Name:

Question:	1	2	3	4	Total
Points:	9	10	18	8	45
Score:					

# E1 244 - Detection & Estimation Theory (2019) Final Exam

## Instructions

- This exam has a total of 4 questions with a maximum score of 45 points. The total time is 3 hours.
- There are partial marks for subquestions, so please attempt as many parts as possible.
- Write your name at the top of this cover sheet.
- <u>Attach</u> your solution sheets to this cover sheet and <u>return everything</u> including rough work.
- No class notes, calculators or electronic aids are permitted.
- Academic dishonesty will not be tolerated.

## Useful formulas, definitions, etc.

• Generalized Likelihood Ratio Test (GLRT). The GLRT for testing the composite hypotheses  $H_0: Y \sim p_{\theta}, \theta \in \Lambda_0$  vs  $H_1: Y \sim p_{\theta}, \theta \in \Lambda_1$  has the form

$$\frac{\max_{\theta \in \Lambda_1} p_{\theta}(y)}{\max_{\theta \in \Lambda_0} p_{\theta}(y)} \gtrless \eta.$$

• Constrained quadratic minimization. For  $f(x) = ax^2 + bx + c$  and  $u \in \mathbb{R}$ ,

$$\arg\min_{x\geq u} f(x) = \max\left\{u, \arg\min_{x\in\mathbb{R}} f(x)\right\} \text{ and}$$
$$\arg\min_{x\leq u} f(x) = \min\left\{u, \arg\min_{x\in\mathbb{R}} f(x)\right\}.$$

- Geometric probability distribution. For  $0 \le \theta \le 1$ , the Geom $(\theta)$  distribution has pmf  $p[i] = \theta(1-\theta)^{i-1}, i = 1, 2, ...$
- Negative binomial probability distribution. For r = 1, 2, ... and  $0 \le \theta \le 1$ , the NegBin $(r, \theta)$  distribution has pmf  $p[i] = \binom{i+r-1}{i} \cdot \theta^r \cdot (1-\theta)^i$ , i = 0, 1, 2, ...

#### Apr 30, 2019

### 1. Mixture testing

Consider testing the hypotheses

$$H_0: (Y_1, \dots, Y_n) \stackrel{\text{nd}}{\sim} \text{Unif}([k]), \quad \text{vs}$$
  
$$H_1: (Y_1, \dots, Y_n) \sim P_{\epsilon},$$

where k is a known positive integer, Unif([k]) is the uniform probability distribution over the alphabet  $[k] = \{1, \ldots, k\}, \epsilon \in (0, 1)$  is known, and  $P_{\epsilon}$  is the joint probability distribution of  $Y_1, \ldots, Y_n$  defined as follows: First,  $Z \sim \text{Unif}([k])$  is sampled uniformly. Then (given Z),  $Y_1, \ldots, Y_n$  are sampled <u>iid</u> from the probability distribution  $P_{\epsilon}^Z$  over [k], under which each outcome  $j \in [k]$  has probability

$$P_{\epsilon}^{Z}[j] = \begin{cases} \frac{1}{k} + \epsilon, & \text{if } j = Z\\ \\ \frac{1}{k} - \frac{\epsilon}{k-1}, & \text{if } j \in [k] \setminus \{Z\} \end{cases}$$

- (a) (2 points) For a general sequence  $(y_1, \ldots, y_n)$  with elements from [k], write down the probability of the sequence under each hypothesis.
- (b) (3 points) Write down, in the shortest possible way, a Bayes-optimal test statistic for deciding between  $H_0$  and  $H_1$ . How does it depend on the observed sequence  $y_1, \ldots, y_n$ ?
- (c) (4 points) Suppose k (the alphabet size) is quite large  $(k \gg 1)$ , and  $\epsilon \gg \frac{1}{k}$ . Explain why the test statistic you devised above should reliably detect the true hypothesis as n (the sample size) becomes large.

(Hint: Approximate the test statistic in this regime of k and  $\epsilon$ , and think about what happens to it under  $H_0$  and  $H_1$  as  $n \to \infty$ ).

## 2. Composite hypothesis testing

Consider testing the hypotheses

$$H_0: Y_1, \dots, Y_n \stackrel{\text{iid}}{\sim} \mathcal{N}(\mu, 1), \quad \mu \in \left(-\infty, -\frac{\epsilon}{2}\right)$$
vs.  
$$H_1: Y_1, \dots, Y_n \stackrel{\text{iid}}{\sim} \mathcal{N}(\mu, 1), \quad \mu \in \left(\frac{\epsilon}{2}, \infty\right).$$

- (a) (5 points) Write down the form of the Generalized Likelihood Ratio Test (GLRT) for this problem, in the shortest possible way. What real-valued function of the observations  $y_1, \ldots, y_n$  does the test statistic depend on?
- (b) (5 points) Sketch graphically the GLRT test statistic vs. the real-valued function of  $y_1, \ldots, y_n$ , that you found above, as clearly as you can.

### 3. Geometric distribution estimation

Consider the family of geometric probability distributions  $\{\text{Geom}(\theta) : \theta \in [0, 1]\}$ .

- (a) (3 points) Is this family complete? Why/why not?
- (b) (3 points) Based on *n* iid samples  $X_1, \ldots, X_n$  from  $\text{Geom}(\theta), \theta \in [0, 1]$ , can you find a sufficient statistic for  $\theta$ ?

- (c) (4 points) What is the Fisher information for a single sample? Write down the Cramér-Rao lower bound for the variance of an unbiased estimator of  $\theta$  based on n iid samples from the Geom( $\theta$ ) distribution.
- (d) (3 points) Suppose  $X_1, \ldots, X_n$  are iid samples from  $\text{Geom}(\theta)$ , for some  $\theta \in [0, 1]$ . Find the maximum likelihood estimator (MLE) of  $\theta$  as a function of  $X_1, \ldots, X_n$ .
- (e) (5 points) Suppose  $X_1, \ldots, X_n$  are iid samples from  $\text{Geom}(\theta)$ , for some  $\theta \in [0, 1]$ . Find the best unbiased estimator of  $\theta$  as a function of  $X_1, \ldots, X_n$ . Provide supporting arguments as clearly as possible. (Hint: Start with a crude unbiased estimator of  $\theta$ , then improve it. You can use the fact that the sum  $\sum_{i=1}^{m} (Z_i - 1)$ , where  $Z_i$  are iid  $\text{Geom}(\theta)$  random variables, has the NegBin $(m, \theta)$  distribution.)

#### 4. Linear estimation of an autoregressive process

A zero-mean discrete-time process  $\{X_t\}_{t=-\infty}^{+\infty}$  evolves as

$$X_{t+1} = \alpha X_t + \beta X_{t-1} + W_t, \tag{3}$$

where  $W_t$  is iid  $\mathcal{N}(0, \sigma_1^2)$  state noise across time t. The observations from this process are given by

$$Y_t = X_t + V_t, \tag{4}$$

where  $V_t$  is iid  $\mathcal{N}(0, \sigma_2^2)$  observation noise across time t. Assume that the system is steady state (i.e., the process  $\{X_t\}_t$  is wide-sense stationary).

- (a) (5 points) Can you find the steady state 0-step and 1-step autocorrelations  $r_0 = \text{Cov}(X_t, X_t)$  and  $r_1 = \text{Cov}(X_{t+1}, X_t)$ , in terms of  $\alpha$ ,  $\beta$  and  $\sigma_1^2$ ? (Hint: Use equation (3) creatively.)
- (b) (3 points) Suppose you want to find the best linear MMSE estimate of  $X_{t+1}$  in terms of the immediately preceding observations  $Y_t$  and  $Y_{t-1}$ . Describe how you would find the optimal linear coefficients in terms of  $r_0, r_1, \alpha, \beta$  and  $\sigma_2^2$ .