Structured Sparse Signal Recovery Algorithm for Finite Alphabet Constellation Symbol Decoding in Communication Systems

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Ashok Bandi (SPC Lab, Dept.ECE, IISc) Structured Sparse Signal Recovery Algorithm

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- Symbol Based Modulation (SBM) and Index Based Modulation (IBM)
 - System Model
 - Structured Sparsity in SBS/IBS
 - Problem formulation to leverage the structure
 - Proposed IESR SSR algorithm for SBS/IBS
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Introduction

General communication system can be represented as

	$\mathbf{y} = \mathbf{\Phi}\mathbf{x} + \mathbf{w},$	(1)
where	$\mathbf{y} \in \mathbb{C}^{M imes 1}$ is the observation vector,	
	$\Phi \in \mathbb{C}^{M\!\!\times\!\!N}$ is the measurement matrix,	
	$\mathbf{x} \in \mathbb{C}^{\mathit{N} imes 1}$ is the unknown vector,	
	$\mathbf{w} \sim \mathcal{N}(0, \sigma^2 \mathbf{I}_N)$ is the AWGN noise vector	

In most of the applications, entries of x come from a finite alphabet set or constellation like *M-PSK*, *M-QAM* etc. In this work, we are interested in recovering such x in the following cases.

- Symbol Based Modulation Schemes (SBM)
 - MIMO
 - GSM
- Index Based Modulation Schemes (IBM)
 - GSSK-MU-MIMO
 - MBM
 - GSSK-MBM

SBM and/or IBM

- In SBM information is conveyed through a symbol from a known finite alphabet set like BPSK, QAM, etc.
- In IBM, unlike SBM, information is conveyed through antenna indices (i.e., one of the possible channel states) like Space shift keying (SSK) modulation.
- In IBM, Symbol decoding can be interpreted as decoding a symbol from {0,1} constellation, and decoded symbol vector is mapped to get actual binary data. Here 0 or 1 indicates the usage of that particular channel realization for transmission.
- Advantages of IBM:
 - Spectral efficiency
 - power efficiency
 - improvement in performance
- Disadvantages of IBM:
 - Increase in number of antennas for higher data rate and independent channel states.
- The combination of SBM and IBM, like GSM, offers advantages of both techniques minimizes the impact of disadvantages.

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MIMO System model



Figure : MxN MIMO system

In all the subsequent slides

- $\Phi \in \mathbb{C}^{M \times N}$ represents channel matrix between transmitter and receiver.
- x = x_i x_N
 is unknown transmitted vector with entries x_is coming from known finite length alphabet A.
 y ∈ C^{Mx1} is the received vector.

MIMO Problem Formulation

- Let A ≜ {a₁,..., a_L} be a known finite alphabet set of length L and ith entry of x i.e., x_i ∈ A.
- Now x can be written as $\mathbf{x} = \mathbf{G}\mathbf{a}$, where $\mathbf{a} \triangleq \begin{pmatrix} a_1 \\ \vdots \\ a_L \end{pmatrix}$ and $\mathbf{G} \in \{0, 1\}^{N \times L}$ is unknown binary matrix
- Let $\mathbf{g}_{i} \in \{0, 1\}^{1 \times L}$ is *ith* row of \mathbf{G} , and $x_{i} = \mathbf{g}_{i}\mathbf{a}$. Then \mathbf{x} can be written as $\mathbf{x} = (I_{N \times N} \otimes \mathbf{a}^{T}) \begin{pmatrix} \mathbf{g}_{1}^{T} \\ \vdots \\ \mathbf{g}_{N}^{T} \end{pmatrix}$
- An element x_i in x represents a structured sparse vector g_i in the transformed domain with structure being one non-zero element in g_i

• Let
$$\mathbf{B} = I_{N \times N} \otimes \mathbf{a}^{T}$$
 with size $N \times NL$, and $\mathbf{g} = \begin{pmatrix} \mathbf{g_{1}}^{T} \\ \vdots \\ \mathbf{g_{N}}^{T} \end{pmatrix}$, then (1) can be written as $\mathbf{y} = \Psi \mathbf{g} + \mathbf{w}$, where $\Psi = \Phi \mathbf{B}$

Breakthrough

Problem of recovering a non-sparse complex valued vector \boldsymbol{x} becomes the problem of recovering structured binary sparse block vector \boldsymbol{g} with structure being one active element in each block i.e. \boldsymbol{g}_i

 $\bullet\,$ The problem of recovering g in MIMO case can be formulated as follows

$$\begin{split} \min_{\mathbf{g}} & f_1(\mathbf{g}) \triangleq \frac{\|\mathbf{y} - \mathbf{\Psi}\mathbf{g}\|_2^2}{2\sigma^2} \\ \text{bject to} \\ C_1 : & g_{ij} \in \{0, 1\}, \ i = 1, \dots, N, \ j = 1, \dots, L \\ C_2 : & \sum_{j=1}^L g_{ij} = 1, \ i = 1, \dots, N \\ C_3 : & \sum_{i=1}^N \sum_{j=1}^L g_{ij} = N \end{split}$$

$$(2)$$

• The problem in (2) is combinatorial in nature, hence difficult to solve directly. Equivalent convex problem with linear constraints is as follows.

$$\begin{split} \min_{\mathbf{g}} f(\mathbf{g}) &\triangleq \frac{\|\mathbf{y} - \mathbf{\psi}\mathbf{g}\|_{2}^{2}}{2\sigma^{2}} + \lambda \left(\sum_{i=1}^{N} \sum_{j=1}^{L} g_{ij} - N\right)^{2} + \mu \sum_{i=1}^{N} \left(\sum_{j=1}^{L} g_{ij} - 1\right)^{2} \\ \text{subject to } C1: 0 \leq g_{ij} \leq 1, \forall i = 1, \dots, N, \ j = 1, \dots, L \end{split}$$
(3)

• $f(\mathbf{g})$ in (3) is convex in \mathbf{g} and can be solved using CVX

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MIMO Simulation results



Advantages

- Decoding of binary vector gives improvement in bit error rate over regular SBM schemes.
- Dimension of constellation increases with increase in alphabet size and number transmit antennas. Hence improvement in performance.

Disadvantage

• Increase in dimension of the vector with alphabet size and number of antennas.

- Problem of recovering complex valued vector, whose elements come from a known finite length alphabet, can be modeled as problem of inclusion-exclusion sparse recovery problem (an active element precludes the other entries being active in each block, we refer this kind of structure as inclusion-exclusion sparsity (IES)).
- Simulation results show that in a *MxN* MIMO system, the transmitter vector of length *N* can be recovered successfully using *M* < *N* receive antennas. This is against the existing fact that in a *MxN* MIMO system *M* should be ≥ *N* for successful decoding.
- By exploiting the structure in the signal, we can recover k sparse signal with M < k measurements in single measurement vector case.

Generalized Spatial Modulation (GSM)

Problem formulation

- In GSM, only a subset of antennas are active at a given time. In other words, only a subset of entries are non-zero in the transmitted vector **x**.
- In GSM, information is conveyed through active antenna indices and modulation symbols.
- Consider a GSM system with N transmit antennas and at a given time only N_a antennas are active, and modulation symbols from A.
- An element x_i in x represents a structured sparse vector g_i in the transformed domain. Since only N_a entries are non-zero in x, so the number of active blocks in g i.e. N_a.
- The problem of recovering **g** in GSM case can be formulated as follows

$$\min_{\mathbf{g}} \qquad f(\mathbf{g}) \triangleq \frac{\|\mathbf{y} - \mathbf{\Psi}\mathbf{g}\|_2^2}{2\sigma^2} \tag{4}$$

subject to

$$C_1: \qquad g_{ij} \in \{0, 1\}, \ i = 1, \dots, N, \ j = 1, \dots, L$$

$$C_2: \qquad \sum_{j=1}^{L} g_{ij} \in \{0, 1\}, \ i = 1, \dots, N$$

$$C_3: \qquad \sum_{i=1}^{N} \sum_{j=1}^{L} g_{ij} = N_a$$

- Constraint C2 ensures the sparsity within the blocks and C3 ensures the sparsity of overall vector g.
- The convex problem with combinatorial constraints in (4) can be converted to non-convex problem with linear constraints as follows

$$\min_{\mathbf{x}} \qquad f(\mathbf{g}) \triangleq \underbrace{\frac{\|\mathbf{y} - \mathbf{\Psi}\mathbf{g}\|_{2}^{2}}{2\sigma^{2}}}_{f_{1}(\mathbf{g})} + \lambda \underbrace{\left(\sum_{i=1}^{N} \sum_{j=1}^{L} g_{ij} - N_{j}\right)^{2}}_{f_{2}(\mathbf{g})} - \mu \underbrace{\sum_{i=1}^{N} \left(\sum_{j=1}^{L} g_{ij}\right) \left(\sum_{j=1}^{L} g_{ij} - 1\right)}_{f_{3}(\mathbf{g})} \tag{5}$$

subject to

$$\begin{array}{ll} {\rm C1:} & 0 \leq g_{ij} \leq 1, \forall \; i=1,\ldots,N, \; j=1,\ldots,L \\ {\rm C_2:} & \sum_{j=1}^L g_{ij} \leq 1, \; i=1,\ldots,N \end{array}$$

- Function $f(\mathbf{g})$ in (5) is difference of convex functions, so the convex-concave procedure (CCP) can be applied.
- CCP is a majorization-minimization procedure, where the concave part is replaced with affine upper bound at current iterate and minimizes the surrogate function.
- The optimization problem at \mathbf{g}^k is as following

$$\min_{\mathbf{x}} \qquad f(\mathbf{g}) \triangleq \underbrace{\frac{\|\mathbf{y} - \mathbf{\Psi}\mathbf{g}\|_{2}^{2}}{2\sigma^{2}}}_{f_{1}(\mathbf{g})} + \lambda \underbrace{\left(\sum_{i=1}^{N} \sum_{j=1}^{L} g_{ij} - N_{a}\right)^{2}}_{f_{2}(\mathbf{g})} - \mu \nabla f_{3}(\mathbf{g}^{\mathbf{k}})^{T} \mathbf{g}$$
(6)

subject to

 $\mathbf{C1:} \ 0 \leq g_{ij} \leq 1, \ \mathbf{C2:} \sum_{i=1}^{L} g_{ij} \leq 1, \ \forall i = 1, \dots, N, j = 1, \dots, L$ Ashok Bandi (SPC Lab, Dept.ECE, IISc) Structured Sparse Signal Recovery Algorithm

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GSM Simulation Results



Figure : NMSE of the proposed algorithm (a) versus M and (b) versus SNR compared against popular LS and SSR algorithms, with N = 20, $N_a = 8$, and L = 16

GSSK-MU-MIMO

Problem formulation

• Consider a uplink MU-MIMO scenario with N users. Assume each user is equipped with L antennas and communicates with base station (BS) using GSSK modulation with $K \leq L$ antennas. In other words each user communicate with BS by transmitting tones through a subset of $K \leq L$ antennas. And at any time only $N_a \leq N$ users allowed to communicate with BS

$$\min_{\mathbf{x}} \qquad f(\mathbf{x}) \triangleq \underbrace{\frac{\|\mathbf{y} - \mathbf{\Phi}\mathbf{x}\|_{2}^{2}}{2\sigma^{2}}}_{f_{1}(\mathbf{x})} + \lambda \underbrace{\left(\sum_{i=1}^{N} \sum_{j=1}^{L} x_{ij} - N_{a}K\right)^{2}}_{f_{2}(\mathbf{x})} - \mu \underbrace{\sum_{i=1}^{N} \left(\sum_{j=1}^{L} x_{ij}\right) \left(\sum_{j=1}^{L} x_{ij} - K\right)}_{f_{3}(\mathbf{x})}$$
(7)

subject to

C1:
$$0 \le x_{ij} \le 1, \forall i = 1, ..., N, j = 1, ..., L$$

C2: $\sum_{j=1}^{L} x_{ij} \le k, i = 1, ..., N$

- Here Φ is channel matrix between all the users and BS, x concatenated transmitted vector from all the users and y is received vector at the BS.
- Above problem, (7), is in the form as (5) hence CCP can be applied.

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GSSK-MU-MIMO

Simulation results



Figure : (a) SRR and (b) NMSE of the proposed algorithm for the recovery of inclusion-exclusion sparse vectors compared against popular SSR algorithms, with N = 16, $N_a = 8$, L = 16, k = 6, and SNR= 40 dB.

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- Binary block sparse recovery vector can also be modeled as IES recovery problem.
- Consider a block sparse vector x with N blocks and each block of length L. Assume only N_a blocks are active. Then x can be recovered by solving following optimization problem.

$$\min_{\mathbf{x}} \qquad f(\mathbf{x}) \triangleq \underbrace{\frac{\|\mathbf{y} - \mathbf{\Phi}\mathbf{x}\|_{2}^{2}}{2\sigma^{2}}}_{f_{1}(\mathbf{x})} + \lambda \underbrace{\left(\sum_{i=1}^{N} \sum_{j=1}^{L} x_{ij} - N_{a}L\right)^{2}}_{f_{2}(\mathbf{x})} - \mu \underbrace{\sum_{i=1}^{N} \left(\sum_{j=1}^{L} x_{ij}\right) \left(\sum_{j=1}^{L} x_{ij} - L\right)}_{f_{3}(\mathbf{x})}$$
(8)

subject to

$$\begin{array}{lll} C1: & 0 \leq x_{ij} \leq 1, \forall \; i=1,\ldots,N, \; j=1,\ldots,L \\ C_2: & \sum_{j=1}^{L} x_{ij} \leq L, \; i=1,\ldots,N \end{array}$$

• The problem in (8) is in the same form as in (5), hence CCP can be applied.

Block Sparse Recovery

Simulation results



Figure : (a) SRR and (b) NMSE of the proposed algorithm compared against popular SSR algorithms in the block-sparse setting, with N = 24, $N_a = 12$, L = 8, and k = 8 and SNR= 30 dB.

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Media Based Modulation

- Varying the end to end channel based on the input is called Media Based Modulation (MBM).
- Carrier is modulated after leaving the transmitter by changing RF properties of the medium.
- All others traditional modulations are referred as Source Based Modulations (SBM).
- Small perturbation near the tx in a rich scattering environment results an independent end-to-end channel. RF mirrors are used for creating perturbations.



• If r_s bits are used for SBM and r_m bit for MBM, total $r_s + r_m$ can be transmitted by combining SBM and MBM, and receiver will receive one of the points from constellation of $2^{(r_s+r_m)}$ points.

Advantages of MBM

- Increasing the spectral efficiency without increasing energy unlike SBM, where increasing r_s results exponential increase in energy.
- Deep fades do not have persisting effect because of Constellation diversity. As constellation size increases, this converts static multi-path fading channel into non-fading AWGN.
- In a 1xD SIMO-MBM system received vector spans in D receive dimension unlike SIMO-SBM which spans in single complex dimension, which is equivalent to SIMO-SBM with D times bandwidth.
- Possibility of choosing subset of channel similar to multi user diversity gain in scheduling.

Disadvantages of MBM

- Random arrangements of constellation points and all points are used with equal probability. While in SBM constellation can be used with non uniform probability to realize shaping gain.
- MBM is Linear Time variant, can trouble the traditional channel equalization techniques
- Signal in single dimension at the input is spread across the multiple dimension at output.

Flavors of MBM:

- MIMO-MBM: MBM discussed in the above single antenna case can be extended to MIMO. This is referred as MIMO-MBM.
- GSM-MIMO: MBM combined with multiple antenna case using GSM is referred as GSM-MBM.
- GSSK-MIMO: MBM combined with multiple antenna case using GSSK is referred as GSSK-MBM.

Data Decoding in GSSK-MBM:

- Consider a BS with M received antennas and a user with N antennas, each equipped with N_{rf} mirrors. Also assume user wants communicate with BS using GSSK modulation using $N_a \leq N$ antennas
- Now the decoding at BS can be formulated as follows

$$\min_{\mathbf{x}} \qquad f(\mathbf{g}) \triangleq \underbrace{\frac{\|\mathbf{y} - \Phi \mathbf{x}\|_2^2}{2\sigma^2}}_{f_1(\mathbf{x})} + \lambda \underbrace{\left(\sum_{i=1}^N \sum_{j=1}^L x_{ij} - N_a\right)^2}_{f_2(\mathbf{x})} - \mu \underbrace{\sum_{i=1}^N \left(\sum_{j=1}^L x_{ij}\right) \left(\sum_{j=1}^L x_{ij} - 1\right)}_{f_3(\mathbf{x})} \tag{9}$$

subject to

C1:
$$0 \le x_{ij} \le 1, \forall i = 1, ..., N, j = 1, ..., L$$

C2: $\sum_{i=1}^{L} x_{ij} \le 1, i = 1, ..., N$

- Here Φ is concatenated channel matrix between BS and all possible mirror patterns at all antennas. $L = 2^{N_{rf}}$ is number of possible mirror activation patterns at each antenna.
- The problem in (9) is in the same form as in (5), hence CCP can be applied

Simulation results: GSSK-MBM



Figure : SER of the proposed algorithm for decoding data with MBM, compared against popular SSR algorithms, with N = 10, $N_a = 8$, $N_{rf} = 4$, and L = 16.

- Coming up with an efficient algorithm instead of using CVX.
- Bounds or exact expression for the number of measurements needed given the sparsity and length of the vector
- Extending this work to recover the vector when maximum number of non-zeros is known instead of exact number of non-zeros.