Journal Watch:

Recent papers on ArXiV related to Sparse Signal Recovery

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Prior Support Knowledge-Aided Sparse Bayesian Learning with Partly Errorneous Support

Information Authors: Jun Fang, Yanning Shen, Fuwei Li and Hongbin Li

Problem Statement:

- Sparse signal recovery with partial support information.
- ▶ Recover sparse $\mathbf{x} \in \mathbb{R}^n$ from m(< n) measurements $\mathbf{y} \in \mathbb{R}^m$, where

$$\mathbf{y} = \mathbf{A}\mathbf{x} + \mathbf{w}$$

Prior support information available in the form of index set P

T, where T is the true support. P can be slightly erroneous.

Proposed algorithm

- Modification to SBL to accomodate prior support information P.
- A three layer hierarchical model is proposed

$$p(\mathbf{x}|\alpha) = \prod_{i=1}^{n} \mathcal{N}(0, \alpha_i^{-1}) \qquad p(\alpha) = \prod_{i=1}^{n} \operatorname{Gamma}(\alpha_i | a, b_i)$$

$$p(b_i) = \begin{cases} \text{Gamma}(b_i|p,q) & i \in P \\ \delta(b_i - 10^{-4}) & i \in P^c \end{cases}$$

Variational Bayesian Inference used to obtain posterior distribution of x and other hidden variables in the latent model.

MAP Support Detection for Greedy Sparse Signal Recovery Algorithms in Compressive Sensing

Authors: Namyoon Lee (Univ. of Texas, Austin)

- Problem Statement:
 - Recover sparse vector x from compressive linear measurements
 y = Ax + w
 - MAIN IDEA: Using MAP support detection techniques in greedy algorithms such as MP, OMP, CoSamp, etc. results in improved performance (at the cost of more computations)

MAP support detection technique

- Conventional way is to pick columns of A in a greedy manner which are maximally correlated with the residual.
- Residual: $\mathbf{r} = \sum_{l \in T \setminus S^{k-1}} \mathbf{a}_l x_l$
- For index *i*, generate correlation metric $Z_i^k = \frac{\mathbf{a}_n^T \mathbf{r}^{k-1}}{||\mathbf{a}_n||_2}$
- Choose index with maximum a posteriori ratio for given observation Z^k_i

$$\Lambda(Z_i^k) = \log \frac{\mathbb{P}(i \in T | Z_i^k)}{\mathbb{P}(i \notin T | Z_i^k)}$$

Closed form expression for Λ(Z^k_i) for different source distributions.

Authors: Jong Chul Ye, Jong Min Kim and Yoram Bresler, KAIST, Korea

- Recover joint sparse vectors X from L compressive linear measurements (MMVs) Y_{m×L} = A_{m×N}X + W.
- ▶ In M-SBL, we do MAP estimation of **X** by assuming parameterized prior on **X**.

$$p(\mathbf{X}; \boldsymbol{\gamma}) = \prod_{j=1}^{L} \mathcal{N}(0, \Gamma), \qquad \Gamma = \operatorname{diag} \boldsymbol{\gamma}$$

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► The prior parameters are found via Type-2 ML estimation, by maximizing $L(\gamma) = Tr((\sigma^2 \mathbf{I} + \mathbf{A}\Gamma \mathbf{A}^T)^{-1} Y Y^T) + N \log |\sigma^2 + \mathbf{A}\Gamma \mathbf{A}^T|$

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 $\begin{aligned} & \text{(Wipf, Rao, Natrajan) An alternate interpretation of M-SBL algorithm:} \\ & \min_{\mathbf{X}} ||\mathbf{Y} - \mathbf{A}\mathbf{X}||_{F}^{2} + \sigma^{2}g_{MSBL}(\mathbf{X}) & (\text{Solve for } X) \\ & g_{MSBL}(\mathbf{X}) = \min_{\boldsymbol{\gamma} \geq 0} \text{Tr}(\mathbf{X}^{T}\Gamma^{-1}\mathbf{X}) + N\log|\sigma^{2}\mathbf{I} + \mathbf{A}\Gamma\mathbf{A}^{T}| & (\text{Solve for } \boldsymbol{\gamma}) \end{aligned}$

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- The first term in (1) behaves like $N||\gamma||_0$.
- The non-separability of log |σ²I + AΓA^T| term is the main reason why MSBL is able to dodge many local minimizers.

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$$g_{MSBL}(\mathbf{X}) = \min_{\gamma \ge 0} \mathcal{T}(\mathbf{X}^T \Gamma^{-1} \mathbf{X}) + N \log |\sigma^2 \mathbf{I} + \mathbf{A} \Gamma \mathbf{A}^T| \qquad (\text{Solve for } \gamma) \quad (1)$$

- The first term in (1) behaves like $N||\gamma||_0$.
- The non-separability of log |σ²I + AΓA^T| term is the main reason why MSBL is able to dodge many local minimizers.
- Looking purely from cost function point of view, can we do better?

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 (Solve for $\boldsymbol{\gamma}$)

Rank proxy interpretation for log-det term

• As $\sigma^2 \rightarrow 0$,

$$g_{MSBL}(\mathbf{X}) \approx \min_{\boldsymbol{\gamma} \geq 0} N ||\boldsymbol{\gamma}||_0 + N \cdot RankProxy(\mathbf{A}\Gamma^{\frac{1}{2}})$$

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► Log-det penalty can be replaced with a better penalty: Rank-Proxy($Q^T \mathbf{A} \Gamma^{\frac{1}{2}}$), where Q is a basis of noise subspace, i.e. $R(Q) = R^{\perp}(\mathbf{Y})$

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- Why RankProxy($Q^T \mathbf{A} \Gamma^{\frac{1}{2}}$) instead of RankProxy($\mathbf{A} \Gamma^{\frac{1}{2}}$)?

Theorem

If $||\mathbf{X}||_0$, $\mathbf{Y} = \mathbf{A}\mathbf{X}$ and if \mathbf{A} satisfies RIP, then we have:

support(
$$\mathbf{X}$$
) = arg min rank($Q^T A_I$)
 $|I| \ge k$

Using Schatten-p norm as rank-proxy leads to performance better than M-SBL.

Bayesian Hypothesis Testing for Block Sparse Signal Recovery Authors: Mehdi Korki, Hadi Zayyani and Jingxin Zhang

Problem statement

▶ Recover a block sparse $\mathbf{x} \in \mathbb{R}^n$ from m(< n) measurements $\mathbf{y} \in \mathbb{R}^m$, where

$$\mathbf{y} = \mathbf{A}\mathbf{x} + \mathbf{w}$$

- Blocks are of unequal sizes and with unknown boundaries
- Main contributions
 - Proposes Block Bayesian Hypothesis Testing Algorithm (Block-BHTA)
 - Assumes Bernoulli Gaussian signal prior:

$$p(x_i) = p\delta(x_i) + (1-p)\mathcal{N}(0,\sigma_s^2)$$

- ► Transitional probabilities $p_{01} \triangleq Pr(x_{i+1} = 0|x_i \neq 0)$ and $p_{10} \triangleq Pr(x_{i+1} \neq 0|x_i = 0)$ are used to encode block structure.
- In steady state (large n),

$$Pr(x_i = 0) = p = \frac{p_{10}}{p_{01} + p_{10}} \qquad Pr(x_i = 1) = p = \frac{p_{01}}{p_{01} + p_{10}}$$

Block start identified at index i if:

$$p_{10}p(\mathbf{y}|x_i=0, x_{i+1} \neq 0) > p_{00}p(\mathbf{y}|x_i=0, x_{i+1}=0)$$

Similar test for identification of block termination

Other Interesting Papers:

- Sparse Multinomial Logistic Regression via Approximate Message Passing, Evan Byrne and Philip Schniter
- Bayesian Masking: Sparse Bayesian Estimation with Weaker Shrinkage Bias, Kondo, Hayashi and Maeda
- Recovery of Sparse Positive Signals on the Sphere from Low Resolution Measurements, Tamir Bendory and Yonina C. Eldar
- SAFFRON: A Fast, Efficient and Robust Framework for Group Testing based on Sparse Graph Codes, Kangwook Lee, Ramtin Pedarsani and Kannan Ramachandran
- Bayesian Optimal Approximate Message Passing to Reciver Structured Sparse Signals, Martin Mayer and Nobert Goertz
- Super-Resolution Sparse MIMO-OFDM Channel Estimation Based on SPatial and Temporal Correlations, Zaocheng Wang et al.
- A framework for sparse online learning and its applications, Dayong Wang, Pengchecg Wu, Peilin Zhao, Steven C. H. Hoi
- Type-I and Type-II Bayesian Methods for Sparse Signal Recovery using Scale Mixtures, Ritwik Giri and Bhaskar D. Rao

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