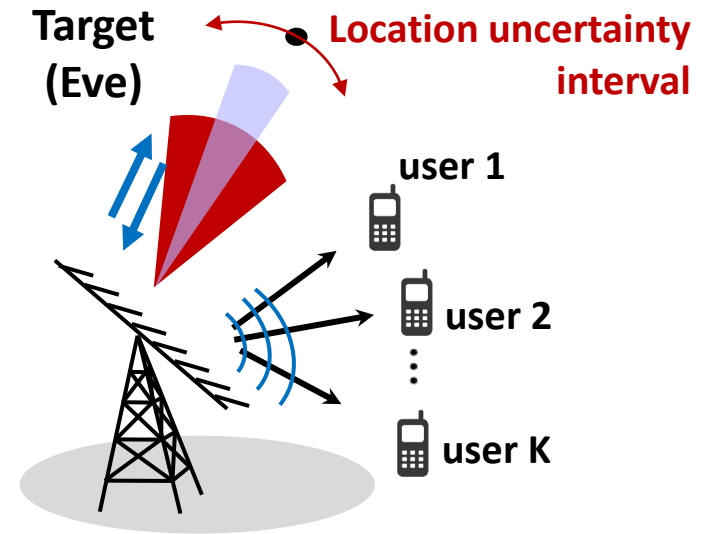
Tx signal

$$\mathbf{x} = \mathbf{W}\mathbf{s} + \mathbf{n} \quad \mathbf{R}_X = \mathbb{E}[\mathbf{x}\mathbf{x}^H] = \sum_{i=1}^K \mathbf{W}_i + \mathbf{R}_N$$

PSRL greater than  $\gamma_s$

Main beam region within angle spread  $\phi$ , within  $\pm\alpha$  of  $\theta_0$

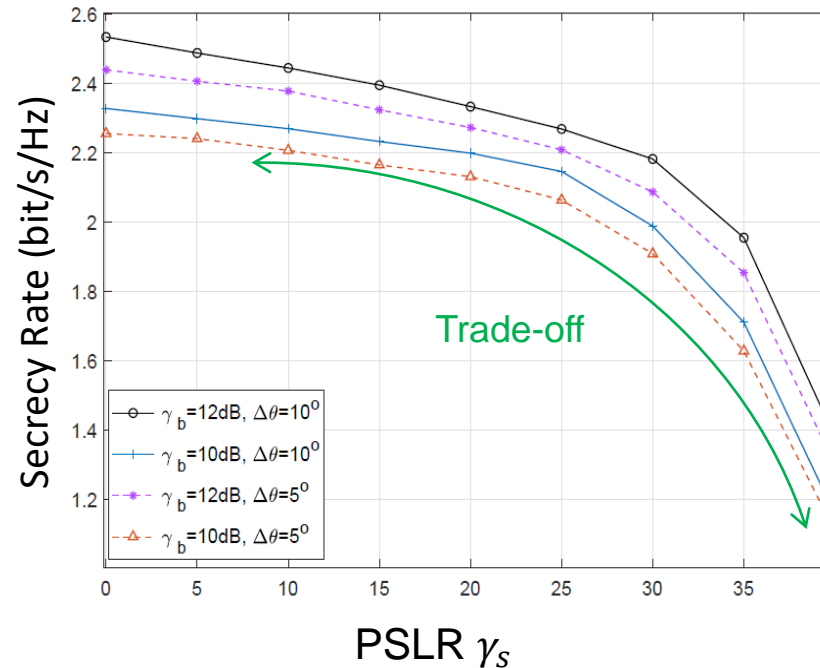
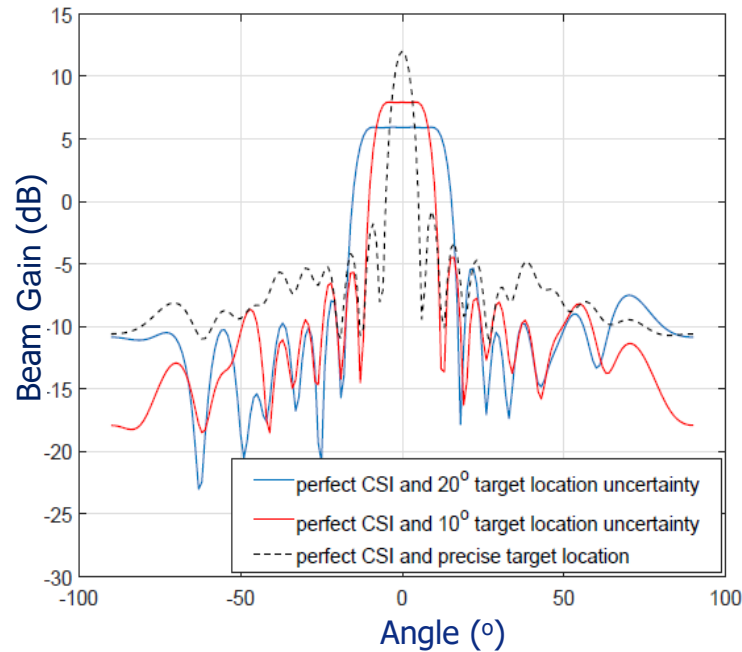
Location uncertainty interval



DFRC BS (Alice)

## Numerical Results

$N = 18$  antennas,  $K = 4$  legitimate users, one target – LU SNR  $\gamma_b = 10\text{dB}$ .



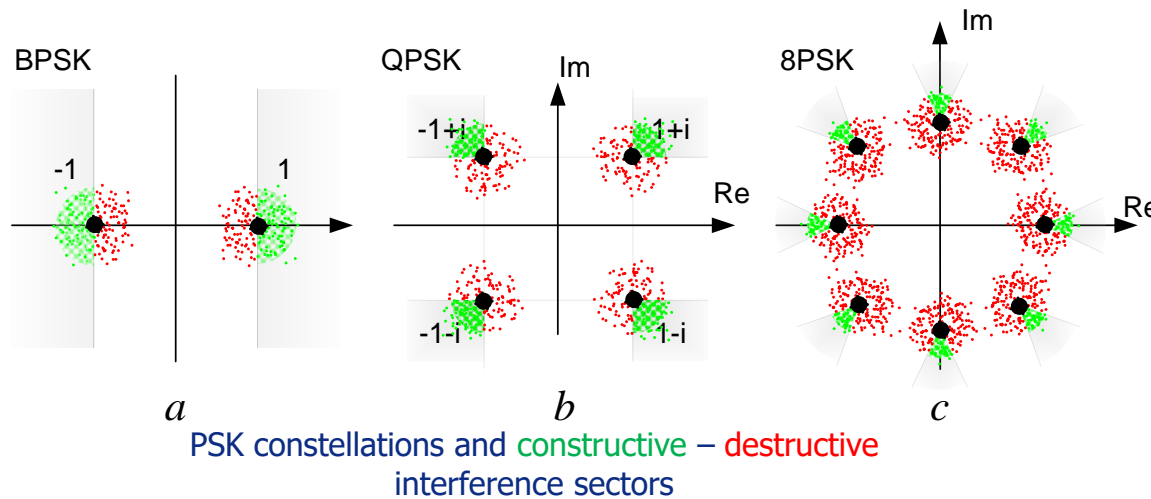
- $\uparrow$  location uncertainty angular interval  $\rightarrow$   $\downarrow$  power gain of mainbeam.
- CSI imperfections deteriorate the radar PSLR
- $\uparrow$  PSLR  $\rightarrow$   $\downarrow$  Secrecy Rate (more power spent on radar PSLR fulfilment)



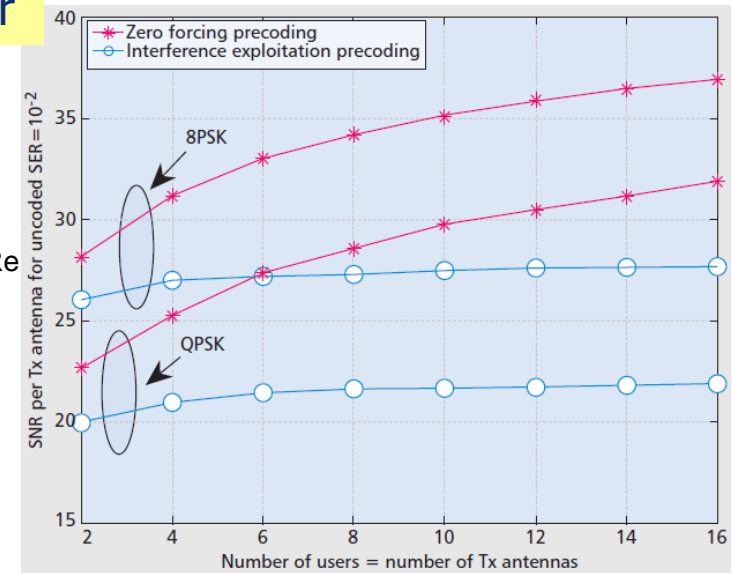
**Secure Dual-functional Radar-Communication**

**Exploiting Constructive / Destructive  
Interference**

## Key Concept: Exploitation of green interference power



## Up to 10x Power Reduction



### Early Works:

C. Masouros and E. Alsusa, "A Novel Transmitter-Based Selective-Precoding Technique for DS/CDMA systems", *IEEE Signal Processing letters*, vol. 14, no. 9, pp. 637-640, Sept. 2007

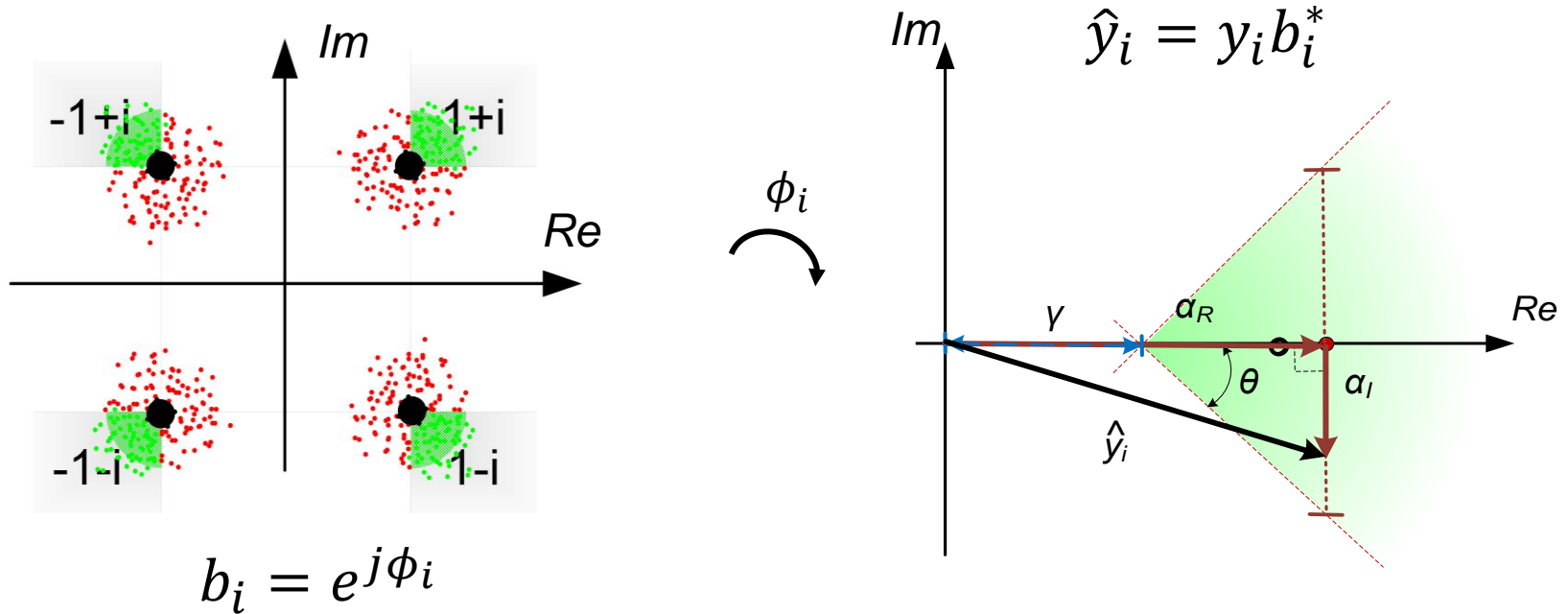
C. Masouros, "Correlation Rotation Linear Precoding for MIMO Broadcast Communications", *IEEE Trans. on Sig. Proc.*, vol 59, issue 1, pp. 252-262, Jan 2011

C. Masouros, T. Ratnarajah, M. Sellathurai, C. Papadias, A. Shukla, "Known Interference in Wireless Communications: A Limiting factor or a Potential Source of Green Signal Power?", *IEEE Comms. Mag.*, vol. 51, no. 10, pp. 162-171, Oct. 2013

C. Masouros, M. Sellathurai, T. Ratnarajah, "Interference Optimization for Transmit Power Reduction in Tomlinson-Harashima Precoded MIMO Downlinks", *IEEE Trans. Sig. Proc.*, vol. 60, no. 5, pp. 2470-2481, May 2012

### Optimization based Interference Exploitation first introduced in the context of Vector Perturbation:

C. Masouros, M. Sellathurai, T. Ratnarajah, "Vector Perturbation Based on Symbol Scaling for Limited Feedback MIMO Downlinks", *IEEE Trans. Sig. Proc.*, vol. 62, no. 3, pp. 562-571, Feb.1, 2014



## Constructive Interference:

1.  $\alpha_R \geq \gamma$

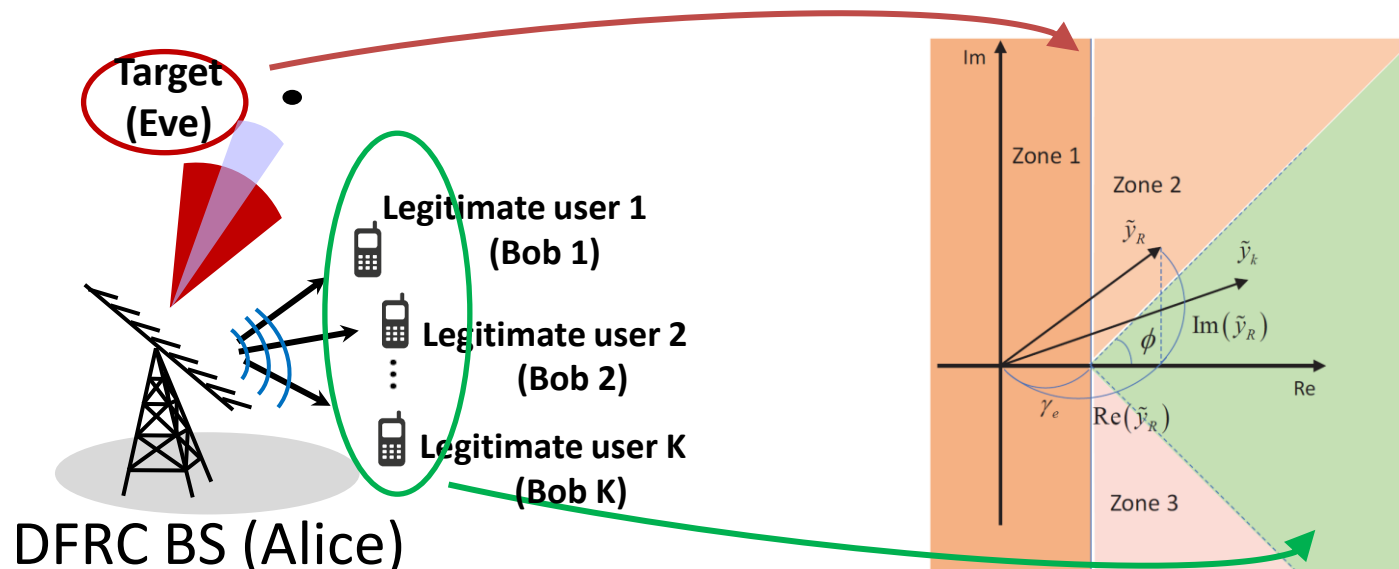
2.  $|\alpha_I| \leq (\alpha_R - \gamma) \tan \theta$

$\alpha_R = \text{Re}(\hat{y}_i), \alpha_I = \text{Im}(\hat{y}_i)$

$\theta = \frac{\pi}{M}, \gamma = \sqrt{\Gamma_i N_0}$

C. Masouros and G. Zheng, "Exploiting Known Interference as Green Signal Power for Downlink Beamforming Optimization", IEEE Trans. Sig. Proc., vol.63, no.14, pp.3668-3680, July, 2015

A. Li, *et al*, "A Tutorial on Interference Exploitation via Symbol-Level Precoding: Overview, State-of-the-Art and Future Directions", IEEE Comms. Surveys and tutorials., vol. 22, no. 2, pp. 796-839, 2020



$$\max_{\mathbf{x}} \min_{\theta_p \in \text{card}(\Psi)} \frac{\mu |\mathbf{w}^H \mathbf{U}(\theta_p) \mathbf{x}|^2}{\mathbf{w}^H (\mathbf{\Sigma}(\mathbf{x}) + \mathbf{I}_{N_R}) \mathbf{w}} \quad (38a)$$

Radar SNR

$$\text{s.t. } \|\mathbf{x}\|^2 \leq P_0 \quad (38b)$$

$$|\text{Im}(\tilde{\mathbf{h}}_k^H \mathbf{x})| \leq \left( \text{Re}(\tilde{\mathbf{h}}_k^H \mathbf{x}) - \sqrt{\sigma_{C_k}^2 \Gamma_k} \right) \tan \phi, \forall k \quad (38c)$$

Constructive interference to users

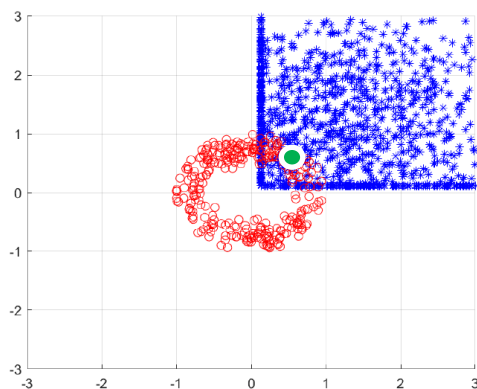
$$|\text{Im}(\alpha_0 \tilde{\mathbf{a}}_t^H(\beta_p) \mathbf{x})| \geq \left( \text{Re}(\alpha_0 \tilde{\mathbf{a}}_t^H(\beta_p) \mathbf{x}) - \sqrt{\sigma_T^2 \Gamma_T} \right) \tan \phi, \forall p, \quad (38d)$$

Destructive interference to target (Eve)

$N = 10$  antennas,  $K = 5$  legitimate users, one target.

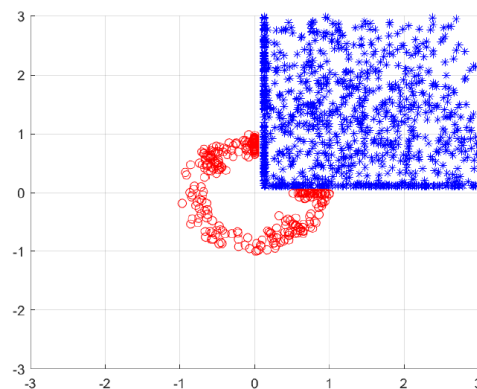
## Signal Constellations at users / target

Constructive interference

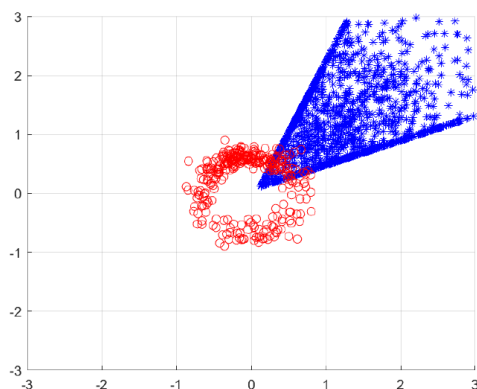


(a) QPSK, CI

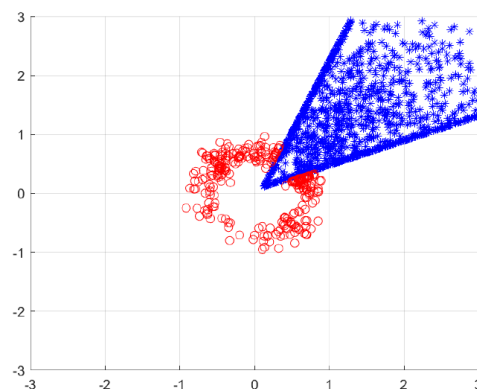
Constructive - Destructive interference



(b) QPSK, CI-DI

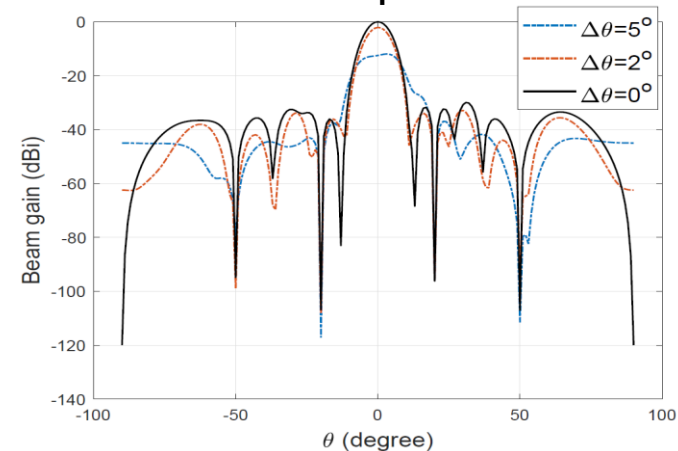


(c) 8PSK, CI

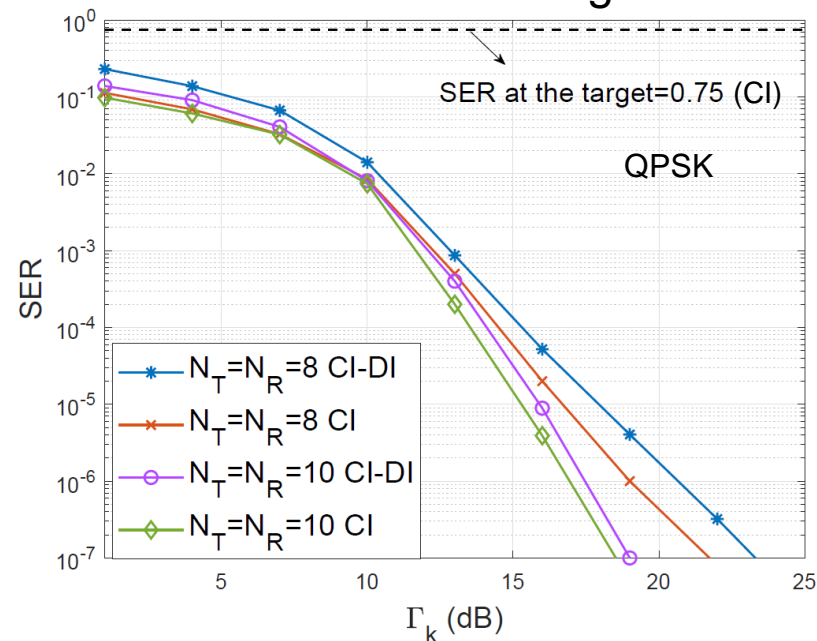


(d) 8PSK, CI-DI

## Radar beampattern



## SER at users / target

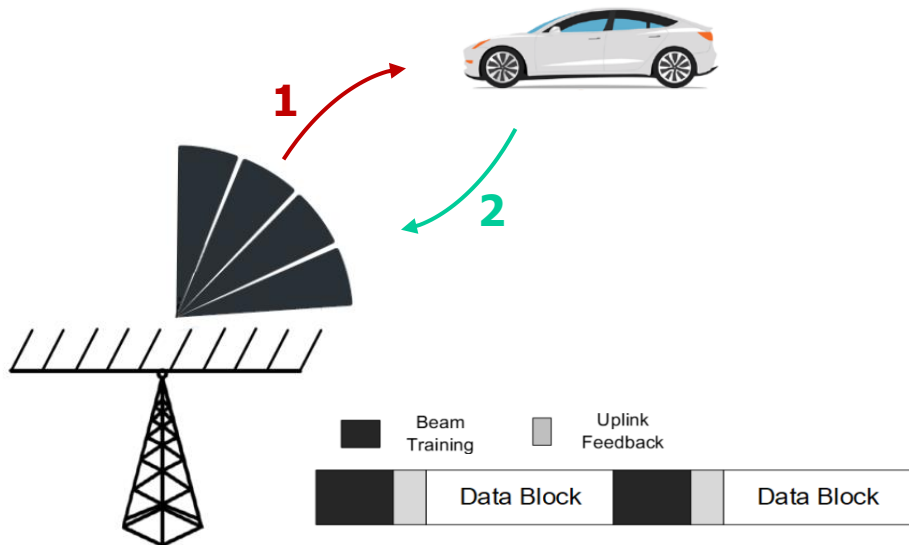


**Radar-assisted Vehicular Network**

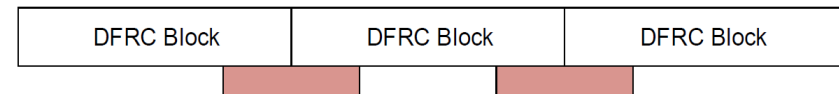
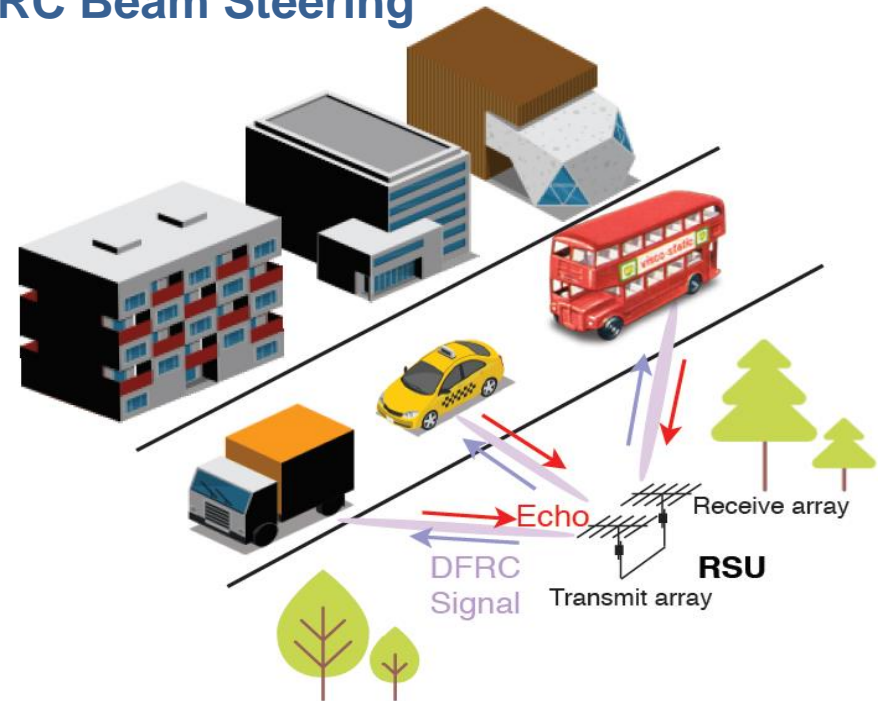
**Communication Served by Sensing**

## Comms served by Sensing: Radar tracking for Comms beam-steering

### Comms-based Beam Training

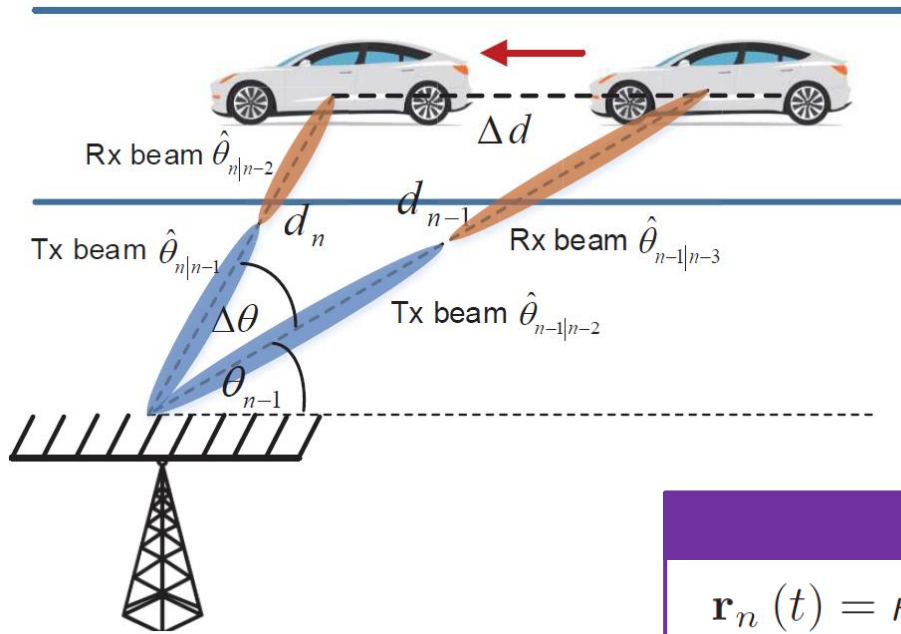


### DFRC Beam Steering



### Advantages of DFRC Signalling:

- No dedicated downlink pilots are needed;
- No uplink feedback is needed;
  - No feedback overhead/errors
  - No quantization errors
- The whole downlink frame can be used for tracking → Significant matched-filtering gain



## State transition model

$$\mathbf{x}_n = \mathbf{g}(\mathbf{x}_{n-1}) + \boldsymbol{\omega}_n$$

$$= \begin{cases} \theta_n = \theta_{n-1} + d_{n-1}^{-1} v_{n-1} \Delta T \sin \theta_{n-1} + \omega_{\theta,n}, \\ d_n = d_{n-1} - v_{n-1} \Delta T \cos \theta_{n-1} + \omega_{d,n}, \\ v_n = v_{n-1} + \omega_{v,n}, \\ \beta_n = \beta_{n-1} (1 + d_{n-1}^{-1} v_{n-1} \Delta T \cos \theta_{n-1}) + \omega_{\beta,n}, \end{cases}$$

## Radar measurement model

$$\mathbf{r}_n(t) = \kappa \sqrt{p_n} \beta_n e^{j2\pi\mu_n t} \mathbf{b}(\theta_n) \mathbf{a}^H(\theta_n) \mathbf{f}_n s_n(t - \tau_n) + \mathbf{z}_n(t)$$

↓ matched filtering

$$\mathbf{y}_n = \mathbf{h}(\mathbf{x}_n) + \tilde{\mathbf{z}}_n$$

$$= \begin{cases} \tilde{\mathbf{r}}_n = \beta_n \sqrt{Gp_n} \kappa \mathbf{b}(\theta_n) \mathbf{a}^H(\theta_n) \mathbf{f}_n + \mathbf{z}_{\theta,n} \\ \hat{\tau}_n = \frac{2d_n}{c} + z_{\tau,n} \quad \text{Round-trip delay} \\ \hat{f}_{D,n} = \frac{2v_n \cos(\theta_n) f_c}{c} + z_{f,n} \quad \text{Doppler offset} \end{cases}$$

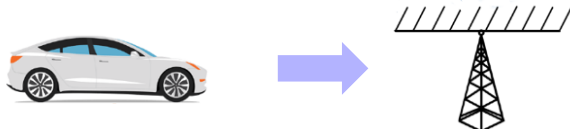
## Communication model

$$c_n(t) = \tilde{\kappa} \sqrt{p_n} \alpha_n \mathbf{w}_n^H \mathbf{u}(\theta_n) \mathbf{a}^H(\theta_n) \mathbf{f}_n s_n(t) + z_c(t),$$

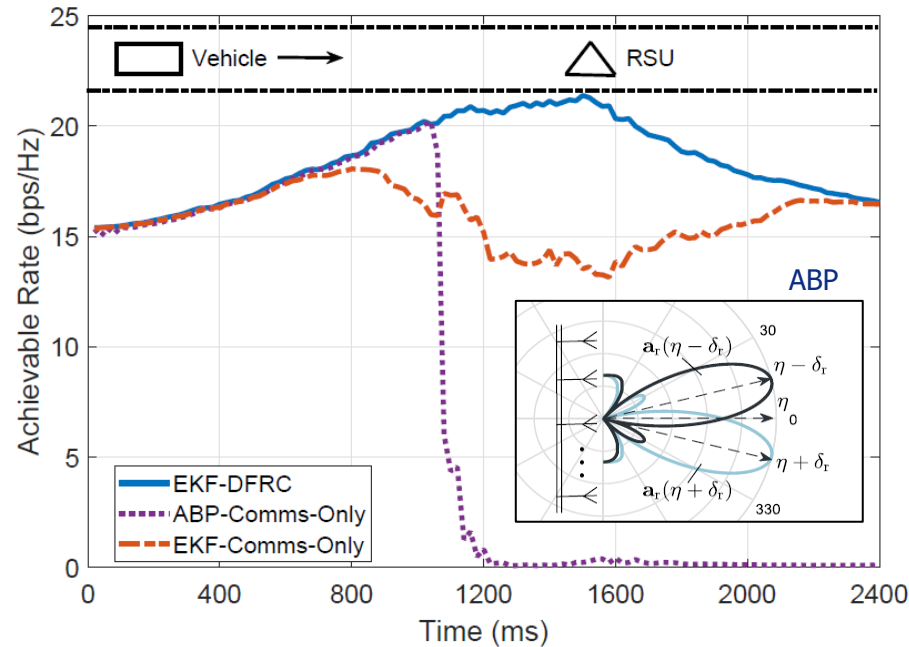
## Predictive Beamformers

$$\text{Tx: } \mathbf{f}_n = \mathbf{a}(\hat{\theta}_{n|n-1}) \quad \text{Rx: } \mathbf{w}_n = \mathbf{u}(\hat{\theta}_{n|n-2})$$





$N = 64$ ,  $v_0 = 18\text{m/s}$  (65 km/hour), beamwidth:  $\pi/64$



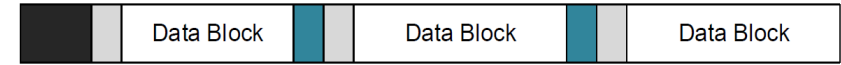
**Legend:**

- Black: Beam Training
- Grey: Uplink Feedback
- Teal: Beam Tracking
- Red: Beam Prediction

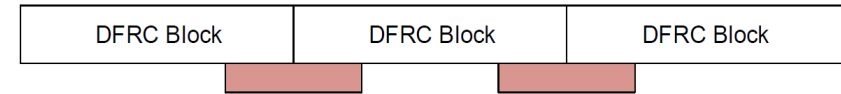
(a) Beam Training Scheme



(b) Beam Tracking Scheme



(c) Beam Prediction using DFRC



- EKF-Comms-only: poor angle estimation at RSU crossing point – suffering data rate
- Auxiliary Beam Pair (ABP) tracking: at RSU crossing point the correct beam will unlikely fall into angle search interval – beam goes beyond the search space and is not recovered
- EKF-DFRC: Minimal disruption in the rate

F. Liu, W. Yuan, C. Masouros and J. Yuan, "Radar-Assisted Predictive Beamforming for Vehicular Links: Communication Served by Sensing", IEEE Trans. Wireless Commun., vol. 19, no 11, pp. 7704-7719, Nov. 2020

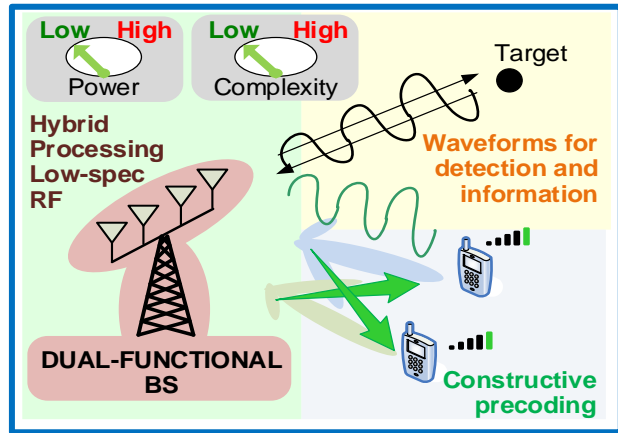
Z. Du, F. Liu, W. Yuan, C. Masouros, Z. Zhang, S. Xia, and G. Caire, "Integrated Sensing and Communications for V2I Networks: Dynamic Predictive Beamforming for Extended Vehicle Targets," IEEE Trans. on Wireless Comms., under review

# Future outlook - Cellular as a Sensor

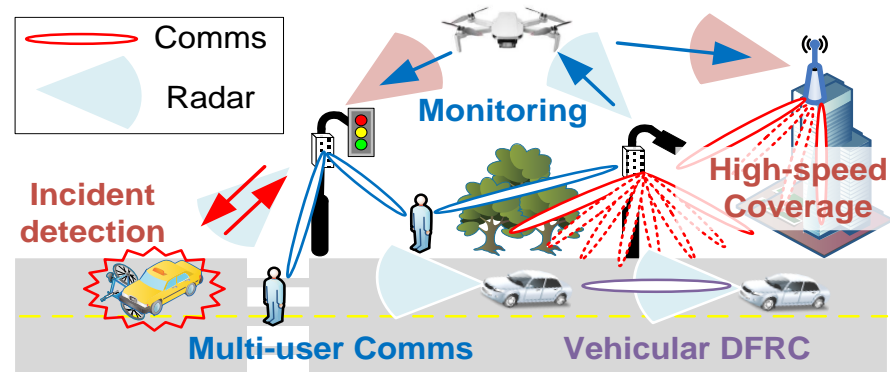
c.masouros@ucl.ac.uk



## Hardware-Efficient DFRC

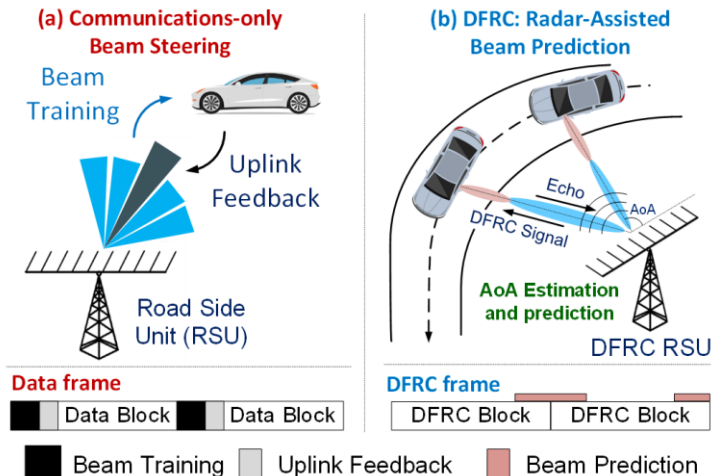


## Pervasive sensing through dense cellular infrastructure

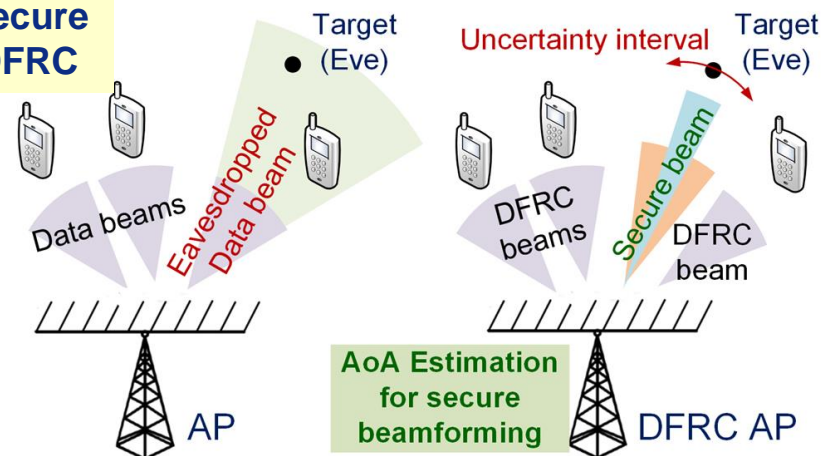


## Multicell / multi-static DFRC

### Sensing-Assisted Comms



### Secure DFRC



# Thank you



Fan Liu



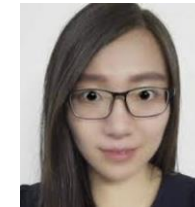
Iman  
Vailulahi



Xiaoye  
Jing



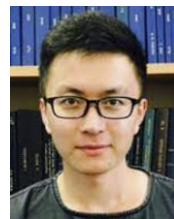
Abdel  
Salem



Xiaoyan Hu



Nanchi Su



Tongyang Xu



Ang Li




Murat Temiz



Nial Peters

 **UDRC Project**  
Mar 2019 – Dec 2021 (£1m)

 **Marie Curie Fellowship**  
Nov 2018 – Oct 2020 (£160k)

 **MoD DASA Project**  
Jul 2021 – Mar 2022 (£100k)  
Defence and Security  
Accelerator

 **CI-PHY Project**  
Apr 2018 – Jul 2021 (£1.1m)

 **LeanCom Project**  
Oct 2019 – Nov 2023 (£860k)

  **PAINLESS Project**  
Oct 2018 – Sep 2022 (€4.2m)

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