# Lecture-20: DTMC: Representation

### **1** *n*-step transition

**Definition 1.1.** For a homogeneous Markov chain  $X : \Omega to X^{\mathbb{Z}_+}$ , we can define *n*-step transition probabilities for  $x, y \in X$  and  $m, n \in \mathbb{N}$ 

$$p_{xy}^{(n)} \triangleq P(\{X_{n+m} = y\} | \{X_m = x\}).$$

That is, the row  $P_x^{(n)} = (p_{xy}^{(n)} : y \in \mathcal{X})$  is the conditional distribution of  $X_n$  given  $X_0 = x$ .

**Theorem 1.2.** The *n*-step transition probabilities form a semi-group. That is, for all positive integers m, n

$$P^{(m+n)} = P^{(m)}P^{(n)}$$

*Proof.* The events  $\{\{X_m = z\} : z \in X\}$  partition the sample space  $\Omega$ , and hence we can express the event  $\{X_{m+n} = y\}$  as the following disjoint union

$$\{X_{m+n} = y\} = \bigcup_{z \in \mathcal{X}} \{X_{m+n} = y, X_m = z\}.$$

It follows from the Markov property and law of total probability that for any states x, y and positive integers m, n

$$p_{xy}^{(m+n)} = \sum_{z \in \mathcal{X}} P_x(\{X_{n+m} = y, X_m = z\}) = \sum_{z \in \mathcal{X}} P(\{X_{n+m} = y \mid X_m = z, X_0 = x\}) P_x(\{X_m = z\})$$
$$= \sum_{z \in \mathcal{X}} P(\{X_{n+m} = y \mid X_m = z\}) P_x(\{X_m = z\}) = \sum_{z \in \mathcal{X}} p_{xz}^{(m)} p_{zy}^{(n)} = (P^{(m)} P^{(n)})_{xy}.$$

Since the choice of states  $x, y \in \mathcal{X}$  were arbitrary, the result follows.

**Corollary 1.3.** The *n*-step transition probability matrix is given by  $P^{(n)} = P^n$  for any positive integer *n*.

*Proof.* In particular, we have  $P^{(n+1)} = P^{(n)}P^{(1)} = P^{(1)}P^{(n)}$ . Since  $P^{(1)} = P$ , we have  $P^{(n)} = P^n$  by induction.

*Remark* 1. That is, for all states x, y and non-negative integers  $n \in \mathbb{Z}_+$ ,  $p_{xy}^{(n)} = P_{xy}^n$ .

# 2 Representation

#### 2.1 Chapman Kolmogorov equations

We denote by  $\pi_0 \in \mathbb{R}^{\mathcal{X}}_+$  the initial distribution of the Markov chain, that is  $\pi_0(x) = P\{X_0 = x\}$ . The distribution of  $X_n$  is given by  $\pi_n \in \mathbb{R}^{\mathcal{X}}_+$ , such that for any state  $x \in \mathcal{X}$ .

$$\pi_n(x) = P\{X_n = x\} = \sum_{z \in \mathcal{X}} p_{zx}^{(n)} \pi_0(z) = (\pi_0 P^n)_x.$$

We can write this succinctly in terms of transition probability matrix *P* as  $\mu_n = \mu_0 P^n$ . We can alternatively derive this result by the following Lemma.

**Lemma 2.1.** The right multiplication of a probability vector with the transition matrix *P* transforms the probability distribution of current state to probability distribution of the next state. That is,

$$\pi_{n+1} = \pi_n P$$
, for all  $n \in \mathbb{N}$ .

*Proof.* To see this, we fix  $y \in X$  and from the law of total probability and the definition conditional probability, we observe that

$$\pi_{n+1}(y) = P\{X_{n+1} = y\} = \sum_{x \in \mathcal{X}} P\{X_{n+1} = y, X_n = x\} = \sum_{x \in \mathcal{X}} P\{X_n = x\} p_{xy} = (\pi_n P)_y.$$

### 2.2 Transition graph

We can define a collection *E* of possible one-step transitions indicated by the initial and the final state, as

$$E \triangleq \left\{ \left[ x, y \right\} \in \mathfrak{X} \times \mathfrak{X} : p_{xy} > 0 \right\}.$$

A transition matrix *P* is sometimes represented by a directed weighted graph  $G = (\mathcal{X}, E, W)$ , where the set of nodes in the graph *G* is the state space  $\mathcal{X}$ , and the set of directed edges is the set of possible transitions. In addition, this graph has a weight  $w_e = p_{xy}$  on each edge  $e = [x, y] \in E$ .

**Example 2.2 (Integer random walk).** For an integer random walk  $X = (X_n \in \mathbb{Z} : n \in \mathbb{N})$  with *i.i.d.* stepsize sequence  $Z = (Z_n \in \{-1,1\}, n \in \mathbb{N})$ , we have and infinite graph  $G = (\mathbb{Z}, E)$ , where the edge set is

$$E = \{(n, n+1) : n \in \mathbb{Z}\} \cup \{(n, n-1) : n \in \mathbb{Z}\}.$$

We have plotted the sub-graph of the entire transition graph for states  $\{-1,0,1\}$  in Figure 1.

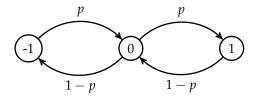


Figure 1: Sub-graph of the entire transition graph for an integer random walk with *i.i.d.* step-sizes in  $\{-1,1\}$  with probability *p* for the positive step.

**Example 2.3 (Sequence of experiments).** Consider the sequence of experiments with the set of outcomes  $\mathcal{X} = \{0,1\}$  with the transition matrix

$$P = \begin{bmatrix} 1-q & q \\ p & 1-p \end{bmatrix}.$$

We have plotted the corresponding transition graph for this two-state Markov chain in Figure 2.

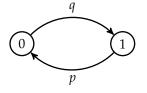


Figure 2: Markov chain for the sequence of experiments with two outcomes.

#### 2.3 Random Mapping Theorem

We saw some example of Markov processes where  $X_n = X_{n-1} + Z_n$ , and  $(Z_n : n \in \mathbb{N})$  is an iid sequence, independent of the initial state  $X_0$ . We will show that any discrete time Markov chain is of this form, where the sum is replaced by arbitrary functions.

**Theorem 2.4 (Random mapping theorem).** For any DTMC X, there exists an i.i.d. sequence  $Z \in \Lambda^{\mathbb{N}}$  and a function  $f : \mathfrak{X} \times \Lambda \to \mathfrak{X}$  such that  $X_n = f(X_{n-1}, Z_n)$  for all  $n \in \mathbb{N}$ .

*Remark* 2. A **random mapping representation** of a transition matrix *P* on state space  $\mathfrak{X}$  is a function *f* :  $\mathfrak{X} \times \Lambda \rightarrow \mathfrak{X}$ , along with a  $\Lambda$ -valued random variable *Y*, satisfying

$$P\{f(x,Y) = y\} = p_{xy}, \text{ for all } x, y \in \mathcal{X}.$$

*Proof.* It suffices to show that every transition matrix *P* has a random mapping representation. Then for the mapping *f* and the *i.i.d* sequence  $Z = (Z_n : n \in \mathbb{N})$  with the same distribution as random variable *Y*, we would have  $X_n = f(X_{n-1}, Z_n)$  for all  $n \in \mathbb{N}$ .

Let  $\Lambda = [0,1]$ , and we choose the *i.i.d.* sequence *Z*, uniformly at random from this interval. Since  $\mathfrak{X}$  is countable, it can be ordered. We let  $\mathfrak{X} = \mathbb{N}$  without any loss of generality. We set  $F_{xy} \triangleq \sum_{w \le y} p_{xw}$  and define

$$f(x,z) = \sum_{y \in \mathbb{N}} y \mathbb{1}_{\left\{F_{x,y-1} < z \leq F_{x,y}\right\}} = \inf \left\{y \in \mathfrak{X} : z \leq F_{x,y}\right\}.$$

Since  $f(x, Z_n)$  is a discrete random variable taking value  $y \in \mathcal{X}$ , iff the uniform random variable  $Z_n$  lies in the interval  $(F_{x,y-1}, F_{x,y}]$ . That is, the event  $\{f(x, Z_n) = y\} = \{Z_n \in (F_{x,y-1}, F_{x,y}]\}$  for all  $y \in \mathcal{X}$ . It follows that

$$P\{f(x,Z) = y\} = P\{F_{x,y-1} < Z \leq F_{x,y}\} = F_{x,y} - F_{x,y-1} = p_{xy}.$$

# 3 Strong Markov property (SMP)

We are interested in generalizing the Markov property to any random times. For a DTMC  $X : \Omega \to X^{\mathbb{Z}_+}$ , let  $T : \Omega \to \mathbb{N}$  be an integer random variable, and we are interested in knowing whether for any historical event  $H_{T-1} = \bigcap_{n=0}^{T-1} \{X_n = x_n\}$  and any state  $x, y \in \mathcal{X}$ , we have

$$P(\{X_{T+1} = y\} \mid H_{T-1} \cap \{X_T = x\}) = p_{xy}.$$

**Example 3.1 (Two-state DTMC).** For the two state Markov chain  $X \in \{0,1\}^{\mathbb{Z}_+}$  such that  $P_0\{X_1 = 1\} = q$  and  $P_1\{X_1 = 0\} = p$  for  $p, q \in [0,1]$ . Let  $T : \Omega \to \mathbb{N}$  be an integer random variable defined as

$$T \triangleq \sup \{n \in \mathbb{N} : X_i = 0, \text{ for all } i \leq n\}.$$

That is,  $\{T = n\} = \{X_1 = 0, ..., X_n = 0, X_{n+1} = 1\}$ . Hence, for the historical event  $H_{T-1} = \{X_1 = ..., X_{T-1} = 0\}$ , the conditional probability  $P(\{X_{T+1} = 1\} | H_{T-1} \cap \{X_T = 0\}) = 1$ , and not equal to q.

**Definition 3.2.** Let *T* be an integer valued stopping time with respect to a random sequence *X*. Then for all states  $x, y \in X$  and the event  $H_{T-1} = \bigcap_{n=0}^{T-1} \{X_n = x_n\}$ , the process *X* satisfies the **strong Markov property** if

$$P(\{X_{T+1} = y\} \mid \{X_T = x\} \cap H_{T-1}) = P(\{X_{T+1} = y\} \mid \{X_T = x\}).$$

Lemma 3.3. Homogeneous Markov chains satisfy the strong Markov property.

*Proof.* Let  $X \in X^{\mathbb{Z}_+}$  be a homogeneous DTMC with transition matrix *P*. We take any historical event  $H_{T-1} = \bigcap_{n=0}^{T-1} \{X_n = x_n\}$ , and  $x, y \in X$ . Then, from the definition of conditional probability, the law of total probability, and the Markovity of the process *X*, we have

$$P(\{X_{T+1} = y\} \mid H_{T-1} \cap \{X_T = x\}) = \frac{\sum_{n \in \mathbb{Z}_+} P(\{X_{T+1} = y, X_T = x\} \cap H_{T-1} \cap \{T = n\})}{P(\{X_T = x\} \cap H_{T-1})}$$
  
=  $\sum_{n \in \mathbb{Z}_+} P(\{X_{n+1} = y\} \mid \{X_n = x\} \cap H_{n-1} \cap \{T = n\}) P(\{T = n\} \mid \{X_T = x\} \cap H_{T-1})$   
=  $p_{xy} \sum_{n \in \mathbb{Z}_+} P(\{T = n\} \mid \{X_T = x\} \cap H_{T-1}) = p_{xy}.$ 

This equality follows from the fact that the event  $\{T = n\}$  is completely determined by  $(X_0, \dots, X_n)$ .

**Example 3.4 (For a non stopping time** *T***).** As an exercise, if we try to use the Markov property on arbitrary random variable *T*, the SMP may not hold. For example, define a non-stopping time  $T \triangleq \inf \{n \in \mathbb{Z}_+ : X_{n+1} = y\}$  for  $y \in \mathcal{X}$ . In this case, we have

$$P(\{X_{T+1} = y\} \mid \{X_T = x, \dots, X_0 = x_0\}) = 1_{\{p_{xy} > 0\}} \neq P(\{X_1 = y\} \mid \{X_0 = x\}) = p_{xy}.$$

*Remark* 3. A useful application of the strong Markov property is as follows. Let  $x_0 \in X$  be a fixed state and  $\tau_0 = 0$ . Let  $\tau_n$  denote the stopping times at which the Markov chain visits  $x_0$  for the *n*th time. That is,

$$\tau_n \triangleq \inf \left\{ n > \tau_{n-1} : X_n = x_0 \right\}.$$

Then  $(X_{\tau_n+m} \in \mathfrak{X}^{\Omega} : m \in \mathbb{Z}_+)$  is a stochastic replica of  $X : \Omega \to \mathfrak{X}^{\mathbb{Z}_+}$  with  $X_0 = x_0$ .