

# Lecture 11: Discrete Time Markov Chains

## 1 Introduction

We have seen that *iid* sequences are easiest discrete time processes. However, they don't capture correlation well. Hence, we look at the discrete time stochastic processes of the form

$$X_{n+1} = f(X_n, Z_{n+1}),$$

where  $\{Z_n : n \in \mathbb{N}\}$  is an iid sequence, independent of initial state  $X_0$ . If  $X_n \in E$  for all  $n \in \mathbb{N}_0$ , then  $E$  is called the **state space** of process  $X$ . We consider a countable state space, and if  $X_n = i \in \mathbb{E}$ , then we say that the process  $X$  is in state  $i$  at time  $n$ . For a countable set  $E$ , a stochastic process  $\{X_n \in E, n \in \mathbb{N}_0\}$  is called a **discrete time Markov chain (DTMC)** if for all positive integers  $n \in \mathbb{N}_0$  and all states  $i_0, i_1, \dots, i_{n-1}, i, j \in E$ , the process  $X$  satisfies the Markov property

$$P\{X_{n+1} = j | X_n = i, X_{n-1} = i_{n-1}, \dots, X_0 = i_0\} = P\{X_{n+1} = j | X_n = i\}.$$

### 1.1 Homogeneous Markov chain

If for each  $n \in \mathbb{N}_0$ , we have  $p_{ij}(n) \triangleq P\{X_{n+1} = j | X_n = i\} = p_{ij}$ . That is, when the transition probability does not depend on  $n$ , the DTMC is **homogeneous** and the matrix  $P = \{p_{ij} : i, j \in \mathbb{E}\}$  is called the **transition matrix**.

For all states  $i, j \in E$ , if a non-negative matrix  $A \in \mathbb{R}_+^{E \times E}$  has the following property

$$a_{ij} \geq 0, \quad \sum_{j \in E} a_{ij} \leq 1,$$

then it is called a **sub-stochastic** matrix. If the second property holds with equality, then it is called a **stochastic** matrix. If in addition,  $A^T$  is stochastic, then  $A$  is called **doubly stochastic**. Clearly, the transition matrix  $P$  is stochastic matrix.

### 1.2 Transition graph

A transition matrix  $P$  is sometimes represented by a directed graph  $G = (E, \{[i, j] \in E \times E : p_{ij} > 0\})$ . In addition, this graph has a weight  $p_{ij}$  on each edge  $e = [i, j]$ .

## 2 Chapman Kolmogorov equations

We can define  $n$ -step transition probabilities for  $i, j \in E$  and  $m, n \in \mathbb{N}$

$$p_{ij}^{(n)} \triangleq P\{X_{n+m} = j | X_m = i\}.$$

It follows from the Markov property and law of total probability that

$$P_{ij}^{(m+n)} = \sum_{k \in E} P_{ik}^{(m)} P_{kj}^{(n)}.$$

We can write this result compactly in terms of transition probability matrix  $P$  as  $P^{(n)} = P^n$ . Let  $\mathbf{v} \in \mathbb{R}_+^E$  is a probability vector such that

$$\mathbf{v}_n(i) = P\{X_n = i\}.$$

Then, we can write this vector  $\mathbf{v}_n$  in terms of initial probability vector  $\mathbf{v}_0$  and the transition matrix  $P$  as

$$\mathbf{v}_n = \mathbf{v}_0 P^n.$$

## 2.1 Strong Markov property (SMP)

Let  $T$  be an integer valued stopping time with respect to the stochastic process  $X$  such that  $P\{T < \infty\} = 1$ . Then for all  $i_0, \dots, i_{n-1}, \dots, i, j \in E$ , the process  $X$  satisfies the **strong Markov property** if

$$P\{X_{T+1} = j | X_T = i, \dots, X_0 = i_0\} = P\{X_{T+1} = j | X_T = i\}.$$

**Lemma 2.1.** *Markov chains satisfy the strong Markov property.*

*Proof.* Let  $X$  be a Markov chain and  $A = \{X_T = i, \dots, X_0 = i_0\}$ . Then, we have

$$P\{X_{T+1} = j | A\} = \frac{\sum_{n \in \mathbb{N}_0} P\{X_{T+1} = j, A, T = n\}}{P\{A\}} = \sum_{n \in \mathbb{N}_0} p_{ij} \frac{P(A, T = n)}{P(A)} = p_{ij}.$$

This equality follows from the fact that  $\{T = n\}$  is completely determined by  $\{X_0, \dots, X_n\}$  □

As an exercise, if we try to use the Markov property on arbitrary random variable  $T$ , the SMP may not hold. For example, define a non-stopping time  $T$  for  $j \in E$

$$T = \inf\{n \in \mathbb{N}_0 : X_{n+1} = j\}.$$

In this case, we have

$$P\{X_{T+1} = j | X_T = i, \dots, X_0 = i_0\} = 1\{p_{ij} > 0\} \neq P\{X_1 = j | X_0 = i\} = p_{ij}.$$

A useful application of the strong Markov property is as follows. Let  $i_0 \in E$  be a fixed state and  $\tau_0 = 0$ . Let  $\tau_n$  denote the stopping times at which the Markov chain visits  $i_0$  for the  $n$ th time. That is,

$$\tau_n = \inf\{n > \tau_{n-1} : X_n = i_0\}.$$

Then  $\{X_{\tau_n+m} : m \in \mathbb{N}_0\}$  is a stochastic replica of  $\{X_m : m \in \mathbb{N}_0\}$  with  $X_0 = i_0$  and can be studied as a regenerative process.

## 3 Communicating classes

State  $j \in E$  is said to be **accessible** from state  $i \in E$  if  $p_{ij}^{(n)} > 0$  for some  $n \in \mathbb{N}$ , and denoted by  $i \rightarrow j$ . If two states  $i, j \in E$  are accessible to each other, they are said to **communicate** with each other, denoted by  $i \leftrightarrow j$ . A set of states that communicate are called a **communicating class**.

**Proposition 3.1.** *Communication is an equivalence relation.*

*Proof.* Reflexivity and Symmetry are obvious. For transitivity, suppose  $i \leftrightarrow j$  and  $j \leftrightarrow k$ . Suppose  $p_{ij}^{(m)} > 0$  and  $p_{jk}^{(n)} > 0$ . Then by Chapman Kolmogorov, we have

$$p_{ik}^{(m+n)} = \sum_{l \in \mathbb{N}_0} p_{il}^{(m)} p_{lk}^{(n)} \geq p_{ij}^{(m)} p_{jk}^{(n)} > 0$$

Hence transitivity is assured. □

### 3.1 Irreducibility and periodicity

A consequence of the previous result is that communicating classes are disjoint or identical. A Markov chain with a single class is called an **irreducible** Markov chain. The **period** of state  $i$  is defined as

$$d(i) = \gcd\{n \in \mathbb{N}_0 : p_{ii}^{(n)} > 0\}$$

If the period is 1, we say the state is **aperiodic**.

**Proposition 3.2.** *If  $i \leftrightarrow j$ , then  $d(i) = d(j)$ . Basically, periodicity is a class property.*

*Proof.* Let  $m$  and  $n$  be such that  $p_{ij}^{(m)} p_{ji}^{(n)} > 0$ . Suppose  $p_{ii}^{(s)} > 0$ . Then

$$p_{jj}^{(n+m)} \geq p_{ji}^{(n)} p_{ij}^{(m)} > 0$$

$$p_{jj}^{(n+s+m)} \geq p_{ji}^{(n)} p_{ii}^{(s)} p_{ij}^{(m)} > 0$$

Hence  $d(j) | n+m$  and  $d(j) | n+s+m$  which implies  $d(j) | s$ . Hence  $d(j) | d(i)$ . By symmetrical arguments, we get  $d(i) | d(j)$ . Hence  $d(i) = d(j)$ . □

### 3.2 Transient and recurrent states

Let  $f_{ij}^{(n)}$  denote the probability that starting from state  $i$ , the first transition into state  $j$  happens at time  $n$ . Then let

$$f_{ij} = \sum_{n=1}^{\infty} f_{ij}^{(n)}$$

Here  $f_{ij}$  would therefore denote the probability of ever entering state  $j$  given that we start at state  $i$ . State  $j$  is said to be **transient** if  $f_{jj} < 1$  and **recurrent** if  $f_{jj} = 1$ .

**Proposition 3.3.** *The total number of visits to a state  $j \in E$  is denoted by  $N_j = \sum_{n \in \mathbb{N}_0} 1\{X_n = j\}$ . Then, for each  $m \in \mathbb{N}$  and  $i \neq j$ , we have*

$$P_j\{N_j = m\} = f_{jj}^{m-1}(1 - f_{jj}), \quad m \in \mathbb{N}$$

$$P_i\{N_j = m\} = \begin{cases} 1 - f_{ij} & m = 0, \\ f_{ij} f_{jj}^{m-1}(1 - f_{jj}) & m \in \mathbb{N}. \end{cases}$$

*Proof.* For each  $k \in \mathbb{N}$ , the time of the  $k$ th visit to the state  $j$  is a stopping time. From strong Markov property, the next return to state  $j$  is independent of the past. Hence, each return to state  $j$  is an *iid* Bernoulli random variable with probability  $f_{jj}$ . It follows that the number of visits  $j$  is the time for first failure to return. Conditioned on  $X_0 = j$ , the distribution of  $N_j$  is geometric random variable with success probability  $1 - f_{jj}$ .

Conditioned on  $X_0 = i$ , the stopping time of first visit to  $j$  is a Bernoulli random variable with probability  $f_{ij}$ . Hence, the second result follows.  $\square$

**Corollary 3.4.** For a Markov chain  $X$ ,  $P_j\{N_j < \infty\} = 1\{f_{jj} < 1\}$ .

*Proof.* We can write the event  $\{N_j < \infty\}$  as disjoint union of events  $\{N_j = n\}$ , to get

$$P_j\{N_j \in \mathbb{N}\} = \sum_{n \in \mathbb{N}} P_j\{N_j = n\} = 1\{f_{jj} < 1\}.$$

$\square$

In particular, this corollary implies the following

1. A transient state is visited a finite amount of times almost surely.
2. A recurrent state is visited infinitely often almost surely.
3. In a finite state Markov chain, not all states may be transient.

**Proposition 3.5.** A state  $j$  is recurrent iff  $\sum_{k \in \mathbb{N}} p_{jj}^{(k)} = \infty$ .

*Proof.* For any state  $j \in E$ , we can write

$$p_{ii}^{(k)} = \mathbb{P}_i\{X_k = i\} = \mathbb{E}_i 1\{X_k = i\}.$$

Using monotone convergence theorem to exchange expectation and summation, we obtain

$$\sum_{k \in \mathbb{N}} p_{ii}^{(k)} = \mathbb{E}_i \sum_{k \in \mathbb{N}} 1\{X_k = i\} = \mathbb{E}_i N_i.$$

Thus,  $\sum_{k \in \mathbb{N}} p_{ii}^{(k)}$  represents the expected number of returns  $\mathbb{E}_i N_i$  to a state  $i$  starting from state  $i$ , which we know to be finite if the state is transient and infinite if the state is recurrent.  $\square$

**Proposition 3.6.** Transience and recurrence are class properties.

*Proof.* Let us start with proving recurrence is a class property. Let  $i$  be a recurrent state and let  $i \leftrightarrow j$ . Hence there exist some  $m, n > 0$ , such that  $p_{ij}^{(m)} > 0$  and  $p_{ji}^{(n)} > 0$ . As a consequence of the recurrence,  $\sum_{s \in \mathbb{N}_0} p_{ii}^{(s)} = \infty$ . It follows that  $j$  is recurrent by observing

$$\sum_{s \in \mathbb{N}_0} p_{jj}^{(m+n+s)} \geq \sum_{s \in \mathbb{N}_0} p_{ji}^{(n)} p_{ii}^{(s)} p_{ij}^{(m)} = \infty.$$

Now, if  $i$  were transient instead, we conclude that  $j$  is also transient by the following observation

$$\sum_{s \in \mathbb{N}_0} p_{jj}^{(s)} \leq \frac{\sum_{s \in \mathbb{N}_0} p_{ii}^{(m+n+s)}}{p_{ji}^{(n)} p_{ij}^{(m)}} < \infty.$$

$\square$

**Corollary 3.7.** If  $j$  is recurrent, then for any state  $i$  such that  $i \leftrightarrow j$ ,  $f_{ij} = 1$ .