Block Sparse Signal Recovery using Tikhonov Regularization

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Block Sparse Signal Recovery Problem



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- Goal: To recover the block sparse signal x from y
- Block boundaries and sizes are unknown

Current Approaches

- Sparse Bayesian Learning
 - Imposing a sparsity inducing prior on the vector x x ~ N(0, Γ)
 - Hyperparameters γ estimated using evidence maximization or type-II ML [1], [2]
 - Posterior density of the weights [2] is given by

$$p(\mathbf{x}|\mathbf{y};\gamma,\sigma^2) = \mathcal{N}(\mu,\Sigma_{\mathbf{x}})$$
(1)

where

$$\begin{split} \Sigma_{\mathbf{x}} &= (\sigma^{-2} \Phi^{\mathrm{T}} \Phi + \Gamma^{-1})^{-1} \\ \mu &= \sigma^{-2} \Sigma_{\mathbf{x}} \Phi^{\mathrm{T}} \mathbf{y} \end{split}$$

SBL Objective function: To maximize p(y; γ, σ²)

$$\mathbf{L} = \log |\Sigma_{t}| + \mathbf{y}^{\mathrm{T}} \Sigma_{t}^{-1} \mathbf{y}$$
⁽²⁾

where $\Sigma_{t} = (\sigma^{2}I + \Phi\Gamma\Phi^{T})$

Current Approaches

Iterative Reweighted l₁ Minimization [4]

$$x^{(k+1)} = \arg \min_{x} ||y - \Phi x||^2 + \lambda \sum_{i} w_i^{(k)} |x_i|$$
 (3)

x_{SBL} satisfies the below equation [3]

$$\mathbf{x}_{\mathrm{SBL}} = \arg\min_{\mathbf{x}} \|\mathbf{y} - \Phi\mathbf{x}\|^2 + \lambda g_{\mathrm{SBL}}(\mathbf{x}) \tag{4}$$

where $g_{SBL}(x) = min_{\gamma \geq 0} x^T \Gamma^{-1} x + \log \lvert \alpha I + \Phi \Gamma \Phi^T \rvert$

▶ $g_{SBL}(x)$ is a non-decreasing, concave function of |x| and can be optimized using a reweighted ℓ_1 algorithm

$$g_{\rm SBL}(\mathbf{x}) = \min_{\gamma, \mathbf{z} \ge 0} \mathbf{x}^{\rm T} \Gamma^{-1} \mathbf{x} + \mathbf{z}^{\rm T} \gamma - \mathbf{h}^*(\mathbf{z})$$
(5)

where $h^*(z)$ is the concave conjugate of $h(\gamma) = \log |\alpha I + \Phi \Gamma \Phi^T|$ given by $h^*(z) = \min_{\gamma \ge 0} z^T \gamma - \log |\alpha I + \Phi \Gamma \Phi^T|$ (6)

Proposed Approaches

 Solution 1: Tikhonov Regularizer term along with the SBL regularizer

$$g_{SBL}(x) = \min_{\gamma, z \ge 0} x^T \Gamma^{-1} x + z^T \gamma - h^*(z) + \|L\gamma\|_2^2$$
 (7)

where

$$L = \begin{bmatrix} 1 & -1 & 0 & 0 & \dots & 0 \\ 0 & 1 & -1 & 0 & \dots & 0 \\ \dots & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & 1 \end{bmatrix}$$

- Numerical Method approach since there is no analytical solution for the problem. Newton's Method of solving simultaneous linear equations
- Solution 2: ℓ₁ regularizer instead of ℓ₂ regularizer to impose block sparsity constraint on the vector Lγ (Solution was computationally complex and difficult to solve)

Proposed Approaches

- Conventional Expectation Maximization (EM) based Approach (for SBL)
 - Objective Function:

 $E_{x|y,\gamma^{(k)},\sigma^2}[\log(p(y,x;\gamma,\sigma^2)] = E_{x|y,\gamma^{(k)},\sigma^2}[\log(p(x;\gamma))]$ (8)

• E Step: Treat x as hidden variables

$$E_{x|y,\gamma^{(k)},\sigma^2}[x_i^2] = (\Sigma_x)_{i,i} + \mu_i^2$$
(9)

▶ M Step
$$\gamma_i^{k+1} = \mathrm{argmax}_{\gamma_i \geq 0} \mathrm{E}_{\mathrm{x}|\mathrm{y},\gamma^{(k)},\sigma^2}[\mathrm{x}_i^2] \tag{10}$$

where

$$\begin{split} \boldsymbol{\Sigma}_{\mathbf{x}} &= (\sigma^{-2} \boldsymbol{\Phi}^{\mathrm{T}} \boldsymbol{\Phi} + \boldsymbol{\Gamma}^{-1})^{-1} \\ \boldsymbol{\mu} &= \sigma^{-2} \boldsymbol{\Sigma}_{\mathbf{x}} \boldsymbol{\Phi}^{\mathrm{T}} \mathbf{y} \end{split}$$

Prior Model:

$$\gamma = [\epsilon_1, \epsilon_1 + \epsilon_2, ..., \sum_i \epsilon_i]^T$$
(11)

Constraint: $\sum_i \varepsilon_i \geq 0$

EM based Approach

- Solution of the prior model shown above is same as that of the SBL
- ▶ ℓ₁ Regularizer

$$\operatorname{argmin}_{\epsilon} \sum_{i=1}^{N} \frac{b_i}{\sum_{j=1}^{i} \epsilon_j} + \log(\sum_{j=1}^{i} \epsilon_j) + \lambda \|\epsilon\|_1$$
(12)

where $b_i = (\Sigma_x)_{i,i}$

• Constrained optimization approach being derived to solve this problem. Solving N simultaneous equations with the constraint that $\sum_{j=1}^{i} \ge 0$ for all i = 1, 2, ..., N

References

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