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Tutorial 6: Characteristic Functions and Jointly Gaussian RVs		
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## 6.1 Characteristic Functions

**Definition** (Characteristic Function). Let  $(\Omega, \mathcal{F}, \mathbb{P})$  be a given probability space, and let X be an  $\mathcal{F}$ -measurable RV. Then, the characteristic function of X denoted as  $\phi_X(\omega)$ , for  $\omega \in \mathbb{R}$ , is defined as

$$\phi_X(\omega) = \mathbb{E}\left[\exp\left(j\omega X\right)\right], \quad \omega \in \mathbb{R},$$

where  $j = \sqrt{-1}$ .

**Remark.**  $|\phi_X(\omega)| \leq 1, \forall \omega \in \mathbb{R}$ . Hence, the characteristic function is bounded in magnitude.

We now compute the characteristic function of the standard normal RV.

**Example** (Characteristic function of the standard normal). Let  $X \sim \mathcal{N}(0, 1)$ . For a fixed  $\omega \in \mathbb{R}$ ,

$$\phi_X(\omega) = \mathbb{E}\left[\exp\left(j\omega X\right)\right]$$
$$= \underbrace{\mathbb{E}\left[\cos\left(\omega X\right)\right]}_{L_1(\omega)} + j\underbrace{\mathbb{E}\left[\left(\sin\left(\omega X\right)\right)\right]}_{L_2(\omega)}.$$

Now, 
$$L_2(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \sin(\omega x) e^{-\frac{x^2}{2}} dx = 0,$$

since  $\sin(\omega x) : \mathbb{R} \to [-1, 1]$  is an odd function.

Further, 
$$L_1(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \cos(\omega X) e^{-\frac{x^2}{2}} dx$$
$$= \frac{2}{\sqrt{2\pi}} \int_{0}^{\infty} \cos(\omega X) e^{-\frac{x^2}{2}} dx.$$

The second equality is valid because  $\cos(\omega x) : \mathbb{R} \to [-1, 1]$  is an even function. We now take the derivative

of  $\phi_X(\omega)$  and use the bounded convergence theorem (because  $|\cos(\omega X)| \leq 1$ ) to get

$$\frac{d\phi_X(\omega)}{d\omega} = \frac{dL_1(\omega)}{d\omega}$$

$$= 2\int_0^\infty -x\sin(\omega x)\frac{1}{\sqrt{2\pi}}e^{-\frac{-x^2}{2}}dx$$

$$= \frac{2}{\sqrt{2\pi}}\int_0^\infty \sin(\omega x)\left(-xe^{-\frac{x^2}{2}}\right)dx$$

$$= -\omega\int_0^\infty \cos(\omega x)\frac{1}{\sqrt{2\pi}}e^{-\frac{x^2}{2}}dx \quad \text{(integration by parts)}$$

$$= -\omega L_1(\omega) = -\omega\phi_X(\omega).$$

The unique solution to the above ODE is

$$\phi_X(\omega) = e^{-\frac{\omega^2}{2}}, \quad \omega \in \mathbb{R}.$$

**Exercise 6.1.** Show that for  $a, b \in \mathbb{R}$ 

$$\phi_{aX+b}\left(\omega\right) = e^{j\omega b}\phi_{aX}\left(\omega\right) = e^{j\omega b}\phi_{X}\left(a\omega\right).$$

Use this to show that for  $Y \sim \mathcal{N}(\mu, \sigma^2)$ , for  $\mu \in \mathbb{R}, \sigma^2 > 0$ ,

$$\phi_Y\left(\omega\right) = e^{j\omega\mu - \omega^2 \sigma^2/2}$$

## 6.1.1 Joint Characteristic Functions

**Definition** (Joint Characteristic Function). Let  $(\Omega, \mathcal{F}, \mathbb{P})$  be a probability space, and let  $X_1, X_2, \ldots, X_n$  be  $\mathcal{F}$ -measurable RVs. Then, the joint characteristic function of  $\mathbf{X} = (X_1, X_2, \ldots, X_n)$  is denoted by  $\phi_{\mathbf{X}}(\boldsymbol{\omega})$  and is defined for all  $\boldsymbol{\omega} = (\omega_1, \omega_2, \ldots, \omega_n) \in \mathbb{R}^n$  as

$$\phi_{\boldsymbol{X}}(\boldsymbol{\omega}) = \mathbb{E}\left[e^{j\boldsymbol{\omega}^{\mathsf{T}}\mathbf{X}}\right] = \mathbb{E}\left[\exp\left(j\sum_{i=1}^{n}\omega_{i}X_{i}\right)\right], \ \omega_{i} \in \mathbb{R}, \ \forall i \in [n].$$

**Remark.** Note that  $\boldsymbol{\omega}$  is an *n*-length vector of real numbers, which are <u>not</u> necessarily identical.

We now state two important results about characteristic functions.

**Theorem** (Joint Characteristic Functions and Independence). Let  $(\Omega, \mathcal{F}, \mathbb{P})$  be a probability space and for  $n \in \mathbb{N}$ , let  $X_1, X_2, \ldots, X_n$  be  $\mathcal{F}$ -measurable RVs. Then  $X_1, X_2, \ldots, X_n$  are mutually independent iff

$$\phi_{\boldsymbol{X}}(\boldsymbol{\omega}) = \prod_{i=1}^{n} \phi_{X_i}(\omega_i) \quad \forall \boldsymbol{\omega} = (\omega_1, \omega_2, \dots, \omega_n) \in \mathbb{R}^n.$$

**Remark.** Note that the condition stated above must hold for all  $\boldsymbol{\omega}$  and for not just  $\boldsymbol{\omega} = (\hat{\omega}, \hat{\omega}, \dots, \hat{\omega}) \in \mathbb{R}$ , for independence to hold true.

**Theorem** (Characteristic Functions and Distributions). Let  $(\Omega, \mathcal{F}, \mathbb{P})$  be a probability space, and let X and Y be two  $\mathcal{F}$ -measurable RVs such that

$$\phi_X(\omega) = \phi_Y(\omega), \quad \forall \omega \in \mathbb{R}.$$

Then,  $F_X(x) = F_Y(x)$  for all  $x \in \mathbb{R}$ .

**Remark.** Thus, in order to show that two RVs have the same distribution, it suffices to show that their characteristic functions are identical.

## 6.2 Jointly Gaussian Random Variables

Before we proceed to study joint Gaussianity in general, here is a small exercise on independent Gaussian RVs.

**Exercise 6.2.** Suppose that  $(\Omega, \mathcal{F}, \mathbb{P})$  is a probability space, and  $X_1, X_2, \ldots, X_n$  are independent  $\mathcal{F}$ -measurable RVs. Then, any linear combination  $Y = a_1X_1 + a_2X_2 + \ldots + a_nX_n$ , for  $a_i \in \mathbb{R}, i \in [n]$ , is a Gaussian RV.

<u>Hint</u>: We know the form of the characteristic function of a RV  $Z = \mathcal{N}(\mu, \sigma^2)$ . Use the independence property to compute  $\phi_Y(\omega)$ , for  $\omega \in \mathbb{R}$ , and use the theorem about characteristic functions and distributions stated above.

**Exercise 6.3** (Supplementary exercise on Normal RVs). Let X be a RV with the  $\mathcal{N}(0,1)$  distribution and let a > 0. Show that the RV Y given by

$$Y = \begin{cases} X, & \text{if } |X| < a, \\ -X, & \text{if } |X| \ge a, \end{cases}$$

has the  $\mathcal{N}(0,1)$  distribution.

Let us now define jointly Gaussian RVs.

**Definition** (Jointly Gaussian RV). A collection  $(X_i : i \in I)$ , for some index set  $I \subseteq \mathbb{R}$ , of RVs has a joint Gaussian distribution if every *finite* linear combination of  $(X_i : i \in I)$  is a Gaussian RV.

**Remark.** A random vector X is called a Gaussian random vector if its co-ordinate random variables are jointly Gaussian.

Let  $X_1, X_2, \ldots, X_n$  be  $\mathcal{F}$ -measurable jointly Gaussian RVs with finite means, and let  $\mathbf{X} = (X_1, X_2, \ldots, X_n)$ . Further let

$$\boldsymbol{\mu} \triangleq \left( \mathbb{E}\left[ X_1 \right], \mathbb{E}\left[ X_2 \right], \dots, \mathbb{E}\left[ X_n \right] \right),$$

and

$$\boldsymbol{K} \triangleq \mathbb{E}\left[ (\boldsymbol{X} - \boldsymbol{\mu}) (\boldsymbol{X} - \boldsymbol{\mu})^{\mathsf{T}} \right].$$

**Remark.** K is called the covariance matrix of the random vector X. Note that K, by definition, is *positive semi-definite*, i.e.,

$$\boldsymbol{x}^{\mathsf{T}}\boldsymbol{K}\boldsymbol{x} \geq 0, \quad \boldsymbol{x} \in \mathbb{R}^{n}.$$

Then, the following lemma holds.

**Lemma** (Characteristic Function of Jointly Gaussian RVs). If  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  is a Gaussian random vector, then its characteristic function is given by

$$\phi_{\boldsymbol{X}}(\boldsymbol{\omega}) = \mathbb{E}\left[e^{j\boldsymbol{\omega}^{\mathsf{T}}\boldsymbol{X}}\right] = \exp\left(j\boldsymbol{\omega}^{\mathsf{T}}\boldsymbol{\mu} - \frac{1}{2}\boldsymbol{\omega}^{\mathsf{T}}\boldsymbol{K}\boldsymbol{\omega}\right), \quad \forall \boldsymbol{\omega} \in \mathbb{R}^{n}.$$

*Proof.* Fix  $\boldsymbol{\omega} = (\omega_1, \omega_2, \dots, \omega_n) \in \mathbb{R}^n$ . Then, the RV  $\boldsymbol{\omega}^{\mathsf{T}} \mathbf{X}$  is Gaussian (why?)

with mean 
$$\mathbb{E}\left[\omega^{\mathsf{T}}X\right] = \omega^{\mathsf{T}}\mu$$

and variance  $\mathbb{E}\left[\left(\boldsymbol{\omega}^{\mathsf{T}}\boldsymbol{X} - \boldsymbol{\omega}^{\mathsf{T}}\boldsymbol{\mu}\right)^{\mathsf{T}}\left(\boldsymbol{\omega}^{\mathsf{T}}\boldsymbol{X} - \boldsymbol{\omega}^{\mathsf{T}}\boldsymbol{\mu}\right)\right] = \boldsymbol{\omega}^{\mathsf{T}}\boldsymbol{K}\boldsymbol{\omega}.$ 

Since the characteristic function of a Gaussian RV Y with mean  $\tilde{\mu} \in \mathbb{R}$  and variance  $\theta^2 > 0$  is given by  $\phi_Y(\omega) = e^{j\omega\tilde{\mu} - \omega^2\theta^2/2}$ , it follows that

$$\phi_{\boldsymbol{X}}(\boldsymbol{\omega}) = \phi_{\boldsymbol{\omega}^{\mathsf{T}}\boldsymbol{\mathbf{X}}}(1) = \exp\left(j\boldsymbol{\omega}^{\mathsf{T}}\boldsymbol{\mu} - \frac{1}{2}\boldsymbol{\omega}^{\mathsf{T}}\boldsymbol{K}\boldsymbol{\omega}\right).$$

**Remark.** In fact, it can be show that a random vector  $\boldsymbol{X}$  with characteristic function  $\phi_X(\boldsymbol{\omega}) = \exp\left(j\boldsymbol{\omega}^{\mathsf{T}}\boldsymbol{\delta} - \frac{1}{2}\boldsymbol{\omega}^{\mathsf{T}}\boldsymbol{Q}\boldsymbol{\omega}\right)$  for some  $\boldsymbol{\delta} \in \mathbb{R}^n$  and a positive semi-definite real matrix  $\boldsymbol{Q} \in \mathcal{M}_{n \times n}$ . The proof of this statement is left as an exercise.

<u>Hint</u>: We need to show that any finite linear combination  $Y = a_1 X_1 + \ldots + a_n X_n$  for  $(a_1, a_2, \ldots, a_n) \in \mathbb{R}^b$  is Gaussian. To show this, it suffices to show that the characteristic function  $\phi_Y(\omega), \omega \in \mathbb{R}$ , is in the form of the characteristic function of a Gaussian RV  $\forall (a_1, a_2, \ldots, a_n) \in \mathbb{R}^n$ .

From the above observation, it follows that the vector  $\boldsymbol{\mu} = (\mathbb{E}[X_1], \mathbb{E}[X_2], \dots, \mathbb{E}[X_n])$ , and the covariance matrix  $\boldsymbol{K}$  are sufficient to fully characterize a Gaussian random vector.

**Exercise 6.4.** Let  $X = (X_1, X_1, \ldots, X_n)$  be a Gaussian random vector with mean  $\mu$  and covariance matrix K. Show that  $(X_i : i \in [n])$  are independent iff K is diagonal.

 $\underline{\operatorname{Hint}}$ : Use the theorem on joint characteristic functions and independence.

**Proposition.** A Gaussian random vector X with mean  $\mu$  and covariance matrix K, such that K is non-singular, has a pdf given by

$$f_X(x) = \frac{1}{\left(2\pi\right)^{\frac{n}{2}} \left(\det\left(\boldsymbol{K}\right)\right)^{\frac{1}{2}}} \exp\left(-\frac{(\boldsymbol{x}-\boldsymbol{\mu})^{\mathsf{T}}\boldsymbol{K}(\boldsymbol{x}-\boldsymbol{\mu})}{2}\right).$$

*Proof.* Let X be a Gaussian random vector with mean  $\mu$  and covariance matrix K. Read the following <u>fact</u> about non-singular positive semi-definite (or positive definite) matrices.

Fact 6.5. Since K is positive semi-definite and non-singular, it can be written as  $K = U\Lambda U^{\mathsf{T}}$ , where U is an *orthonormal matrix*, i.e.,  $UU^{\mathsf{T}} = U^{\mathsf{T}}U = I$ , and  $\Lambda$  is a diagonal matrix with positive eigenvalues  $\lambda_1, \lambda_2, \ldots, \lambda_n$  along the diagonal.

Let  $Y = U^{\dagger} (X - \mu)$ . Then Y is a Gaussian vector (why?) of mean 0 and covariance matrix

$$oldsymbol{Q} = \mathbb{E}\left[oldsymbol{Y}oldsymbol{Y}^{\intercal}
ight] = oldsymbol{U}^{\intercal}Koldsymbol{U} = oldsymbol{\Lambda}.$$

Since  $\Lambda$  is diagonal,  $\mathbf{Y}$  is a vector of *independent* Gaussian RVs (follows from the exercise), and  $Y_i \sim \mathcal{N}(0, \lambda_i)$ . Hence,  $\mathbf{Y}$  has the joint pdf

$$f_{\mathbf{Y}}(\mathbf{y}) = \prod_{i=1}^{n} \frac{1}{\sqrt{2\pi\lambda_i}} \exp\left(-\frac{y_i^2}{2\lambda_i}\right)$$
$$= \frac{1}{(2\pi)^{\frac{n}{2}}\sqrt{\lambda_1\lambda_2\dots\lambda_n}} \exp\left(-\frac{1}{2}\sum_{i=1}^{n}\frac{y_i^2}{\lambda_i}\right)$$

Note that det  $(\mathbf{K}) = \prod_{i=1}^{n} \lambda_i$  and  $\sum_{i=1}^{n} \frac{y_i^2}{\lambda_i} = \mathbf{y}^{\mathsf{T}} \mathbf{\Lambda}^{-1} \mathbf{y}$  since  $\mathbf{\Lambda}^{-1}$  has terms  $(1/\lambda_i)_{i \in [n]}$  along its diagonals and zeros everywhere else. Thus,

$$f_{\boldsymbol{Y}}(\boldsymbol{y}) = \frac{1}{\sqrt{2\pi^{\frac{n}{2}}}\sqrt{\det\left(\boldsymbol{K}\right)}} \exp\left(-\frac{\boldsymbol{y}^{\mathsf{T}}\boldsymbol{\Lambda}^{-1}\boldsymbol{y}}{2}\right).$$

Observe that  $X = UY + \mu$  and hence, by the transformation of random vectors, since  $|\det(U)| = 1$  (and the determinant of the Jacobian inverse is 1),

$$f_{\boldsymbol{X}}(\boldsymbol{x}) = f_{\boldsymbol{Y}} \left( \boldsymbol{U}^{\mathsf{T}}(\boldsymbol{x} - \boldsymbol{\mu}) \right)$$
  
$$= \frac{1}{\sqrt{2\pi^{\frac{n}{2}}} \sqrt{\det(\boldsymbol{K})}} \exp\left(-\frac{1}{2} (\boldsymbol{x} - \boldsymbol{\mu})^{\mathsf{T}} \boldsymbol{U} \boldsymbol{\Lambda}^{-1} \boldsymbol{U}^{\mathsf{T}}(\boldsymbol{x} - \boldsymbol{\mu})\right)$$
  
$$= \frac{1}{\sqrt{2\pi^{\frac{n}{2}}} \sqrt{\det(\boldsymbol{K})}} \exp\left(-\frac{1}{2} (\boldsymbol{x} - \boldsymbol{\mu})^{\mathsf{T}} \boldsymbol{K}^{-1} (\boldsymbol{x} - \boldsymbol{\mu})\right). \quad (\text{since } \boldsymbol{K}^{-1} = \boldsymbol{U} \boldsymbol{\Lambda}^{-1} \boldsymbol{U}^{\mathsf{T}})$$

This simple exercise uses the Fact 6.5 presented in the proof above.

**Exercise 6.6.** Show that a positive semi-definite (symmetric) matrix V has a square root i.e., there exists a symmetric matrix W such that  $W^2 = V$ .

We have seen in the proposition above that, if the covariance matrix K is non-singular, the pdf of a Gaussian random vector is determined entirely by  $\mu$  and K. But what if K is singular, i.e., det (K) = 0?

In such a situation, the random vector X <u>does not</u> have a pdf. We shall now analyze this situation.

**Illustration.** Let X be jointly Gaussian with covariance matrix K such that det (K) = 0. Hence,  $\lambda_i = 0$  for some  $i \in [n]$ , where the  $\lambda_i$ s are obtained from the decomposition in Fact 6.5.

In other words, there is a vector  $\boldsymbol{\alpha}$  (which is an eigenvector of eigenvalue 0) such that  $\boldsymbol{\alpha}^{\mathsf{T}} \boldsymbol{K} \boldsymbol{\alpha} = 0$ . However,

$$\boldsymbol{\alpha}^{\mathsf{T}} \boldsymbol{K} \boldsymbol{\alpha} = \operatorname{Var} \left( \boldsymbol{\alpha}^{\mathsf{T}} \boldsymbol{X} \right) \quad \text{Show this!} \\ = 0.$$

This implies, from the property of non-negative RVs with mean zero (we've seen this property in a previous tutorial), that

$$\boldsymbol{\alpha}^{\mathsf{T}} \left( \boldsymbol{X} - \boldsymbol{\mu} \right) = 0$$
 w.p. 1, or,

that if  $\mu = 0$ , there exists some linear combination of X that equals 0, or that if  $\mu = 0$ , the  $X_i$ s are <u>not</u> linearly independent.

**Exercise 6.7.** Let X and Y be RVs such that the vector  $\mathbf{Z} = (X, Y)$  is a Gaussian random vector with zero mean and covariance matrix

$$oldsymbol{K} = egin{bmatrix} 1 & 
ho \ 
ho & 1 \end{bmatrix}.$$

 $\rho$  is the correlation co-efficient between X and Y. Find the joint density of X + Y and X - Y.

**Exercise 6.8.** let  $\mathbf{X} = (X_1, X_2, X_3)$  be a zero mean Gaussian random vector with covariance matrix

$$\boldsymbol{K} = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 3 & 6 & 9 \end{bmatrix}.$$

- 1. Write down the marginal distributions of  $X_1, X_2$ , and  $X_3$ .
- 2. Does a joint density exist for X?