# Interference Modeling and Simulator

Raksha Ramakrishna SPC lab IISc Bangalore



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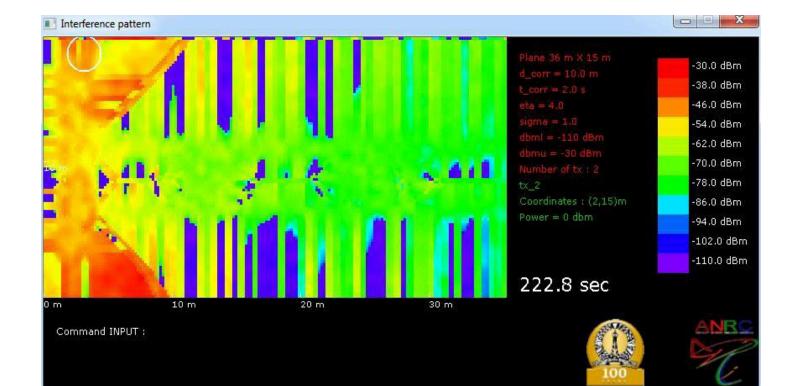
# Objective:

To develop a Visualization tool to view the power pattern on a plane due to 13 Access Points:

- path loss values- real world dataset
- Shadowing-artificial

### Overview

- Real world data CRAWDAD website incorporated into simulator
- Dataset-RSSI from 14 APs recorded at 581 points.
- Path loss values extracted from dataset-Linear interpolation
- Shadowing- still artificial



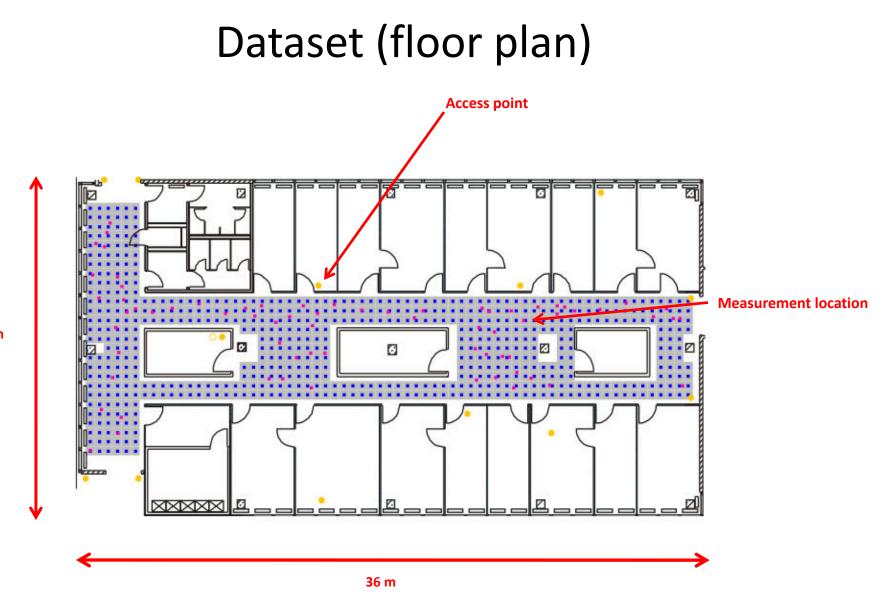


Fig: Floor plan

15 m

## Dataset (format)

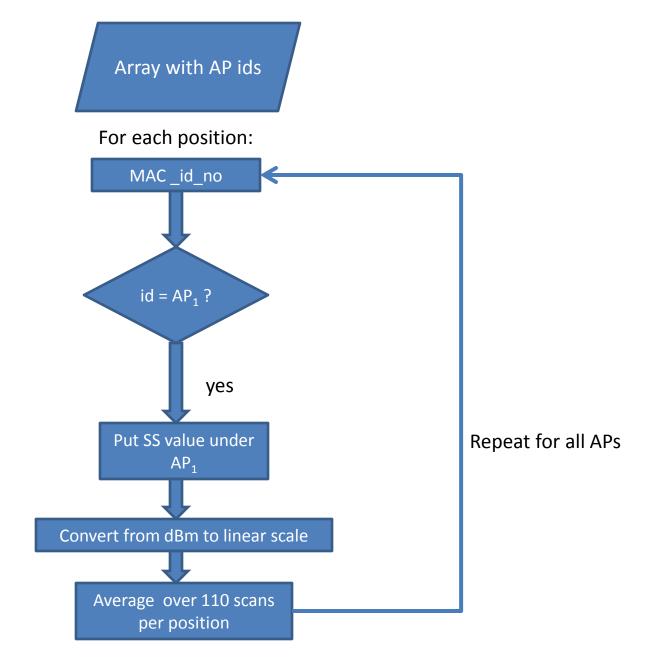
| t | id | pos | degree | MAC_AP_1=<br>SS , freq, | MAC_AP_2=<br>SS , freq, | <br>MAC_AP_N=<br>SS , freq, |
|---|----|-----|--------|-------------------------|-------------------------|-----------------------------|
|   |    |     |        | mode                    | mode                    | mode                        |

| t          | Timestamp                |
|------------|--------------------------|
| id         | MAC-scanning device      |
| pos        | Coordinate-(x,y,z)       |
| degree     | Orientation-degrees      |
| MAC_AP_No. | MAC -responding AP       |
| SS         | Signal strength in dBm   |
| freq       | Channel frequency        |
| mode       | Access point =3, adhoc=1 |

# Raw data:

| #               | trace           | started              | 2006-10-14                           | 09:42:16                            |
|-----------------|-----------------|----------------------|--------------------------------------|-------------------------------------|
| #               | iwlib           | based                | active                               | scan                                |
| t=1160811736850 | pos=0.0,0.0,0.0 | id=00:02:2D:21:0F:33 | 00:14:BF:B1:97:81=-43,2.467E9,3,-102 | 00:14:BF:B1:7C:54=-50,2.412E9,3,-94 |
| t=1160811737110 | pos=0.0,0.0,0.0 | id=00:02:2D:21:0F:33 | 00:14:BF:B1:97:81=-47,2.467E9,3,-100 | 00:14:BF:B1:7C:54=-50,2.412E9,3,-96 |
| t=1160811737394 | pos=0.0,0.0,0.0 | id=00:02:2D:21:0F:33 | 00:14:BF:B1:97:81=-43,2.467E9,3,-95  | 00:14:BF:B1:7C:54=-52,2.412E9,3,-97 |
| t=1160811737662 | pos=0.0,0.0,0.0 | id=00:02:2D:21:0F:33 | 00:14:BF:B1:7C:54=-49,2.412E9,3,-94  | 00:14:BF:B1:97:8D=-58,2.417E9,3,-98 |
| t=1160811737938 | pos=0.0,0.0,0.0 | id=00:02:2D:21:0F:33 | 00:14:BF:B1:97:81=-44,2.467E9,3,-99  | 00:14:BF:B1:7C:54=-50,2.412E9,3,-97 |
| t=1160811738206 | pos=0.0,0.0,0.0 | id=00:02:2D:21:0F:33 | 00:14:BF:B1:97:81=-44,2.467E9,3,-100 | 00:14:BF:B1:7C:54=-49,2.412E9,3,-95 |
| t=1160811738474 | pos=0.0,0.0,0.0 | id=00:02:2D:21:0F:33 | 00:14:BF:B1:7C:54=-49,2.412E9,3,-95  | 00:14:BF:B1:97:81=-46,2.467E9,3,-92 |
| t=1160811738750 | pos=0.0,0.0,0.0 | id=00:02:2D:21:0F:33 | 00:14:BF:B1:7C:54=-48,2.412E9,3,-97  | 00:14:BF:B1:97:81=-46,2.467E9,3,-94 |
| t=1160811739034 | pos=0.0,0.0,0.0 | id=00:02:2D:21:0F:33 | 00:14:BF:B1:97:81=-45,2.467E9,3,-99  | 00:14:BF:B1:7C:54=-48,2.412E9,3,-97 |

#### Data Extraction:



### Data extracted using Matlab

|    | 1                 | 2              | 3            | 4            | 5             | 6            | 7             | 8             | 9            | 10           | 11           | 12           | 13           | 14          | 15           | 16           |
|----|-------------------|----------------|--------------|--------------|---------------|--------------|---------------|---------------|--------------|--------------|--------------|--------------|--------------|-------------|--------------|--------------|
| 1  | 'positions'       | '00:11:88:28:5 | '00:14:BF:B1 | '00:14:BF:B1 | '00:13:46:26: | '00:14:BF:B1 | '00:13:46:32: | '00:11:88:28: | '00:14:BF:B1 | '00:14:6C:62 | '00:14:BF:3B | '00:14:6C:62 | '00:14:6C:62 | '00:0F:B5:D | '00:14:BF:B1 | '00:14:BF:B1 |
| 2  | 'pos=0.0,0.0,0.0' | 1.8093e-06     | 9.5565e-06   | 1.9552e-06   | 1.3916e-07    | 3.8967e-07   | NaN           | 2.6031e-07    | 1.5484e-07   | 1.3567e-08   | 5.8708e-08   | 2.7495e-09   | 1.4622e-09   | NaN         | 3.3263e-05   | 6.5705e-07   |
| 3  | 'pos=0.0,0.5,0.0' | 4.6165e-06     | 2.0375e-05   | 1.4790e-06   | 1.5860e-07    | 3.7309e-07   | NaN           | 4.5052e-07    | 5.9199e-08   | 5.5183e-08   | 1.0188e-07   | 2.2018e-09   | 9.9142e-10   | 7.9900e-10  | 7.6558e-05   | 2.3048e-06   |
| 4  | 'pos=0.0,1.0,0.0' | 2.3662e-06     | 1.4943e-05   | 4.8906e-06   | 9.0921e-08    | 3.9527e-07   | NaN           | 2.8840e-07    | 4.4365e-07   | 1.6114e-08   | 7.3533e-08   | 2.1151e-09   | 8.4978e-10   | 6.8010e-10  | 6.0902e-05   | 2.5306e-06   |
| 5  | 'pos=0.0,1.5,0.0' | 2.3363e-06     | 7.2863e-06   | 4.3787e-06   | 3.1748e-07    | 7.0657e-07   | NaN           | 3.3346e-07    | 4.8396e-07   | 2.9006e-08   | 1.1210e-07   | 1.9475e-09   | 1.7940e-09   | 6.8974e-10  | 3.4950e-05   | 1.1796e-06   |
| 6  | 'pos=0.0,2.0,0.0' | 1.2130e-06     | 2.1483e-06   | 3.2767e-06   | 2.0099e-07    | 1.1970e-06   | 3.1623e-09    | 2.8551e-07    | 5.2641e-07   | 1.5642e-08   | 8.4234e-08   | 1.5685e-09   | 1.0951e-09   | 7.5201e-10  | 3.3268e-05   | 1.7739e-06   |
| 7  | 'pos=0.0,2.5,0.0' | 2.7468e-06     | 4.2785e-06   | 2.2540e-06   | 5.3725e-07    | 1.0392e-06   | NaN           | 4.1961e-07    | 1.7205e-07   | 1.6253e-08   | 7.0558e-08   | 2.4345e-09   | 1.1227e-09   | 8.9080e-10  | 4.1204e-05   | 3.9430e-06   |
| 8  | 'pos=0.0,3.0,0.0' | 2.1596e-06     | 5.0041e-06   | 1.6357e-06   | 4.4488e-08    | 1.4648e-06   | NaN           | 4.2925e-07    | 2.7954e-07   | 7.6622e-09   | 1.3271e-07   | 1.6615e-09   | 1.4363e-09   | 6.9214e-10  | 2.5152e-05   | 3.6593e-06   |
| 9  | 'pos=0.0,3.5,0.0' | 2.6249e-06     | 6.8730e-06   | 5.8339e-07   | 7.5081e-08    | 1.5766e-06   | NaN           | 3.6236e-07    | 5.5727e-07   | 2.4784e-08   | 6.3280e-08   | 2.7784e-09   | 3.8353e-09   | 1.1476e-09  | 1.8153e-05   | 2.2291e-06   |
| 10 | 'pos=0.0,4.0,0.0' | 2.3857e-06     | 5.6642e-06   | 8.7496e-07   | 1.8375e-07    | 5.9532e-07   | 4.6642e-09    | 2.2902e-07    | 5.1434e-07   | 3.6260e-09   | 5.4781e-08   | 1.5779e-09   | 9.9952e-10   | 1.0666e-09  | 1.8878e-05   | 4.9291e-06   |
| 11 | 'pos=0.0,4.5,0.0' | 4.6747e-06     | 9.5667e-06   | 1.2515e-06   | 4.4144e-07    | 6.7152e-07   | 4.4536e-09    | 2.1203e-07    | 7.6807e-07   | 9.5683e-09   | 8.9647e-08   | 1.7994e-09   | 1.0920e-09   | 4.9429e-10  | 1.9743e-05   | 4.3646e-06   |
| 12 | 'pos=0.0,5.0,0.0' | 2.8465e-06     | 3.0160e-06   | 8.7623e-07   | 1.0345e-07    | 3.8409e-07   | NaN           | 1.2723e-07    | 2.2818e-07   | 1.4488e-08   | 5.4339e-08   | 2.8824e-09   | 1.1111e-09   | 6.2762e-10  | 3.1513e-05   | 5.6700e-07   |
| 13 | 'pos=0.0,6.0,0.0' | 3.4627e-06     | 1.3861e-06   | 3.6777e-07   | 1.1721e-07    | 6.9919e-07   | NaN           | 3.9499e-07    | 4.5271e-07   | 3.4050e-09   | 3.5455e-08   | 1.6443e-09   | 1.8510e-09   | NaN         | 3.2388e-06   | 2.2048e-06   |
| 14 | 'pos=0.0,6.5,0.0' | 4.8199e-06     | 2.4915e-06   | 2.1872e-06   | 4.0692e-07    | 6.7155e-07   | NaN           | 2.3162e-07    | 3.3362e-07   | 9.4176e-09   | 5.2980e-08   | 3.3780e-09   | 7.9439e-10   | 8.2344e-10  | 1.4614e-06   | 8.3418e-07   |

### **Linear Interpolation**

• Solve the system of equations:

 $z_1 = ax_1 + by_1 + c;$   $z_2 = ax_2 + by_2 + c;$  $z_3 = ax_3 + by_3 + c;$ 

- $z_{1,} z_{2,} z_{3}$ : power measurements
- $(x_1, y_1), (x_2, y_2), (x_3, y_3)$ : position of measurements.
- Find a,b and c.

- $z_4 = ax_4 + by_4 + c;$
- (x<sub>4</sub>, y<sub>4</sub>): point –value needed.
- Z<sub>4</sub> –value after interpolation

Done for all (184 X 98) points.

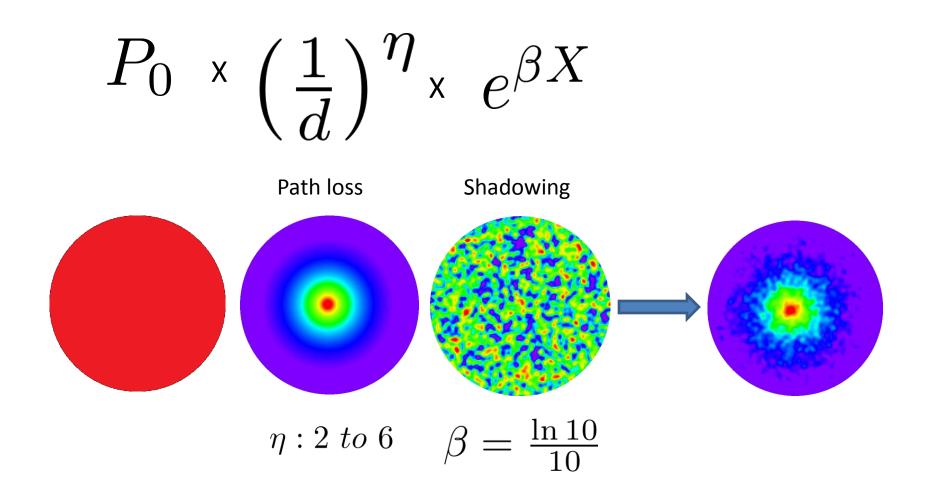
#### To Pick $(x_1, y_1), (x_2, y_2), (x_3, y_3)$ :

- 1. Find distance to all 581 points from  $(x_4, y_4)$ .
- 2. Sort distances-ascending order
- 3. Pick 3 points (least distance) such that:
  - Should not be collinear
  - Power value-available at that point.

# Simulator

- 13 Access Points at fixed locations.
- AP<sub>i</sub> power P<sub>i</sub>.
- Power value -effect of all APs calculated colour displayed corresponding to the power level.
- power radiated by each AP- path-loss + time varying shadowing.

Power pattern for individual transmitters



### Power at each point:

• P(x,y) at (x,y):

$$P(x,y) = \sum_{i=1}^{tx\_num} P_i e^{\beta X} \left( \frac{d_0}{d((x,y),(x_i,y_i))} \right)^{\eta}$$

 $tx\_num$ 

No. of transmitters

 $d((x,y),(x_i,y_i))$ 

Euclidean distance

 $\eta$ 

path loss exponent

X

Gaussian distributed space time correlated random field

$$\beta$$
 =  $\log(10)/10$ 

$$\mathbf{E}\left[X(x,y,t)X(x+\delta_x,y+\delta_y,t+\tau)\right] = e^{-\frac{\delta_x^2+\delta_y^2}{d_{corr}^2}-\frac{\tau^2}{t_{corr}^2}}$$

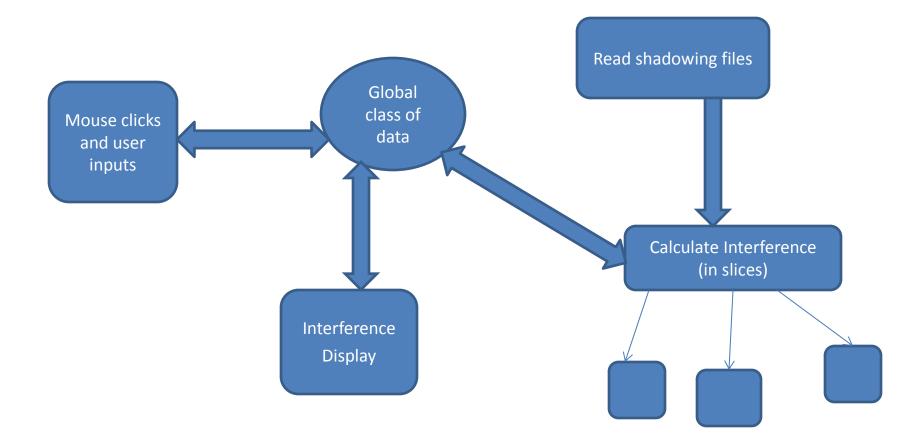
 $d_{corr}$  $t_{corr}$ 

Decorrelation distance

Decorrelation time

Demo

### Structure of simulator



# Modifications

Mouse clicks and user inputs •No movement of APs -fixed locations •t\_corr,sigma,dbml,dbmu -changeable

Interference Display Scaling-according to floor plan-window sizeScaling-no change with d\_corr

### **Modifications-contd**

Arrays – •X & Y coordinates of APs •Path loss values –each AP<sub>1</sub> , AP<sub>2</sub> etc



Switch case: Read from AP<sub>1</sub> if k=1 Read from AP<sub>2</sub> if k=2 etc

Put in shadowing values *log* (output power)
Plot corr colour

## Further Improvements

- Extracting shadowing information from the dataset.
- Using other interpolation techniques.
- Change shadowing by changing the decorrelation distance d\_corr.
- Improving the GUI

# Bibliography

• Dataset from CRAWDAD:

http://crawdad.cs.dartmouth.edu/meta.php?name=mannhei m/compass#N100E0

- Deployment, Calibration, and Measurement Factors for Position Errors in 802.11 based Indoor Positioning Systems-Thomas King, Thomas Haenselmann,Wolfgang Effelsberg.
- An interference simulator for shadow fading environments Document by Joyson Sebastian
- stackoverflow.com