E2 212: Matrix Theory Fall 2012 – Test 1

Rules

- 1. This exam counts for 30% of your final grade.
- 2. It is a closed book exam. There is no need for a calculator as there are no complex numerical computations involved. Please leave your cell-phones turned off, preferably in your bag.
- 3. Please indicate your final answer clearly (for example, by drawing a box around it) and provide justifications. In your proofs, if you want to use a result stated and proved in class, please clearly state the result you plan to use. Avoid mixing up answers to different questions, making it hard to evaluate.
- 4. The points assigned to a problem does not necessarily indicate its difficulty level. Generally more "basic" questions carry more points.
- 5. Code of conduct: Cheating is, needless to say, strictly forbidden and will be taken extremely seriously, so don't even think about it. I reserve the right to immediately terminate your exam at any point in time if I suspect you of cheating. So, it is your responsibility to conduct yourself in a manner that is completely above board and beyond suspicion.

Problems

- 1. (Vector spaces)
 - (a) If \mathbf{x}, \mathbf{y} and \mathbf{z} are linearly independent, then are $\mathbf{x} + \mathbf{y}, \mathbf{y} + \mathbf{z}$ and $\mathbf{z} + \mathbf{x}$ linearly independent? (3 points)
 - (b) If \mathcal{U} and \mathcal{V} are finite dimensional subspaces of a vector space, then show that (3 points)

$$\dim(\mathcal{U}) + \dim(\mathcal{V}) = \dim(\mathcal{U} + \mathcal{V}) + \dim(\mathcal{U} \cap \mathcal{V})$$

2. Let **X** be partitioned as $\mathbf{X} = \begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{C} & \mathbf{D} \end{bmatrix}$, where **A** and **D** are square matrices of possibly different dimensions.

(a) If **X** is invertible and all the relevant inverses exist, show that (3 points)

$$\mathbf{X}^{-1} = \begin{bmatrix} (\mathbf{A} - \mathbf{B}\mathbf{D}^{-1}\mathbf{C})^{-1} & \mathbf{A}^{-1}\mathbf{B}(\mathbf{C}\mathbf{A}^{-1}\mathbf{B} - \mathbf{D})^{-1} \\ (\mathbf{C}\mathbf{A}^{-1}\mathbf{B} - \mathbf{D})^{-1}\mathbf{C}\mathbf{A}^{-1} & (\mathbf{D} - \mathbf{C}\mathbf{A}^{-1}\mathbf{B})^{-1} \end{bmatrix}$$

(b) If either $\mathbf{B} = \mathbf{0}$ or $\mathbf{C} = \mathbf{0}$, show that $\det \mathbf{X} = (\det \mathbf{A})(\det \mathbf{D})$. (3 points)

- 3. Let $\mathbf{A} \in \mathbb{R}^{m \times n}$ with $m \ge n$, $\mathbf{y} \in \mathbb{R}^n$, and define $\tilde{\mathbf{A}} = \begin{bmatrix} \mathbf{A} \\ \mathbf{y}^T \end{bmatrix}$. Show that $\|\|\mathbf{A}\|\|_2 \le \|\|\mathbf{A}\|\|_2^2 + \|\mathbf{y}\|_2^2$. (6 points)
- 4. Let $\mathbf{A}, \mathbf{B} \in \mathbb{C}^{n \times n}$, and suppose that at least one of \mathbf{A} or \mathbf{B} is nonsingular. Show that
 - (a) **AB** and **BA** have the same eigenvalues, counting multiplicities. (3 points)
 - (b) If **AB** is diagonalizable, then **BA** is diagonalizable. (3 points)
- 5. Let $\lambda_1, \ldots, \lambda_n$ be the eigenvalues of $\mathbf{A} \in \mathbf{C}^{n \times n}$. Then, prove the following:

(a)
$$\operatorname{tr}(\mathbf{A}) = \sum_{i=1}^{n} \lambda_i$$
. (3 points)

(b) det(\mathbf{A}) = $\prod_{i=1}^{n} \lambda_i$. (3 points)