# Lecture-14: Discrete Time Markov Chains

# **1** Introduction

We have seen that *i.i.d.* sequences are easiest discrete time processes. However, they don't capture correlation well. Hence, we look at the discrete time stochastic processes of the form

 $X_{n+1} = f(X_n, Z_{n+1}),$ 

where  $Z : \Omega \to \mathbb{Z}^{\mathbb{N}}$  is an *i.i.d.* sequence independent of initial state  $X_0 \in \mathcal{X}$ , and  $f : \mathcal{X} \times \mathcal{Z} \to \mathcal{X}$  is a measurable function. The set  $\mathcal{X}$  is called the **state space** of process  $X : \Omega \to \mathcal{X}^{\mathbb{Z}_+}$ . We consider a countable state space  $\mathcal{X}$ , and if  $X_n = x \in \mathcal{X}$ , then we say that the process X is in state x at time n.

**Definition 1.1.** For the discrete random process  $X : \Omega \to \mathcal{X}^{\mathbb{Z}_+}$ , the history until time *n* is denoted by

$$\mathcal{F}_n \triangleq \sigma(X_0,\ldots,X_n).$$

The natural filtration of process *X* is denoted by  $\mathcal{F}_{\bullet} = (\mathcal{F}_n : n \in \mathbb{Z}_+)$ .

*Remark* 1. We observe that  $\mathcal{F}_n \subseteq \sigma(X_0, Z_1, \ldots, Z_n)$ .

**Definition 1.2 (Markov property).** A discrete random process  $X : \Omega \to \mathcal{X}^{\mathbb{Z}_+}$  adapted to a filtration  $\mathcal{F}_{\bullet}$  is said to have **Markov property** if

$$P(\{X_{n+1} \leqslant x\} \mid \mathcal{F}_n) = P(\{X_{n+1} \leqslant x\} \mid \sigma(X_n)), \quad n \in \mathbb{Z}_+.$$

**Definition 1.3 (DTMC).** For a countable set  $\mathcal{X}$ , a stochastic process  $X : \Omega \to \in \mathcal{X}^{\mathbb{Z}_+}$  is called a **discrete time Markov chain (DTMC)** if it satisfies the Markov property.

*Remark* 2. For a discrete Markov process  $X : \Omega \to \mathfrak{X}^{\mathbb{Z}_+}$ , we have

$$P(\{X_{n+1}=y\} | \{X_n=x, X_{n-1}=x_{n-1}, \dots, X_0=x_0\}) = P(\{X_{n+1}=y\} | \{X_n=x\}),$$

for all non-negative integers  $n \in \mathbb{Z}_+$  and all states  $x_0, x_1, \ldots, x_{n-1}, x, y \in \mathcal{X}$ .

### 1.1 Homogeneous Markov chain

For each time  $n \in \mathbb{Z}_+$ , we can define the transition probability

$$p_{xy}(n) \triangleq P(\{X_{n+1} = y\} | \{X_n = x\}).$$

When the transition probability does not depend on *n*, the DTMC is called **homogeneous**. The matrix  $P \in [0,1]^{\mathcal{X}\times\mathcal{X}}$  is called the **transition matrix**.

**Definition 1.4.** For all states  $x, y \in \mathcal{X}$ , if a non-negative matrix  $A \in \mathbb{R}^{\mathcal{X} \times \mathcal{X}}_+$  has the following property

$$a_{xy} \ge 0$$
, for all  $x, y \in \mathfrak{X}$ ,  $\sum_{y \in \mathfrak{X}} a_{xy} \le 1$ , for all  $x \in \mathfrak{X}$ 

then it is called a sub-stochastic matrix.

Definition 1.5. If the second property holds with equality, then it is called a stochastic matrix.

*Remark* 3. For a stochastic matrix, the all one vector  $\mathbf{1} \in \{1\}^{\mathcal{X}}$  is a right eigenvector with eigenvalue unity, i.e.  $A\mathbf{1} = \mathbf{1}$ .

*Remark* 4. The transition matrix *P* is stochastic matrix. Each row  $p_x = (p_{xy} : y \in \mathcal{X})$  of the stochastic matrix *P* is a distribution on the state space  $\mathcal{X}$ . This is the conditional distribution of  $X_{n+1}$  given  $X_n = x$ .

**Definition 1.6.** If in addition  $A^T$  is stochastic, then A is called **doubly stochastic**.

*Remark* 5. For a doubly stochastic matrix  $A = A^T$ , and hence

$$\mathbf{1}^T A = \mathbf{1}^T A^T = (A\mathbf{1})^T = \mathbf{1}^T.$$

For a doubly stochastic matrix, the all one vector  $\mathbf{1} \in \{1\}^{\mathcal{X}}$  is both a left and right eigenvector with eigenvalue unity.

#### **1.2** Transition graph

Let *E* be the collection of ordered pairs of states  $(x, y) \in \mathfrak{X} \times \mathfrak{X}$  such that  $p_{xy} > 0$ , i.e.

$$E = \left\{ (x, y) \in \mathfrak{X} \times \mathfrak{X} : p_{xy} > 0 \right\}.$$

Then a transition matrix *P* can be represented by a directed edge-weighted graph  $G = (\mathfrak{X}, E)$  such that weight  $w: E \to [0, 1]$  for each edge *e* is  $w(e) \triangleq p_{xy}$  on each edge  $e = (x, y) \in E$ .

**Example 1.7 (Random walk on lattice).** We denote the random particle location on a *d*-dimensional lattice after *n* steps by  $X_n \in \mathbb{Z}^d$ , where the random *i.i.d.* step-size sequence is denoted by  $Z : \Omega \to (\mathbb{Z}^d)^{\mathbb{N}}$  having common probability mass function  $p \in [0,1]^{\mathbb{Z}^d}$ . The particle location at time *n* is  $X_n = \sum_{i=1}^n Z_i$ . We will show that *X* is a homogeneous DTMC.

For a lattice point  $x \in \mathbb{Z}^d$ , we can write the conditional expectation

$$\mathbb{E}[\mathbb{1}_{\{X_n=x\}}|\mathcal{F}_{n-1}] = \sum_{y\in\mathbb{Z}^d} \mathbb{E}[\mathbb{1}_{\{X_{n-1}=x-y\}}\mathbb{1}_{\{Z_n=y\}}|\mathcal{F}_{n-1}] = \sum_{y\in\mathbb{Z}^d} p(y)\mathbb{1}_{\{X_{n-1}=x-y\}} = \mathbb{E}[\mathbb{1}_{\{X_n=x\}}|\sigma(X_{n-1})].$$

Markov property of the random walk follows from the independence of random step-sizes. Homogeneity follows from the identical distribution of random step-sizes.

#### **1.3 Chapman Kolmogorov equations**

Let  $v_n \in [0,1]^{\mathcal{X}}$  denote the marginal distribution of the process *X* at time *n*, i.e.  $v_n(x) = P\{X_n = x\}$ .

**Definition 1.8.** We can define *n*-step transition probabilities for a homogeneous Markov chain  $X : \Omega \to \mathcal{X}^{\mathbb{Z}_+}$  for states  $x, y \in \mathcal{X}$  and non-negative integers  $m, n \in \mathbb{Z}_+$  as

$$p_{xy}^{(n)} \triangleq P(\{X_{n+m} = y\} | \{X_m = x\}).$$

Remark 6. It follows from the Markov property and law of total probability that

$$p_{xy}^{(m+n)} = \sum_{z \in \mathcal{X}} p_{xz}^{(m)} p_{zy}^{(n)}.$$

We can write this result compactly in terms of transition probability matrix *P* as  $P^{(n)} = P^n$ . *Remark* 7. We can write this vector  $v_n$  in terms of initial probability vector  $v_0$  and the transition matrix *P* as

$$v_n = v_0 P^n$$
.

*Remark* 8. Let  $f : \mathfrak{X} \to \mathbb{R}$  be a vector then we define its inner product of matrix  $P : \mathfrak{X} \times \mathfrak{X} \to \mathbb{R}$  as a vector  $\langle P, f \rangle : \mathfrak{X} \to \mathbb{R}$ , where

$$(Pf)_x = \sum_{y \in \mathcal{X}} P_{xy} f_y, \quad x \in \mathcal{X}.$$

It follows that, we can write

$$(Pf)_x = \mathbb{E}[f(X_1)| \{X_0 = x\}] = \mathbb{E}_x f(X_1).$$

#### **1.4** Strong Markov property (SMP)

Let  $\tau : \Omega \to \mathbb{Z}_+$  be an almost surely finite integer valued stopping time adapted to the natural filtration of the stochastic process  $X : \Omega \to \mathcal{X}^{\mathbb{Z}_+}$ . Then for all  $x_0, \ldots, x_{n-1}, x, y \in \mathcal{X}$ , the process X satisfies the **strong Markov property** if

$$P(\{X_{\tau+1}=y\} | \{X_{\tau}=x,\ldots,X_0=x_0\}) = p_{xy}.$$

Lemma 1.9. Markov chains satisfy the strong Markov property.

*Proof.* Let *X* be a Markov chain and an event  $A = \{X_{\tau} = x, \dots, X_0 = x_0\} \in \mathcal{F}_{\tau}$ . Then, we have

$$P(\{X_{\tau+1}=y\}\cap A) = \sum_{n\in\mathbb{Z}_+} P(\{X_{\tau+1}=y,\tau=n\}\cap A) = \sum_{n\in\mathbb{Z}_+} p_{xy}P(A\cap\{\tau=n\}) = p_{xy}P(A).$$

This equality follows from the fact that the event  $\{\tau = n\}$  is completely determined by  $\{X_0, \dots, X_n\}$ 

**Example 1.10 (Non-stopping time).** As an exercise, if we try to use the Markov property on arbitrary random variable  $\tau$ , the SMP may not hold. Consider a Markov chain  $X : \Omega \to X^{\mathbb{Z}_+}$  with natural filtration  $\mathcal{F}_{\bullet}$ . For example, define a non-stopping time  $\tau_v : \Omega \mathcal{Z}_+$  for some state  $y \in X$ 

$$\tau_{\mathbf{y}} \triangleq \inf \left\{ n \in \mathbb{Z}_+ : X_{n+1} = \mathbf{y} \right\}.$$

We can verify that  $\tau_y$  is not a stopping time for the process *X*. From the definition of  $\tau_y$ , we have  $X_{\tau_y+1} = y$ , and for  $x \in \mathcal{X}$  such that  $p_{xy} > 0$ 

$$P(\{X_{\tau_{v}+1}=y\} | \{X_{\tau_{v}}=x,\ldots,X_{0}=x_{0}\}) = 1 \neq P(\{X_{1}=y\} | \{X_{0}=x\}) = p_{xy}.$$

**Example 1.11 (Regeneration points of DTMC).** Let  $x_0 \in \mathcal{X}$  be a fixed state and  $\tau_0 = 0$ . Let  $\tau_n^+$  denote the stopping times at which the Markov chain visits state  $x_0$  for the *n*th time. That is,

$$\tau_n^+ \triangleq \inf \left\{ n > \tau_{n-1}^+ : X_n = x_0 \right\}.$$

Then  $(X_{\tau_n^++m}: m \in \mathbb{Z}_+)$  is a stochastic replica of  $(X_m: m \in \mathbb{Z}_+)$  with  $X_0 = x_0$  and can be studied as a regenerative process.

#### 1.5 Random mapping representation

**Proposition 1.12.** Any DTMC  $X : \Omega \to X^{\mathbb{Z}_+}$  on finite state space X has a random mapping representation. That is, there exists an i.i.d. sequence  $Z : \Omega \to \mathbb{Z}^{\mathbb{N}}$  and a function  $f : X \times \mathbb{Z} \to X$  such that  $X_n = f(X_{n-1}, Z_n)$  for each  $n \in \mathbb{N}$ .

*Proof.* We can order any finite set, and hence we can assume the finite state space  $\mathcal{X} = [n]$ , without any loss of generality. For *i*th row of the transition matrix *P*, we can define

$$F_{i,k} \triangleq \sum_{j=1}^{k} p_{ij} = P(\{X_{n+1} \leqslant k\} \mid \{X_n = i\}).$$

We assume  $Z : \Omega \to [0,1]^{\mathbb{N}}$  to be a sequence of *i.i.d.* uniform random variables. We define a function  $f : [n] \times [0,1]$  as

$$f(i,z) \triangleq \sum_{k=1}^{n} k \mathbb{1}_{\{F_{i,k-1} \leq z < F_{i,k}\}}, \quad i \in [n], z \in [0,1].$$

To show that this choice of function f and *i.i.d.* sequence Z works, it suffices to show that  $p_{ij} = P\{f(i, Z_n) = j\}$ . Indeed, we can write

$$P\{f(i,Z_n) = j\} = \mathbb{E}\mathbb{1}_{\{f(i,Z_n) = j\}} = \mathbb{E}\mathbb{1}_{\{F_{i,j-1} \leq Z_n < F_{i,j}\}} = F_{i,j} - F_{i,j-1} = p_{ij}.$$

## 2 Communicating classes

**Definition 2.1.** Let  $x, y \in \mathcal{X}$ . If  $p_{xy}^{(n)} > 0$  for some  $n \in \mathbb{Z}_+$ , then we say that state *y* is **accessible** from state *x* and denote it by  $x \to y$ . If two states  $x, y \in \mathcal{X}$  are accessible to each other, they are said to **communicate** with each other and denoted by  $x \leftrightarrow y$ . A set of states that communicate are called a **communicating class**.

**Definition 2.2.** A relation *R* on a set  $\mathcal{X}$  is a subset of  $\mathcal{X} \times \mathcal{X}$ .

**Definition 2.3.** An equivalence relation  $R \subseteq \mathfrak{X} \times \mathfrak{X}$  has following three properties.

Reflexivity: If  $x \in \mathcal{X}$ , then  $(x, x) \in R$ .

Symmetry: If  $(x, y) \in R$ , then  $(y, x) \in R$ .

Transitivity: If  $(x, y), (y, z) \in R$ , then  $(x, z) \in R$ .

*Remark* 9. Equivalence relations partition a set X.

Proposition 2.4. Communication is an equivalence relation.

*Proof.* Reflexivity follows from zero-step transition, and symmetry follows from the definition of communicating class.

For transitivity, suppose  $x \leftrightarrow y$  and  $y \leftrightarrow z$ . Then we can find  $m, n \in \mathbb{N}$  such that  $p_{xy}^{(m)} > 0$  and  $p_{yz}^{(n)} > 0$ . From Chapman Kolmogorov equations, we have  $m + n \in \mathbb{N}$  such that

$$p_{xz}^{(m+n)} = \sum_{w \in \mathbb{N}_0} p_{xw}^{(m)} p_{wz}^{(n)} \ge p_{xy}^{(m)} p_{yz}^{(n)} > 0.$$

#### 2.1 Irreducibility and periodicity

A consequence of the previous result is that communicating classes are disjoint or identical.

Definition 2.5. A Markov chain with a single class is called an irreducible Markov chain.

**Definition 2.6.** A class property is the one that is satisfied by all states in the communicating class.

*Remark* 10. We will see many examples of class properties. Once we have shown that a property is a class property, then one only needs to check that one of the states in the communicating class has the property for the entire class to have that.

**Definition 2.7.** We denote the set of recurrences for a Markov chain with transition probability matrix  $P : \mathcal{X} \times \mathcal{X} \rightarrow [0,1]$  to re-visit a state  $x \in \mathcal{X}$  as

$$A_x \triangleq \left\{ n \in \mathbb{N} : p_{xx}^{(n)} > 0 
ight\} \subseteq \mathbb{N}.$$

*Remark* 11. If one can re-visit a state x in m and n steps, then also in m + n steps, since  $p_{xx}^{(m+n)} \ge p_{xx}^{(m)} p_{xx}^{(n)}$ . It follows that this set is closed under addition.

**Definition 2.8.** The **period** of state *x* is defined as  $d(x) \triangleq gcd(A_x)$ . If the period is 1, we say the state is **aperiodic**.

Proposition 2.9. Periodicity is a class property.

*Proof.* We will show that for two communicating states  $x \leftrightarrow y$ , the periodicities are identical. We will show that d(x)|d(y)| and d(y)|d(x). We choose  $m, n \in \mathbb{N}$  such that

$$p_{xx}^{(m+n)} \geqslant p_{xy}^{(m)} p_{yx}^{(n)} > 0, \qquad \qquad p_{yy}^{(m+n)} \geqslant p_{yx}^{(n)} p_{xy}^{(m)} > 0.$$

It follows that  $m + n \in A_x \cap A_y$ . Let  $s \in A_x$ , then it follows that  $m + n + s \in A_y$ , since

$$p_{yy}^{(n+s+m)} \ge p_{yx}^{(n)} p_{xx}^{(s)} p_{xy}^{(m)} > 0$$

Hence d(y)|n+m and d(y)|n+s+m which implies d(y)|s. Since the choice of  $s \in A_x$  was arbitrary, it follows that d(y)|d(x). Similarly, we can show that d(x)|d(y).

**Lemma 2.10.** If A is a set closed under addition and gcd(A) = 1, then there exists  $m_0 \in A$  such that  $m \in A$  for all  $m \ge m_0$ .

*Proof.* Since the set of recurrence A is closed under addition, for any  $a \in A$ , we have  $na \in A$  for all  $n \in \mathbb{N}$ . If the minimal element of A is 1, then there is nothing to prove. Complete the proof for when minimial element is not unity.

**Proposition 2.11.** If a Markov chain  $X : \Omega \to X^{\mathbb{Z}_+}$  on a finite state space  $\mathfrak{X}$  is irreducible and aperiodic, then there exists an integer  $n_0$  such that  $p_{xy}^{(n)} > 0$  for all  $x, y \in \mathfrak{X}$  and  $n \ge n_0$ .

*Proof.* Since periodicity is a class property, it follows that  $gcd(A_x) = 1$  for all states  $x \in \mathcal{X}$ . Further, we have  $m_x \in A_x$  such that  $n \in A_x$  for all  $n \ge m_x$ . Further for any pair of states  $x, y \in \mathcal{X}$ , we can find  $n_{xy} \in \mathbb{N}$  such that  $p_{xy}^{(n_{xy})} > 0$  from the irreducibility of the Markov chain. It follows that  $p_{xy}^{(n)} > 0$  for all  $n \ge n_{xy} + m_y \in \mathbb{N}$ . Since the state space  $\mathcal{X}$  is finite, we have a finite  $n_0 \triangleq \sup_{x \in \mathcal{X}} m_x + \sup_{x,y \in \mathcal{X}} n_{xy} \in \mathbb{N}$  such that  $p_{xy}^n > 0$  for any state  $x, y \in \mathcal{X}$  for all  $n \ge a$ .

**Example 2.12 (Random walk on a ring).** Let G = (V, E) be a finite graph where  $V = \{0, ..., n-1\}$  and  $E = \{(i, i+1) : i \in V\}$  where addition is modulo n. Let  $\xi : \Omega \to \{-1, 1\}^{\mathbb{N}}$  be a random *i.i.d.* sequence of step-sizes with  $\mathbb{E}\xi_n = 2p - 1$ . We denote the location of particle after n random steps by  $X_n \triangleq X_0 + \sum_{i=1}^n \xi_i$ . It follows that the random walk  $X : \Omega \to V^{\mathbb{N}}$  is an irreducible homogeneous Markov chain with period 2 if nis even.

#### 2.2 **Random walks on graphs**

Let G = (V, E) be a graph, where  $E \subseteq V \times V$ . We say that x is a neighbor of y, when  $(x, y) \in E$  and denote it by  $x \sim y$ . Degree of a vertex  $x \in V$  is denoted by  $deg(x) = |\{y \in V : x \sim y\}|$ . For each edge  $e \in E$ , we define a function  $p: E \to [0, 1]$  such that for a fixed vertex *x*, we have  $\sum_{e=(x,y)\in E} p_e = 1$ . Random walk on this graph is denoted by the random location  $X_n \in \mathcal{X}$  of a particle on this graph after *n* random

steps, where each step is random such that

 $P(\{X_{n+1} = y\} | \{X_n = x\}) = p_e \mathbb{1}_{\{e = (x,y) \in E\}}.$