

# Error Exponent Analysis for Bayesian Energy Detection under Fading

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# Outline

- ▶ Motivation and System Model.
- ▶ *Error Exponents with a confidence level.*
- ▶ Detection at the Sensor level.
- ▶ Detection at the Fusion Center.
  - ▶ Lower bounds on the error exponents.
  - ▶ Actual error exponents.
- ▶ Application : Narrowband vs. Wideband Sensing.
- ▶ Numerical and Simulation results.



## System Model

- ▶  $N$  sensors with  $M$  observations each.
- ▶ At the individual sensors under low SNR,  
 $V_y \triangleq \frac{1}{M} \sum_{i=1}^M |y_i|^2 - 1$ , and

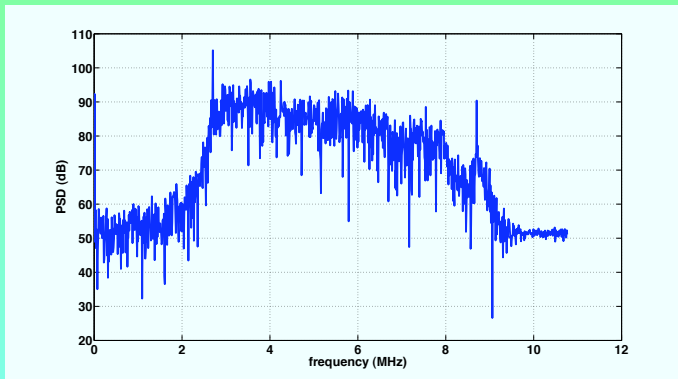
$$\mathcal{H}_0 : V_y \sim \mathcal{N}\left(0, \frac{1}{M}\right),$$

$$\mathcal{H}_1 : V_y \sim \mathcal{N}\left(|h|^2 P, \frac{1}{M}\right).$$

- ▶ **Interest** : Wideband (WB) primary signals with a strong pilot.
- ▶ NB signals undergo Rayleigh fading, WB signals undergo Lognormal fading [Shellhammer et al. 2006]



# Primary Signals of Interest - An Example



# The Bayesian ED Problem

- ▶ Bayesian problem  $\Rightarrow$  minimize  $p_e$ . LRT is optimal.

- ▶ 
$$LR(V_y) = \frac{\frac{1}{\sqrt{2\pi/M}} \int_{|h|^2} \exp\left(-\frac{M(V_y - |h|^2 P)^2}{2}\right) f_{|h|^2}(|h|^2) d|h|^2}{\frac{1}{\sqrt{2\pi/M}} \exp\left(-\frac{MV_y^2}{2}\right)}.$$

- ▶ Closed form analysis of  $p_e$  becomes difficult.



# Error Exponents

- ▶ **Error exponent** gives the exponential rate of decay on  $p_e$ .  
Mathematically,

$$\epsilon_e \triangleq - \lim_{M \rightarrow \infty} \frac{\log p_e}{M} \quad \text{and} \quad \epsilon_E^{(N)} \triangleq - \lim_{M \rightarrow \infty} \frac{\log P_E}{M}.$$

- ▶ Turns out that the error exponents under both WB and NB sensing are zero. Therefore, **in terms of the error exponents, WB and NB sensing problems are equivalent.**
- ▶ Discount the low channel gains?



# Error Exponent With A Confidence Level (EECL)

## Definition

*Let  $S_q$  denote a set of channel instantiations such that  $P(h \in S_q) = q$ . The highest error exponent achievable over all possible choices of  $S_q$  is the error exponent with confidence  $q$ .*

- ▶ This novel concept is used to answer the question of WB vs. NB SS.



# EECL at the Sensor Level

## Theorem

For the above SS problem, a positive error exponent of  $(|h_0|^2 P)^2/8$  is achievable with a confidence level  $q$ , where  $|h_0|^2$  satisfies  $\mathcal{P}(|h|^2 > |h_0|^2) = q$ .

- ▶ Note that the above is valid for a **general fading** model. Also, note that **EECL = 0**, with  $q = 1$ .
- ▶ It follows that,
  - ▶ For **Rayleigh fading** case, an EECL of  $\frac{(\alpha_0 P)^2}{8}$  is achievable with confidence  $\exp(-\alpha_0)$ .
  - ▶ For **lognormal shadowing** case, an EECL of  $\frac{(\ell_0 P)^2}{8}$  is achievable with confidence  $1 - Q\left(\frac{\log(\ell_0/P)}{\sigma_s}\right)$ .





## Outline of the Proof

- ▶ Let  $\alpha = |h|^2$ . It is straightforward to show that

$$p_e = \pi_0 Q(x\sqrt{M}) + \pi_1 \int_{-\infty}^x \int_{\alpha_0}^{\infty} f_N\left(v - \alpha P, \frac{1}{\sqrt{M}}\right) \frac{f_\alpha(\alpha)}{q} d\alpha dv.$$

- ▶ Further simplification yields

$$\frac{q\pi_0}{\pi_1} = \int_{\alpha_0}^{\infty} \exp\left(M\left(x\alpha P - \frac{\alpha^2 P^2}{2}\right)\right) f_\alpha(\alpha) d\alpha.$$

- ▶ The rest of the proof involves showing that  $x \rightarrow \frac{\alpha_0 P}{2}$  as  $M \rightarrow \infty$  and examining the exponent of  $p_f$  (obtained through direct analysis) which is  $\frac{x^2}{2}$ .



- Upper bound** : Let  $g(x, \alpha) \triangleq x\alpha P - \frac{\alpha^2 P^2}{2}$ . Observe that  $g\left(\frac{\alpha_0 P}{2}, \alpha\right) < 0$ , for  $\alpha \geq \alpha_0$ . For  $x_M < \frac{\alpha_0 P}{2}$ ,  $g(x_M, \alpha) < 0$ , for  $\alpha \geq \alpha_0$ . Let  $g_{\max} \triangleq \max_{\alpha \geq \alpha_0} g(x_M, \alpha)$ .  $\Rightarrow$  **The integral would then  $\rightarrow$  zero.**
- Lower bound** : Let  $x_0 > \frac{\alpha_0 P}{2}$ . Therefore,  $g(x_0, \alpha) > 0$ , when  $\alpha < \frac{2x_0}{P}$ . By assumption,  $\alpha_0 \leq \alpha$ .  $\Rightarrow$ ,  $g(x_0, \alpha) > 0$ , when  $\alpha_0 \leq \alpha < \frac{2x_0}{P}$ . Therefore, for  $x_M > x_0$ ,  $g(x_M, \alpha) > 0$ . There exists a  $\delta > 0$ , such that  $g(x_M, \alpha) > 0$ , for  $\alpha_0 \leq \alpha < \frac{2x_0}{P} - \delta$ . Let  $g_{\min} \triangleq \min_{\alpha_0 \leq \alpha < \frac{2x_0}{P} - \delta} g(x_M, \alpha)$ .  $\Rightarrow$  **The integral would then  $\rightarrow +\infty$ .**



## EECL at the FC

- ▶ **Question** : Can EECL be improved with a decentralized detection scheme?
- ▶ **OR rule is considered for analytical tractability**. The FC should exploit even if one of the  $N$  sensors experiences a “good” channel state.



# The analysis

- ▶ Obtain exponent on  $P_F$  (direct) and the same on  $P_M$  (multinomial expansion and analyzing term-by-term) i.e.,

- ▶  $\epsilon_F = \alpha_{\min}^2 P/8$  and  $\epsilon_M = \sum_{j=1}^N \frac{1}{2} \left( \alpha_j P - \frac{\alpha_{\min} P}{2} \right)^2 \mathbb{I} \left\{ \frac{2\alpha_j}{\alpha_{\min}} > 1 \right\}$ .

- ▶ Equating both and bringing in the notion of confidence,

$$\mathcal{P} \left\{ \sum_{j=1}^N \left( \alpha_j - \frac{\alpha_{\min}}{2} \right)^2 \mathbb{I} \left\{ \frac{2\alpha_j}{\alpha_{\min}} > 1 \right\} \leq \frac{\alpha_{\min}^2}{4} \right\} = 1 - q.$$



# LB on EECL using OR rule for Rayleigh fading

## Theorem

When the channel between the primary and sensors is *Rayleigh faded*, given that the FC combines decisions from  $N$  sensors using the *OR rule*, the error exponent with confidence level  $q$  at the FC for the HT **is lower bounded by**  $(\alpha_{\min} P)^2 / 8$  with confidence  $q$ , where  $\alpha_{\min}$  satisfies

$$\alpha_{\min} = 2 \left( \frac{1 - q}{C_N} \right)^{\frac{1}{N}}, \quad C_N \triangleq \sum_{k=0}^N \binom{N}{k} \frac{\mathcal{V}_k}{2^k},$$

where  $\mathcal{V}_k = \pi^{k/2} / \Gamma\left(1 + \frac{k}{2}\right)$  is the volume of a  $k$  dimensional unit sphere.



# LB on EECL using OR rule for Lognormal fading

## Theorem

When the channel between the primary and sensors is *lognormal faded*, given that the FC combines the decisions from  $N$  sensors using the *OR rule*, the error exponent with confidence level  $q$  at the FC for HT is *lower bounded by*  $\frac{(\ell_{\min}P)^2}{8}$  with confidence  $q$ , where  $\ell_{\min}$  satisfies

$$\sum_{k=0}^N \binom{N}{k} D_A^k D_B^{N-k} \frac{\mathcal{V}_k}{2^k} = 1 - q, \text{ with } \mathcal{V}_k = \pi^{k/2} / \Gamma\left(1 + \frac{k}{2}\right)$$

$$D_A \triangleq \frac{1}{2\sigma_s\sqrt{2\pi}} \exp\left(-\frac{\left(\log\left(\frac{\ell_{\min}}{P}\right)\right)^2}{2\sigma_s^2}\right), D_B \triangleq Q\left(\frac{1}{\sigma_s} \log\left(\frac{2P}{\ell_{\min}}\right)\right)$$



## EECL at the FC - OR rule and Rayleigh

### Theorem

When the channel between the primary transmitter and sensors is *Rayleigh faded*, given that the FC combines decisions from  $N$  sensors using the *OR rule*, the error exponent on the probability of error at the FC for the above SS problem is positive and is given by  $\frac{(\alpha_{min}P)^2}{8}$  with confidence  $q$ , where  $\alpha_{min}$  satisfies

$$\sum_{l=1}^N \binom{N}{l} \left[ 1 - \exp\left(-\frac{\alpha_{min}}{2}\right) \right]^{N-l} \mathcal{P} \left\{ \sum_{k=1}^l a_k^2 \leq 1 \right\} e^{-\frac{\alpha_{min}}{2} l} + \left[ 1 - \exp\left(-\frac{\alpha_{min}}{2}\right) \right]^N = 1 - q,$$

where,  $a_k \sim \exp\left(\frac{\alpha_{min}}{2}\right)$ .



## EECL at the FC - OR rule and Lognormal

### Theorem

The same detector under *lognormal fading* achieves an error exponent of  $\frac{(\ell_{\min} P)^2}{8}$  with confidence  $q$ , where  $\ell_{\min}$  satisfies

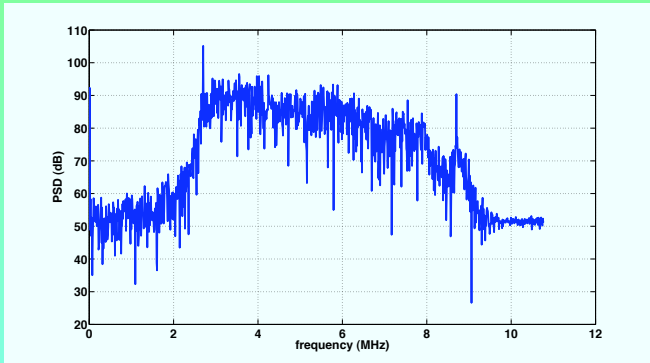
$$\sum_{l=1}^N \binom{N}{l} \left[ Q \left( -\frac{\mu_s + \log \left( \frac{2}{\ell_{\min}} \right)}{\sigma_s} \right) \right]^{N-l} \mathcal{P} \left\{ \sum_{k=1}^l (t_k - 1)^2 \leq 1 \right\} + \left[ Q \left( -\frac{\mu_s + \log \left( \frac{2}{\ell_{\min}} \right)}{\sigma_s} \right) \right]^N = 1 - q,$$

where,  $t_k \sim \mathcal{LN} \left( \mu_s + \log \left( \frac{2}{\ell_{\min}} \right), \sigma_s \right)$ .





# Application : WB and NB SS



**Figure:** DTV Power Spectral Density



## Quantifying in terms of error exponents with confidence

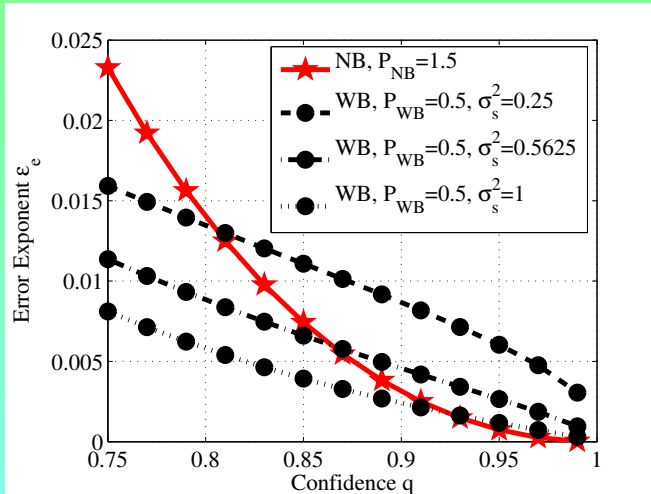
- ▶ Let  $\epsilon_{NB}$  and  $\epsilon_{WB}$  represent the error exponents by detectors under NB and WB SS, respectively.
- ▶ At the individual sensors, with the same confidence level  $q$ , NB sensing is “better” than WB sensing whenever,

$$\frac{(\alpha_0 P_{NB})^2}{8} > \frac{(I_0 P_{WB})^2}{8} \Rightarrow \left( \frac{P_{NB}}{P_{WB}} \right)^2 > \left( \frac{I_0}{\alpha_0} \right)^2.$$

- ▶ Similarly, at the FC, NB sensing is better than WB sensing with the same confidence level whenever

$$\frac{(\alpha_{\min} P_{NB})^2}{8} > \frac{(\ell_{\min} P_{WB})^2}{8} \Rightarrow \left( \frac{P_{NB}}{P_{WB}} \right)^2 > \left( \frac{\ell_{\min}}{\alpha_{\min}} \right)^2.$$





**Figure:** Error Exponents  $\epsilon_e$  with confidence  $q$  at single sensor



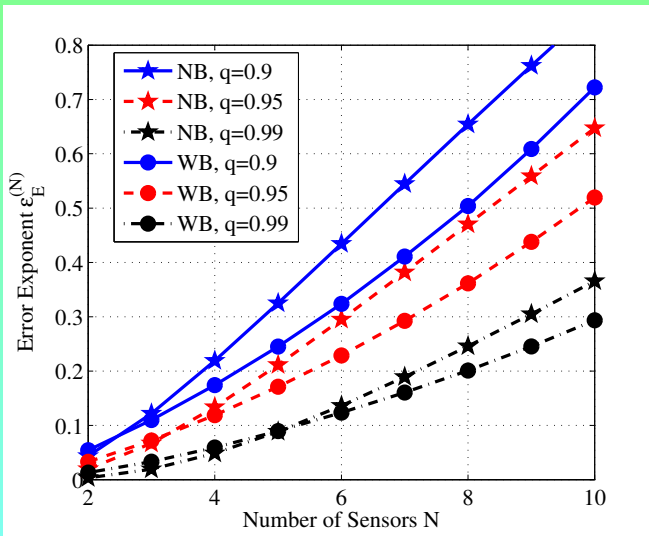


Figure. Variation of  $\epsilon_E^{(N)}$  with  $q$



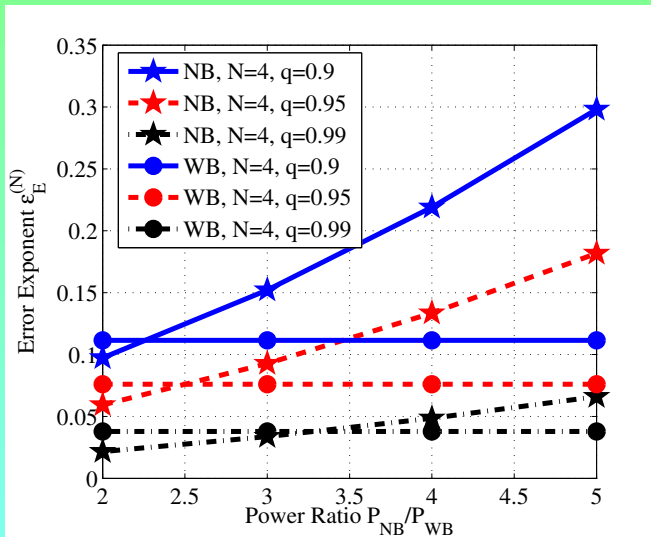


Figure. Variation of  $\epsilon_E^{(N)}$  with ratio  $\frac{P_{NB}}{P_{WB}}$



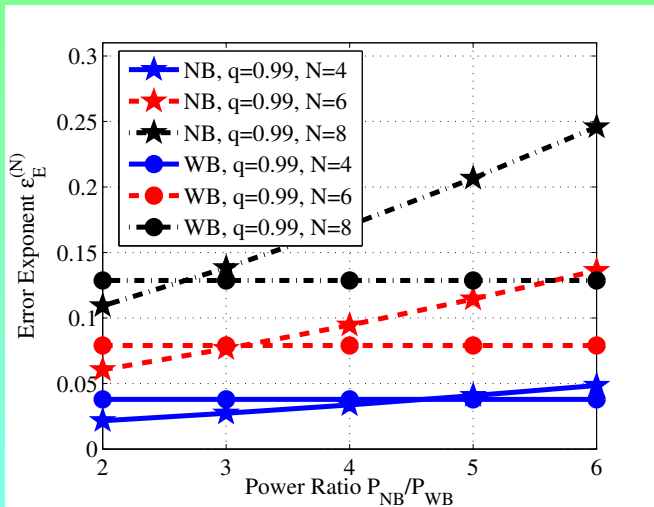


Figure: Variation of  $\epsilon_E^{(N)}$  with ratio  $\frac{P_{NB}}{P_{WB}}$



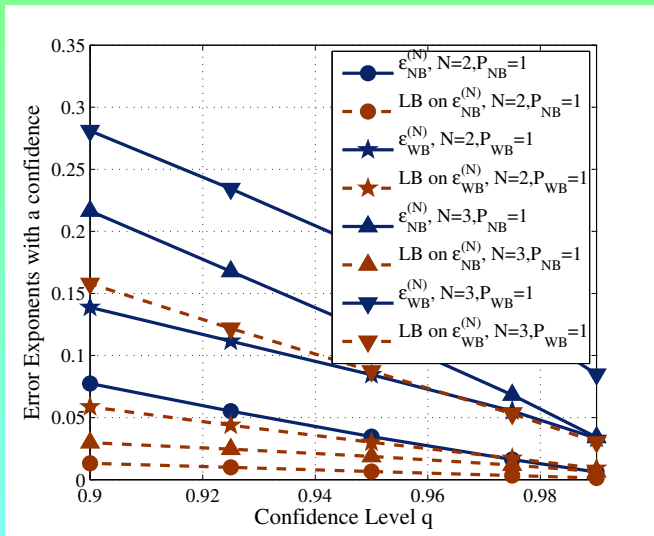


Figure. Comparison of  $\epsilon_E^{(N)}$  and its LB



# List of $\alpha_{\min}$ and $\ell_{\min}$ for Different $q$ and $N$

$N$	$q=0.9$		$N$	$q=0.95$		$N$	$q=0.99$	
	$\alpha_{\min}$	$\ell_{\min}$		$\alpha_{\min}$	$\ell_{\min}$		$\alpha_{\min}$	$\ell_{\min}$
2	0.3937	0.5268	2	0.2635	0.4111	2	0.1109	0.2578
3	0.6579	0.7497	3	0.4878	0.6078	3	0.2612	0.4119
4	0.8824	0.9442	4	0.6890	0.7799	4	0.4153	0.5502
5	1.07489	1.1200	5	0.8665	0.9358	5	0.5610	0.6771
6	1.2428	1.2875	6	1.02403	1.0819	6	0.6958	0.7949
7	1.3916	1.4500	7	1.1652	1.2235	7	0.8201	0.9062
8	1.5251	1.6062	8	1.2930	1.3602	8	0.9349	1.0144
9	1.6462	1.7655	9	1.4097	1.4971	9	1.0412	1.1209
10	1.7571	1.9230	10	1.5171	1.6308	10	1.1403	1.2257





# Theoretical and Simulated Error Exponents (1/2)

P (dB)	q=0.9		P (dB)	q=0.95		P (dB)	q=0.99	
	Th	Sims		Th	Sims		Th	Sims
-3	34.69	35.912	0	32.888	34.189	5	11.364	14.495
-4	22.02	23.556	-0.5	26.6639	28.232	4	7.8913	9.3611
-5	12.488	13.633	-1	21.048	22.301	3	5.0505	7.3419
-7	5.5504	6.5754	-1.5	16.115	17.642	2	2.8409	4.3919
-10	1.3876	2.1998	-2.25	11.84	14.282	0	1.2626	2.3234

**Table:**  $\epsilon_e$  for different  $q$ . All EECL values have to be multiplied by  $\times 10^{-5}$ .



## Theoretical and Simulated Error Exponents (2/2)

N	q=0.9, P=-10 dB		N	q=0.95, P=-10 dB	
	Th	Sims		Th	Sims
2	1.9373	2.1102	2	0.86768	0.88057
3	5.4111	6.1154	3	2.9749	3.5199
4	9.7329	10.2832	4	5.9349	6.3426

**Table:**  $\epsilon_E^{(N)}$  for different  $q$ . All EECL values have to be multiplied by  $\times 10^{-4}$ .



# Conclusions

- ▶ Proposed a novel concept called *error exponent with a confidence level*. Using this, it was shown that the ED achieves a zero error exponent under a general fading model.
- ▶ This generalized concept was extended to the decentralized setup and performance under the OR rule was studied in detail.
- ▶ The question of WB vs. NB sensing was successfully answered using this novel metric.



# Reference

- ▶ Sanjeev G., Chandra R. Murthy and Vinod Sharma, [Error Exponent Analysis of Energy-Based Bayesian Spectrum Sensing Under Fading Channels](#), Journal draft.

