# Stochastic Divergences and Applications to Multi-Dimensional Goodness-of-Fit Tests for Spectrum Sensing

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Presented by Sanjeev on 6th Oct '12 Divergences and MDGoFT

## Introduction to Stochastic Divergences

- ► It all started with Measure theory (Hellinger's Integral) → Statistics (ISI) → Information Theory!
- Roughly, a Stochastic Divergence measures the similarity between two discrete/continuous probability distributions
- Earliest examples include Hellinger's distance, Mahalanobis distance, Bhattacharyya distance, Kullback-Leibler divergence etc.



## **Connection to Information Theory (1/4)**

- Logarithm as a measure of information [Shannon1948] (restricted scope).
- $\mathcal{P} \triangleq \left\{ P = (p_1, p_2, \cdots, p_n) : \sum_{i=1}^n p_i = 1, p_i > 0, i = 1, 2, \cdots, n \right\} \\ \mathcal{Q} \triangleq \left\{ Q = (q_1, q_2, \cdots, q_n) : \sum_{i=1}^n q_i = 1, q_i \ge 0, i = 1, 2, \cdots, n \right\}$
- ► A measure of information,  $H(P) = -\sum_{i=1}^{n} p_i \log p_i$  (following four postulates [Ash]).
- "Conditional entropy",  $H(P||Q) = -\sum_{i=1}^{n} p_i \log q_i$
- H(P) satisfies additivity, recursivity and sum representations



# **Connection to Information Theory (2/4)**

- In other problems, other functions serve better as measures of information! [Renyi1961]
- ► Renyi's entropy of order  $\alpha$ :  $H_{\alpha}(P) = (1 - \alpha)^{-1} \log \left( \sum_{i=1}^{n} p_{i}^{\alpha} \right), \alpha > 0, \alpha \neq 1$
- $\bullet \ \lim_{\alpha \to 1} H_{\alpha}(P) = H(P)$
- ► H<sub>α</sub>(P) satisfies additivity, but not recursivity and sum representations
- Renyi's entropy finds its use in numerous applications as well!



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## **Connection to Information Theory (3/4)**

 [AczelDaroczy1963], [Varma1966], [Kapur1967], [HavrdaCharvat1967], [BelisGuiasu1968], [Rathie1970], [Arimoto1971], [SharmaMittal1975], [Taneja1975], [Picard1979], [Ferreri1980], [Sant'annaTaneja1983], ...



# **Connection to Information Theory (4/4)**

- It can be shown that H(P) ≤ H(P||Q) (Shannon-Gibbs inequality)
- Consider  $D(P||Q) \triangleq H(P||Q) H(P)$
- ► Obviously, D(P||Q) > 0, with equality iff P = Q. Visualized as a distance metric. Not an actual metric, since it does not satisfy the symmetric property and the triangle inequality
- D(P||Q) is called as the Kullback-Leibler divergence [KullbackLeibler1951]
- ► Generalizations on entropy → Generalizations on divergences!



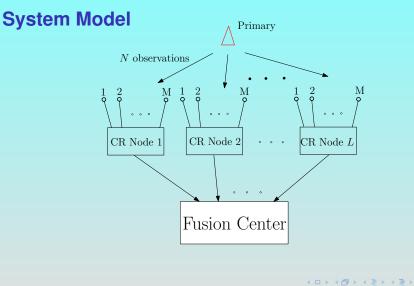
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## An Important Generalization [Csiszar1967]

- ►  $\phi$  (or f-) divergences  $\phi(P||Q) = \int_{\mathcal{X}} Q(x)\phi\left(\frac{P(x)}{Q(x)}\right) d\mu(x)$ , with  $\phi$  being a real valued convex function on  $(0, \infty)$ .
- Special cases include the KL, variational, χ<sup>2</sup>, Matusita, Balakrishnan and Sanghvi, Havrda and Charvat etc.
- Notation :  $\delta(A, B)$  represents a stochastic divergence







### **Test I - Interpoint Distances Theorem**

#### Theorem (MaaPearlBartoszynski1996)

Let  $X_1, X_2, \dots, X_N$  be *M*-dimensional observations from a known distribution  $\mathcal{F}$ . Let  $Y_1$  and  $Y_2$  be the samples from the hypothesized distribution  $\mathcal{G}$ . Let  $\delta(\cdot, \cdot)$  be an appropriately chosen stochastic distance function. Then,  $\mathcal{F} = \mathcal{G}$  if and only if the distribution of  $\delta(X_i, X_j)$  and  $\delta(X_i, Y_1)$  (and  $\delta(X_j, Y_1)$ ) are same and equal to  $\delta(Y_1, Y_2)$ , for all  $1 \leq i, j \leq N, i \neq j$ .



# **Test I - Intuition**

► Triangle formed between any two points X<sub>i</sub>, X<sub>j</sub> ~ F, and Y ~ G. Null hypothesis is true if and only if the three sides of the triangle have the same distribution (which was specified earlier)

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## **Test I - Construction**

Define p<sub>1</sub>(·, ·), p<sub>2</sub>(·, ·) and p<sub>3</sub>(·, ·) as the probabilities associated with Y ∼ G falling in the regions 1, 2 and 3 respectively

• 
$$U_k \triangleq \frac{1}{\binom{N}{2}} \sum_{i < j} p_k(X_i, X_j), k = 1, 2, 3, \text{ with } 1 \le i, j \le N$$

Lemma (BartoszynskiPearlLawrence1997)

If  $Z_k \triangleq \frac{U_k - \frac{1}{3}}{\sqrt{\operatorname{var}(U_k | H_0)}}$ , and  $\rho_{k,l} \triangleq \operatorname{cov}(Z_k, Z_l | H_0)$  for  $k, l \in \{1, 2, 3\}$ and  $k \neq l$ , then  $Q \triangleq \frac{Z_k^2 + Z_l^2 - 2\rho_{k,l} Z_k Z_l}{1 - \rho_{k,l}^2} \sim \chi_2^2$ , as  $N \to \infty$ 



# **Test I - Observations and Problems**

- In the present form, the probabilities p<sub>1</sub>(·, ·), p<sub>2</sub>(·, ·) and p<sub>3</sub>(·, ·) have to be estimated for a particular choice of δ(·, ·)
- The asymptotic result is very tight for N ≥ 10, for the M-antenna, N-observations SS problem
- For a range of alternate hypothesis, this test performs better than some of the sphericity tests
- ► Q statistic can be constructed from any Z<sub>k</sub>, Z<sub>l</sub> pair. "Better" combining of Z<sub>1</sub>, Z<sub>2</sub> and Z<sub>3</sub>?
- What is the optimum choice of  $\delta(\cdot, \cdot)$ ?



# Test II - Model

- ► Let W<sub>1</sub>, W<sub>2</sub>, · · · , W<sub>L</sub> be the matrices of observations from the L sensors
- Assumption : Physical layer fusion at the FC, without noise and fading. Idea still holds without this assumption
- If noise at each antenna is complex Gaussian with known variance, then each W<sub>I</sub> ~ CW(N, Σ).
- Statistic at the FC is  $\widehat{\Sigma} \triangleq \frac{1}{L} \sum_{l=1}^{L} \mathbf{W}_{l}$



Test II -  $< h, \phi >$  distances [Salicru et al. 1994]

►  $\delta_{\phi}^{h}(X, Y) \triangleq h\left\{\int_{\mathbb{H}} \phi\left(\frac{f_{X}(\mathbf{Z}; \theta_{1})}{f_{Y}(\mathbf{Z}; \theta_{2})}\right) f_{Y}(\mathbf{Z}; \theta_{2}) d\mathbf{Z}\right\}$ , where  $\mathbb{H}$  is the space of all Hermitian PD matrices,

 $h: (0, \infty) \to (0, \infty)$  is a strictly increasing function with h(0) = 0, and  $\phi: (0, \infty) \to (0, \infty)$  is a convex function

► The differential element  $d\mathbf{Z} = dZ_{11}dZ_{22}\cdots dZ_{MM}\prod_{i<i}^{M} dReZ_{ij}dImZ_{ij}$ 

• Let 
$$d^h_{\phi}(X, Y) \triangleq rac{\delta^h_{\phi}(X, Y) + \delta^h_{\phi}(Y, X)}{2}$$

 Many divergence measures (including *f*-divergences) are special cases of δ<sup>h</sup><sub>φ</sub>



#### **Test II - Main Theorem**

Since the noise PDF is known, let  $\widehat{\Sigma_0} \triangleq \widehat{\Sigma} | \mathcal{H}_0$ .

# **Theorem (Salicru et al. 1994)** Under some regularity conditions, if $\widehat{\Sigma_0} = \widehat{\Sigma}$ then $\frac{Ld_{\phi}^h(\widehat{\Sigma},\widehat{\Sigma_0})}{h'(0)\phi''(1)} \xrightarrow[L \to \infty]{d.} \chi^2_{M^2}$



## **Test II - Observations and Problems**

- ► Closed form to d<sup>h</sup><sub>φ</sub>(·, ·) for a suitable choice of δ<sup>h</sup><sub>φ</sub>(·, ·)
- The asymptotic result is very tight for L ≥ 10, for the M-antenna, N-observations, L sensors SS problem
- For a range of alternate hypothesis, this test performs better than some of the sphericity tests
- Suitable choice of  $\delta_{\phi}^{h}(\cdot, \cdot)$ ?



# Conclusions

- Studied a family of stochastic divergences
- Test I based on interpoint distances; suitable for M-antenna CR system with N-observations
- Test II based on < h, \u03c6 > distances; suitable for CR system having L sensors with M-antenna each with N-observations
- Comparison to Sphericity tests

