

Power Controlled Feedback and Training in MIMO Systems

T. Ganesan

gana@ieee.org

SPC Lab, Dept. of ECE

Jul 16th, 2011

Outline

- 1 Introduction
 - Preliminaries
 - DMT
- 2 DMT with Partial CSIT and Full CSIR
 - DMT with CSIR
 - DMT with CSIT and CSIR
- 3 DMT with Partial CSIT and Partial CSIR
 - Constant Power Training
 - Adaptive Power Training
 - DMT - Partial CSIT and CSIR

- 1 Introduction
 - Preliminaries
 - DMT
- 2 DMT with Partial CSIT and Full CSIR
 - DMT with CSIR
 - DMT with CSIT and CSIR
- 3 DMT with Partial CSIT and Partial CSIR
 - Constant Power Training
 - Adaptive Power Training
 - DMT - Partial CSIT and CSIR
- 4 References

Definitions

- Diversity of the MIMO wireless link is defined as [1]

$$d = - \lim_{SNR \rightarrow \infty} \frac{\log P_{out}}{\log SNR}$$

- Multiplexing gain is defined as [1] $r = \lim_{SNR \rightarrow \infty} \frac{R}{\log SNR}$

- CSIR - Perfect Channel state knowledge at the Rx.

- CSIT - Perfect Channel state knowledge at the Tx.

- For a χ^2 random variable H , with $2k$ degrees of freedom

- $f_H(h) = \frac{1}{(k-1)!} h^{k-1} e^{-h}$

- $\Pr(h \leq \epsilon) \doteq \epsilon^k$

Definitions(2)

- Given the $N_r \times N_t$ MIMO channel matrix \mathbf{H} ($N_r \geq N_t$) with IID Gaussian entries, the joint PDF of the ordered eigenvalues of $\mathbf{H}^H \mathbf{H}$, $\mu_1 \leq \mu_2 \dots \mu_{N_t}$ is given by [1]

$$f(\mu_1, \mu_2, \dots, \mu_{N_t}) = K_{N_r, N_t}^{-1} \prod_{i=1}^{N_t} \mu_i^{N_r - N_t} \prod_{i < j} (\mu_i - \mu_j)^2 e^{-\sum_i \mu_i},$$

where K_{N_r, N_t}^{-1} is a normalization constant.

- Let $\mu_i = SNR^{-\alpha_i}$. The joint PDF $f(\alpha_1, \alpha_2, \dots, \alpha_{N_t})$ is given by

$$K_{N_r, N_t}^{-1} (\log SNR)^{N_t} \prod_{i=1}^{N_t} SNR^{(N_r - N_t + 1)\alpha_i} \prod_{i < j} (SNR^{-\alpha_i} - SNR^{-\alpha_j})^2 e^{-\sum_i SNR^{-\alpha_i}}$$

Related Literature

- 1 Fundamental DMT with full CSIR - L. Zheng and D. Tse 2003 [1].
- 2 DMT with Partial CSIT (Noiseless feedback to Tx) - T.T.Kim and M. Skoglund 2007 [2].
- 3 Exponential Diversity using Spatio-temporal power allocation - V. Sharma et al 2008 [3].
- 4 Diversity Gains of Power Control with Noisy CSIT - T.T.Kim and G. Caire 2009 [4].
- 5 Power Controlled Feedback and Training - V. Aggarwal and A. Sabharwal 2010 [5].

SISO - Diversity Trade-off

- Consider a SISO link with Tx power constraint P and Rayleigh fading channel.
- It is known that $P_{out} = \Pr(|h|^2 < \frac{SNR^r - 1}{SNR}) \doteq \frac{1}{SNR^{1-r}}$.
 - Diversity order $d = 1 - r$, where r is the multiplexing gain [6].
 - If SNR^α is used as Tx power, then $d = (\alpha - r)$.
- The average Tx power constraint is achieved by using
 - constant Tx power (independent of channel gain).
 - Adapt the Tx power for channel gain (using knowledge from FB path)
 - That is, $\int_{h_0}^{\infty} P(h)dh \leq P$, where h is Rayleigh distributed
- **Note:** Tx power changes the diversity even in SISO channel!

SISO - Average Power Control

- For channel adaptive Tx power control, we need

$$\int_{h_0}^{\infty} P(h)dh \leq P_{avg} \quad [5]$$

- e.g., $P(h) = \begin{cases} SNR^2, h < \frac{1}{SNR} \\ SNR, \text{ otherwise} \end{cases}$

- $P_{avg} = SNR^2 \Pr(h < \frac{1}{SNR}) + SNR[1 - \Pr(h < \frac{1}{SNR})] \leq SNR$

- Thus, with even 1 bit of feedback about h , one can gain improved diversity from 1 to 2.
- That is, one can divide the range of h into 2^B regions and select $P(h)$ such that, average Tx power control is satisfied.

MISO - Diversity Trade-off

- Consider a MISO link with Tx power constraint P_{avg} and Rayleigh fading channel.
- It is known that $P_{out} \doteq \frac{1}{SNR^{N_t}}$.
 - maximum diversity order is $d = N_t$ and DMT trade-off is $N_t(1 - r)$ [6].
 - If SNR^α is used as Tx power, then $d = N_t(\alpha - r)$.
 - When the CSIT error variance $\sigma_e^2 = SNR^{-d_e}$, then it is shown that $d = N_t(1 + N_t d_e - r)$ [4].

MIMO - Diversity Trade-off

- Consider a MIMO link with Tx power constraint P_{avg} and Rayleigh fading channel.
- It is known that $P_{out} \doteq \frac{1}{SNR^{N_t N_r}}$.
 - Diversity order $d = N_t N_r$ and multiplexing trade-off is $(N_t - r)(N_r - r)[6]$.

- 1 Introduction
 - Preliminaries
 - DMT
- 2 DMT with Partial CSIT and Full CSIR**
 - DMT with CSIR
 - DMT with CSIT and CSIR
- 3 DMT with Partial CSIT and Partial CSIR
 - Constant Power Training
 - Adaptive Power Training
 - DMT - Partial CSIT and CSIR
- 4 References

DMT with full CSIR

- When CSIR is known [2],
 - $P_{out} = \Pr \left(\log \det \left[\mathbf{I}_{N_r} + \frac{SNR}{N_t} \mathbf{H}\mathbf{H}^H \right] < r \log SNR \right)$
 - $P_{out} = \Pr \left(\sum_{i=1}^{\min(N_r, N_t)} \log(1 + \frac{SNR}{N_t} \lambda_i) < \log SNR^r \right)$
- Let $\lambda_j = SNR^{\alpha_j}$. Then we get
 - $P_{out} \doteq \Pr \left(\prod_{i=1}^{\min(N_r, N_t)} SNR^{(1-\alpha_j)^+} < SNR^r \right)$
- Now, using the distribution of singular values $\mathbf{H}\mathbf{H}^H$,
 - $P_{out} \doteq SNR^{-D(r,p)}$, $D(r,p) =$
 $\inf_{\alpha \in \mathcal{A}} \sum_{i=1}^{\min(N_r, N_t)} (2i - 1 + \max(N_r, N_t) - \min(N_r, N_t)) \alpha_i$
 - where $\mathcal{A} = \{ \alpha_i : \alpha_i > 0, \sum_i (p - \alpha_i)^+ < r \}$
- This coincides with Zheng-Tse bound when $p = 1$ [1].

CSIR vs CSIT

- Zheng and Tse [1] published the well known Diversity and Multiplexing Trade-off (DMT) when CSIR is known.
 - Diversity order $d = N_t N_r$ and multiplexing trade-off is $(N_t - r)(N_r - r)$.
- However, if the Tx has CSIT, then use $\mathbf{P} = \mathbf{H}^\dagger$ as the precoding matrix. That is,

$$\mathbf{Y} = \mathbf{H}\mathbf{P}\mathbf{X} + \mathbf{N} = \mathbf{X} + \mathbf{N}$$

- We can achieve infinite order diversity!
 - Tx power control is crucial.
- **Note:** Power control over channel instantiations is crucial.

DMT with Perfect Feedback

- Suppose, if the Rx with CSIR feeds back B bits via noiseless feedback channel, the maximum diversity achievable increase exponentially.
 - Using B bits of feedback, SISO link can achieve $K = 2^B$ diversity order.
- With K levels of feedback, the DMT is given by

$$d_K = D(r, 1 + d_{K-1}(r))$$
 - For $r = 0$, $d = (N_r N_t)^K$ and for $r = \min(N_r, N_t)$, $d = 0$.
- As $SNR \rightarrow \infty$ and $K \rightarrow \infty$, we get infinite diversity order!

DMT with Noisy Feedback

- In SISO, if the Rx with CSIR feeds back B bits via noisy feedback channel using constant Tx power, then the maximum diversity achievable doubles when compared to no CSIT case.
 - The worst case error event in the noisy feedback results in higher Tx power than required. Hence, limit the Tx power to SNR^2 always which results in the diversity limit of 2.
 - Average Tx power for $B = 2$ is,

$$(1 - SNR^{-1})[SNR(1 - p_1 - p_2 - p_3) + SNR^2(p_1 + p_2 + p_3)] + SNR^{-1}[SNR^2(1 - p_1 - p_2 - p_3) + p_1 SNR + p_2 SNR^2 + p_3 SNR^2] + \dots \approx SNR$$

- Similarly in MIMO, max. diversity gets limited to $2N_r N_t$.

Power Controlled CSI Feedback (SISO)

- The diversity order gets limited due to constant power used to send the feedback bits though they do not occur with equal probability.
 - That is, the probability of events $(1 - SNR^{-1}), SNR^{-1}, SNR^{-2}, SNR^{-3}$ are unequal.
 - Even if we use higher Tx power for occasional events, the average Tx power does not increase dramatically.

Power Controlled CSI Feedback (SISO)

- If we use exponential Tx power (SNR^β) for feedback of rare events, feedback bits are received with more reliability.
 - e.g., for $B=2$, Average Tx power for sending feedback is

$$SNR^0(1 - SNR^{-1}) + SNR^2SNR^{-1} + SNR^3SNR^{-2} + SNR^4SNR^{-3} \doteq SNR.$$
 - Diversity is limited by the dominant error event when 1 is transmitted and 2 is received.
 - Prob of rare error event is SNR^{-2} ; hence, diversity is limited to 3.

Power Controlled CSI Feedback (MIMO)

- Let $SNR^{q_1}, SNR^{q_2}, \dots, SNR^{q_K}$ are the various power levels used in the Tx.

- Using the MAP receiver, the feedback bits can be received

reliably. $\Pr(J_T = 0 | J_R = 1) = \Pr(\text{tr}(\mathbf{H}\mathbf{H}^H)SNR^{q_1} < SNR^{q_0+\epsilon})$

$$\doteq \Pr\left(\sum_{i=1}^{\min(N_r, N_t)} SNR^{q_1 - \alpha_i} < SNR^{q_0 + \epsilon}\right)$$

$$\doteq \Pr(SNR^{\max(q_1 - \min(\alpha_i), 0)} < SNR^{q_0 + \epsilon})$$

$$\doteq \Pr(\min(\alpha_i) > q_1 - q_0 - \epsilon) = SNR^{-N_r N_t (q_1 - q_0)}$$

Power Controlled CSI Feedback (MIMO)

- $\Pr(J_T = j | J_R = i) \doteq SNR^{-N_r N_t (q_i - q_j)}$
- The DMT for this case with K levels of feedback is given by

$$D(r, K) = \max_{q_j \leq 1 + D(r, j)} \min_{i=1, \dots, K-1} (N_r N_t ((q_i^+ - q_{i-1}^+) + D(r, i)))$$
- As $K \rightarrow \infty$, the maximum diversity order with power controlled feedback is given by $N_r N_t (N_r N_t + 2)$.

- 1 Introduction
 - Preliminaries
 - DMT
- 2 DMT with Partial CSIT and Full CSIR
 - DMT with CSIR
 - DMT with CSIT and CSIR
- 3 DMT with Partial CSIT and Partial CSIR**
 - Constant Power Training
 - Adaptive Power Training
 - DMT - Partial CSIT and CSIR
- 4 References

Channel Estimation - Constant Training Power

- In real scenarios, CSIR is obtained via training and channel estimation.
- MMSE channel estimates improve with SNR and length of training sequence.
 - $\hat{\mathbf{H}} = \mathbf{H} \frac{1}{1 + \frac{N_f}{N SNR}} + \text{noise}.$
 - The variance of the channel estimation error is $\doteq 1/SNR.$
- Let $|\hat{\mathbf{H}}|^2 = SNR^{-\hat{\alpha}} \Rightarrow |\tilde{\mathbf{H}}|^2 = |\mathbf{H} - \hat{\mathbf{H}}|^2 = SNR^{-1} SNR^{-\hat{\alpha}}$

Diversity - Constant Training Power

- The outage due to dominant error event is given by

$$\Pr \left(\log \left(1 + \frac{|\hat{\mathbf{H}}|^2 SNR^2}{1 + SNR^2 |\tilde{\mathbf{H}}|^2} \right) < r \log SNR, \right.$$

$$\log \left(1 + |\hat{\mathbf{H}}|^2 SNR^2 \right) \geq r \log SNR, \quad \left. \log \left(1 + |\hat{\mathbf{H}}|^2 SNR \right) < r \log SNR \right).$$

- $P_{out} \doteq \Pr((2 - \hat{\alpha} - (1 - \tilde{\alpha})^+)^+ < r, (2 - \hat{\alpha})^+ \geq r, (1 - \hat{\alpha})^+ < r)$
- This can be simplified to $P_{out} \geq SNR^{-(1-r)}$ (let $\hat{\alpha} = 1 - r + \delta$).
- Note: The above calculation assumes noise free feedback bits to Tx.

Diversity - Adaptive Training Power

- **Steps:** (1) Tx sends a training sequence, (2) Rx estimate channel $\hat{\mathbf{H}}_1$ and sends index J_1 to Tx. (3) Tx sends training again with power $P(J_T) = SNR^{1+i}$ followed by data with the same Tx power. The new channel estimate is $\hat{\mathbf{H}}_2$.

- The outage prob. is given by

$$\Pr \left(\log \det \left[\mathbf{I} + \frac{P(J_T)}{N_t} \frac{\hat{\mathbf{H}}_2 \mathbf{Q} \hat{\mathbf{H}}_2^H}{1 + \frac{SNR}{N_r N_t} \text{tr}(\hat{\mathbf{H}} \hat{\mathbf{H}}^H)} \right] < R \right)$$

- e.g., for $B = 2$, the outage events are

$$\hat{\mathcal{O}}_i = \left\{ \hat{\mathbf{H}} : \log \left(1 + |\hat{\mathbf{H}}|^2 SNR^{1+i} \right) < R \right\} \text{ where } SNR^{1+i} \text{ is used for Tx if } \hat{\mathbf{H}} \in \hat{\mathcal{O}}_i.$$

DMT - Adaptive Training Power

- For e.g, Let $B = 2$ and an outage occurs when $J_T = 2$ and $J_R < 2$. That is, $P_{out} \doteq SNR^{-2}$.
- For $K > 1$ and $r < \min(N_r, N_t)$, the DMT that can be achieved with power controlled training is given by

$$D(r, K) = G(r, 1 + G(r, 1))$$
- The maximum diversity for $r = 0$ is $N_r N_t (N_r N_t + 1)$.

DMT - Partial CSIT and CSIR

- **Steps:** (1) Tx uses SNR to send training, (2) Rx estimates the channel $\hat{\mathbf{H}}_1$ and sends an index J_R using power controlled feedback, (3) Tx uses received index J_T to determine $P(J_T)$ for training as well as data. New channel estimate is $\hat{\mathbf{H}}_2$.
- An outage occurs when $\Pr \left(\log \det \left(\mathbf{I} + P(J_T) \hat{\mathbf{H}}_2 \hat{\mathbf{H}}_2^H \right) < R \right)$.
- For e.g., for $B = 1$, $\Pr(J_T = 0 | J_R = 1) \doteq SNR^{-N_r N_t (1+G(r,1))}$, $\Pr(J_T = 1 | J_R = 0) \doteq 0$ and $\Pr(J_R = 0 | J = 1) \doteq 0$, where J is 1 if $\log \det(\mathbf{I} + \hat{\mathbf{H}}_2 \hat{\mathbf{H}}_2^H P_0) < R$ and $\log \det(\mathbf{I} + \hat{\mathbf{H}}_2 \hat{\mathbf{H}}_2^H P_1) \geq R$.

DMT - Partial CSIT and CSIR

- Accounting for all possible values of J_R , J_T and J , the outage probability can be computed.
- The DMT can be shown to be $D(r, 2) = G(r, 1 + G(r, 1))$.
- That is, diversity order achievable with 1 bit of feedback when CSIR and CSIT are imperfect is same as the diversity order achievable with 1 bit of perfect feedback and perfect CSIR.

References



L. Zheng and D. N. C. Tse,

“Diversity and multiplexing : A fundamental tradeoff in multiple antenna channels,”

IEEE Transactions on Information Theory, vol. 49, no. 5, pp. 1073–1096, May 2003.



T. T. Kim and M. Skoglund,

“Diversity-multiplexing tradeoff in mimo channels with partial csit,”

IEEE Transactions on Information Theory, vol. 53, no. 8, Aug 2007.



V. Sharma, K. Premkumar, and R. N. Swamy,

“Exponential diversity achieving spatio-temporal power allocation scheme for fading channels,”

IEEE Transactions on Information Theory, vol. 54, no. 1, pp. 188–208, Jan 2008.



T. T. Kim and G. Caire,

“Diversity gain of power control with noisy csit in mimo channels,”

IEEE Transactions on Information Theory, vol. 55, no. 4, pp. 1618–1626, Apr 2009.



V. Aggarwal and A. Sabharwal,

“Power controlled feedback and training for two-way mimo channels,”

IEEE Transactions on Information Theory, vol. 56, no. 7, pp. 3310–3331, Jul 2010.



D. Tse and P. Viswanath,

Fundamentals of Wireless Communication,

Cambridge University Press, first edition, 2005.