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## Asynchronous Capacity per Unit Cost

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- Synchronization: important aspect of any communication system
- Problem: What is the fundamental limitation due to the lack of a priori synchrony between the transmitter and the receiver in bursty communication?
- Performance measure
  - Data rate: delay sensitive
  - Capacity per unit cost: constrained in energy
- The data burst arrives at a random symbol time (ν), not known a priori to the receiver

- $\nu \in [0, A]$ : known at transmitter and receiver
- Decoder: sequential test (τ, φ): τ: stopping time and φ: declares the decoding message
- Main result: single-letter characterization of the asynchronous capacity per unit cost
- No cost for idle symbols:

 $(B + \log A)k_{sync}$ 

 $k_{sync}$ : minimum cost to transmit one bit of information in the synchronous setting

 Degrees of Freedom Region of the MIMO Interference Channel With Output Feedback and Delayed CSIT

Authors: R. Tandon, S. Mohajer, H. V. Poor, and S. Shamai (Shitz)

Affiliations: Virginia Polytechnic Institute and State University, USA, University of California, Berkeley, USA, Princeton University, Princeton, USA and Technion-Israel Institute of Technology, Israel

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- System model
  - 2-user MIMO interference channel (IC) with arbitrary numbers of antennas at each terminal
  - Local output feedback and delayed CSIT
- Goal: characterize the DoF region



- Main result: output feedback and delayed CSIT can strictly enlarge the DoF region as compared to delayed CSIT only
- DoF region with local feedback and delayed CSIT = DoF region with global feedback and delayed CSIT
- Converse: channels to the two receivers need not be statistically equivalent



 Distributed Optimization in an Energy-Constrained Network: Analog Versus Digital Communication Schemes

Authors: A. Razavi, W. Zhang, and Z. Luo

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- Network of *n* nodes collaborate to minimize a cost function:  $f(\mathbf{x})$ , where  $\mathbf{x} = [x_1, x_2, \dots, x_n]$
- x<sub>l</sub>: a local variable controlled by the node S<sub>l</sub>
- Capability of nodes:
  - Can perform local computation
  - Can exchange analog or digital messages with a set of predefined neighbors through orthogonal noisy channels

 Convergence has remained an important issue in such problems

- Objective: impact of communication energy on convergence
- Main results
  - Communication energy required to obtain an *ϵ*-minimizer of *f*(**x**) must grow at least at the rate of Ω(1/*ϵ*)
  - Bound is tight when f is convex quadratic
  - Same energy requirement can be reduced to O(log<sup>2</sup> 1/ε) if a suitable digital communication scheme is used

 Performance Guarantees of the Thresholding Algorithm for the Cosparse Analysis Model

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- Cosparse analysis model: signal can be multiplied by an analysis dictionary → sparse outcome
- Ω ∈ R<sup>p×d</sup>: analysis dictionary and rows of Ω constitutes analysis atoms
- Cosparsity: number of zeros in the vector Ωx
- Problem: Need to recover x from y

 $\mathbf{y} = \mathbf{x} + \mathbf{e}$ , where,  $\mathbf{x}$  is a cosparse analysis signal

- Performance guarantee of the thresholding algorithm for pursuit problem in the presence of noise
- Pursuit problem

$$\{\hat{\mathbf{x}}, \hat{\Lambda}\} = \arg \min_{\mathbf{x}, \Lambda} ||\mathbf{x} - \mathbf{y}||_2$$
  
 $\Omega_{\Lambda} \mathbf{x} = 0 \text{ and } \operatorname{Rank}(\Omega_{\Lambda}) = d - r$ 

- Algorithm computes Ωy and chooses the smallest entries as the estimated cosupport
- Two significant properties of Ω
  - Degree of linear dependencies between sets of rows in Ω: cosparsity level
  - Restricted orthogonal projection property: level of independence between such dependent sets and other rows in  $\Omega$