

# Lecture-21: Reversibility

## 1 Introduction

**Definition 1.1.** A stochastic process  $X : \Omega \rightarrow \mathcal{X}^{\mathbb{R}}$  is **time reversible** if the vector  $(X_{t_1}, \dots, X_{t_n})$  has the same distribution as  $(X_{\tau-t_1}, \dots, X_{\tau-t_n})$  for all finite positive integers  $n$ , time instants  $t_1 < t_2 < \dots < t_n$  and shifts  $\tau \in \mathbb{R}$ .

**Lemma 1.2.** A time reversible process is stationary.

*Proof.* It suffices to show that for any shift  $s \in \mathbb{R}$ , a finite  $n \in \mathbb{N}$ , time instants  $t_1 < \dots < t_n$ , and states  $x_1, \dots, x_n \in \mathcal{X}$ , we have

$$P\left(\bigcap_{i \in [n]} \{X_{t_i} = x_i\}\right) = P\left(\bigcap_{i \in [n]} \{X_{s+t_i} = x_i\}\right).$$

This follows from time reversibility of  $X$ , since both  $(X_{t_1}, \dots, X_{t_n})$  and  $(X_{s+t_1}, \dots, X_{s+t_n})$  have the same distribution as  $(X_{-t_1}, \dots, X_{-t_n})$ , by taking  $\tau = 0$  and  $\tau = -s$  respectively.  $\square$

**Theorem 1.3.** A stationary homogeneous Markov process  $X : \Omega \rightarrow \mathcal{X}^{\mathbb{R}}$  with countable state space  $\mathcal{X} \subseteq \mathbb{R}$  and probability transition kernel  $P : \mathbb{R}_+ \rightarrow [0, 1]^{\mathcal{X} \times \mathcal{X}}$  is time reversible iff there exists a probability distribution  $\pi \in \mathcal{M}(\mathcal{X})$ , that satisfy the detailed balanced conditions

$$\pi_x P_{xy}(t) = \pi_y P_{yx}(t) \text{ for all } x, y \in \mathcal{X} \text{ and times } t \in \mathbb{R}_+. \quad (1)$$

When such a distribution  $\pi$  exists, it is the invariant distribution of the process.

*Proof.* We assume that the process  $X$  is time reversible, and hence stationary. We denote the stationary distribution by  $\pi$ , and by time reversibility of  $X$ , we have

$$P_\pi \{X_{t_1} = x, X_{t_1+t} = y\} = P_\pi \{X_{t_1} = y, X_{t_1+t} = x\},$$

for  $\tau = 2t_1 + t$ . Hence, we obtain the detailed balanced conditions in Eq. (1).

Conversely, let  $\pi$  be the distribution that satisfies the detailed balanced conditions in Eq. (1), then summing up both sides over  $y \in \mathcal{X}$ , we see that  $\pi$  is the invariant distribution for  $X$ . Let  $x \in \mathcal{X}^m$ , then applying detailed balanced equations in Eq. (1) repeatedly, we can write

$$\pi(x_1) P_{x_1 x_2}(t_2 - t_1) \dots P_{x_{m-1} x_m}(t_m - t_{m-1}) = \pi(x_m) P_{x_m x_{m-1}}(t_m - t_{m-1}) \dots P_{x_2 x_1}(t_2 - t_1).$$

For the time homogeneous stationary Markov process  $X$ , it follows that for all  $t_0 \in \mathbb{R}_+$

$$P_\pi \{X_{t_1} = x_1, \dots, X_{t_m} = x_m\} = P_\pi \{X_{t_0} = x_m, \dots, X_{t_0+t_m-t_1} = x_1\}.$$

Since  $m \in \mathbb{N}$  and  $t_0, t_1, \dots, t_m$  were arbitrary, the time reversibility follows.  $\square$

### 1.1 Reversible Chains

**Corollary 1.4.** A stationary homogeneous discrete time Markov chain  $X : \Omega \rightarrow \mathcal{X}^{\mathbb{Z}}$  with transition matrix  $P \in [0, 1]^{\mathcal{X} \times \mathcal{X}}$  is time reversible iff there exists a probability distribution  $\pi \in \mathcal{M}(\mathcal{X})$ , that satisfies the detailed balanced conditions

$$\pi_x P_{xy} = \pi_y P_{yx}, \quad x, y \in \mathcal{X}. \quad (2)$$

When such a distribution  $\pi$  exists, it is the invariant distribution of the process.

**Example 1.5 (Random walks on edge-weighted graphs).** Consider an undirected graph  $G = (\mathcal{X}, E)$  with the vertex set  $\mathcal{X}$  and the edge set  $E = \{\{x, y\} : x, y \in \mathcal{X}\}$  being a subset of unordered pairs of elements from  $\mathcal{X}$ . We say that  $y$  is a neighbor of  $x$  (and  $x$  is a neighbor of  $y$ ), if  $e = \{x, y\} \in E$  and denote  $x \sim y$ . We assume a function  $w : E \rightarrow \mathbb{R}_+$ , such that  $w_e$  is a positive number associated with each edge  $e = \{x, y\} \in E$ . Let  $X_n \in \mathcal{X}$  denote the location of a particle on one of the graph vertices at the  $n$ th time-step. Consider the following random discrete time movement of a particle on this graph from one vertex to another. If the particle is currently at vertex  $x$  then it will next move to vertex  $y$  with probability

$$P_{xy}^g \triangleq P(\{X_{n+1} = y\} | \{X_n = x\}) = \frac{w_e}{\sum_{f:x \in f} w_f} \mathbb{1}_{\{e=\{x,y\}\}}.$$

The Markov chain  $X : \Omega \rightarrow \mathcal{X}^{\mathbb{N}}$  describing the sequence of vertices visited by the particle is a random walk on an undirected edge-weighted graph. Google's PageRank algorithm, to estimate the relative importance of webpages, is essentially a random walk on a graph!

**Proposition 1.6.** Consider an irreducible homogeneous Markov chain that describes the random walk on an edge weighted graph with a finite number of vertices. In steady state, this Markov chain is time reversible with stationary probability of being in a state  $x \in \mathcal{X}$  given by

$$\pi_x = \frac{\sum_{f:x \in f} w_f}{2 \sum_{g \in E} w_g}. \quad (3)$$

*Proof.* Using the definition of transition probabilities for this Markov chain and the given distribution  $\pi$  defined in (3), we notice that

$$\pi_x P_{xy}^g = \frac{w_e}{\sum_{f \in E} w_f} \mathbb{1}_{\{e=\{x,y\}\}}, \quad \pi_y P_{yx}^g = \frac{w_e}{\sum_{f \in E} w_f} \mathbb{1}_{\{e=\{x,y\}\}}.$$

Hence, the detailed balance equation for each pair of states  $x, y \in \mathcal{X}$  is satisfied, and the result follows.  $\square$

We can also show the following *dual* result.

**Lemma 1.7.** Let  $X : \Omega \rightarrow \mathcal{X}^{\mathbb{Z}^+}$  be a time reversible Markov chain on a finite state space  $\mathcal{X}$  and transition probability matrix  $P \in [0, 1]^{\mathcal{X} \times \mathcal{X}}$ . Then, there exists a random walk on a weighted, undirected graph  $G$  with the same transition probability matrix  $P$ .

*Proof.* We create a graph  $G = (\mathcal{X}, E)$ , where  $E = \{\{x, y\} : x, y \in \mathcal{X}, P_{xy} > 0\}$ . For the stationary distribution  $\pi : \mathcal{X} \rightarrow [0, 1]$  for the Markov chain  $X$ , we set the edge weights

$$w_{\{x,y\}} \triangleq \pi_x P_{xy} = \pi_y P_{yx},$$

With this choice of weights, it is easy to check that  $w_x = \sum_{f:x \in f} w_f = \pi_x$ , and the transition matrix associated with a random walk on this graph is exactly  $P$  with  $P_{xy}^g = \frac{w_{\{x,y\}}}{w_x} = P_{xy}$ .  $\square$

### Is every Markov chain time reversible?

1. If the process is not stationary, then no. To see this, we observe that

$$P\{X_{t_1} = x_1, X_{t_2} = x_2\} = \nu_{t_1}(x_1) P_{x_1 x_2}(t_2 - t_1), \quad P\{X_{\tau-t_2} = x_2, X_{\tau-t_1} = x_1\} = \nu_{\tau-t_2}(x_2) P_{x_2 x_1}(t_2 - t_1).$$

If the process is not stationary, the two probabilities can't be equal for all times  $\tau, t_1, t_2$  and states  $x_1, x_2 \in \mathcal{X}$ .

2. If the process is stationary, then it is still not true in general. Suppose we want to find a stationary distribution  $\alpha \in \mathcal{M}(\mathcal{X})$  that satisfies the detailed balance equations  $\alpha_x P_{xy} = \alpha_y P_{yx}$  for all states  $x, y \in \mathcal{X}$ . For any arbitrary Markov chain  $X$ , one may not end up getting any solution. To see this consider a state  $z \in \mathcal{X}$  such that  $P_{xy} P_{yz} > 0$ . Time reversibility condition implies that  $P_\alpha\{X_1 = x, X_2 = y, X_3 = z\} = P_\alpha\{X_1 = z, X_2 = y, X_3 = z\}$ , and hence

$$\frac{\alpha_x}{\alpha_z} = \frac{P_{zy} P_{yx}}{P_{xy} P_{yz}} \neq \frac{P_{zx}}{P_{xz}}.$$

Thus, we see that a necessary condition for time reversibility is  $P_{xy}P_{yz}P_{zx} = P_{xz}P_{zy}P_{yx}$  for all  $x, y, z \in \mathcal{X}$ .

**Theorem 1.8 (Kolmogorov's criterion for time reversibility of Markov chains).** *A stationary homogeneous Markov chain  $X : \Omega \rightarrow \mathcal{X}^{\mathbb{Z}}$  is time reversible if and only if starting in state  $x_0 \in \mathcal{X}$ , any path back to state  $x_0$  has the same probability as the time reversed path, for all initial states  $x_0 \in \mathcal{X}$ . That is, for any  $n \in \mathbb{N}$  and state vector  $x \in \mathcal{X}^n$*

$$P_{x_0x_1}P_{x_1x_2}\cdots P_{x_nx_0} = P_{x_0x_n}P_{x_nx_{n-1}}\cdots P_{x_1x_0}. \quad (4)$$

*Proof.* The detailed balance equation for a time reversible Markov process  $X$  implies that  $P_{x_0x_1}P_{x_1x_2}\cdots P_{x_nx_0} = P_{x_0x_n}P_{x_nx_{n-1}}\cdots P_{x_1x_0}$ . Conversely, if (4) holds for any non-negative integer  $n \in \mathbb{N}$ , then for any states  $x_0, y \in \mathcal{X}$ , we have

$$(P^{n+1})_{x_0y}P_{yx_0} = \sum_{x_1, x_2, \dots, x_n} P_{x_0x_1}\cdots P_{x_ny}P_{yx_0} = \sum_{x_1, x_2, \dots, x_n} P_{x_0y}P_{yx_n}\cdots P_{x_1x_0} = P_{x_0y}(P^{n+1})_{yx_0}.$$

Taking the limit  $n \rightarrow \infty$  and noticing that  $\lim_{n \rightarrow \infty} (P^n)_{xy} = \pi_y$  for all  $x, y \in \mathcal{X}$ , we observe that  $X$  is a time-reversible process.  $\square$

## 1.2 Reversible Processes

**Corollary 1.9.** *A stationary homogeneous Markov process  $X : \Omega \rightarrow \mathcal{X}^{\mathbb{R}}$  with generator matrix  $Q \in \mathbb{R}^{\mathcal{X} \times \mathcal{X}}$  is time reversible iff there exists a probability distribution  $\pi \in \mathcal{M}(\mathcal{X})$ , that satisfies the detailed balanced conditions*

$$\pi_x Q_{xy} = \pi_y Q_{yx}, \quad x, y \in \mathcal{X}. \quad (5)$$

When such a distribution  $\pi$  exists, it is the invariant distribution of the process.

**Definition 1.10.** Let  $X : \Omega \rightarrow \mathcal{X}^{\mathbb{R}}$  be a stationary homogeneous Markov process with stationary distribution  $\pi \in \mathcal{M}(\mathcal{X})$  and the generator matrix  $Q \in \mathbb{R}^{\mathcal{X} \times \mathcal{X}}$ . The **probability flux** from state  $x$  to state  $y$  is defined as  $\lim_{t \rightarrow \infty} \frac{N_t^{xy}}{t}$ , where  $N_t^{xy} \triangleq \sum_{n \in \mathbb{N}} \mathbb{1}_{\{S_n \leq t, X_n = y, X_{n-1} = x\}}$  denotes the total number of transitions from state  $x$  to state  $y$  in the time duration  $(0, t]$ .

**Lemma 1.11.** *For a time-homogeneous CTMC  $X$ , the probability flux from state  $x$  to state  $y$  is  $\pi_x Q_{xy} = \lim_{t \rightarrow \infty} \frac{N_t^{xy}}{t}$ .*

*Proof.* Let  $X_0 = x$  and  $\tau_x^+(k)$  be the  $k$ th visiting time to state  $x$ . It follows that  $\tau_x^+ : \Omega \rightarrow \mathbb{R}_+^{\mathbb{N}}$  is a renewal sequence. We consider a reward process  $N_t^{xy}$ . We let  $N^{xy}(k)$  denote the total number of transitions from state  $x$  to state  $y$  in the  $k$ th inter-renewal duration. Then, we observe that  $\mathbb{E}_x N^{xy}(k) = p_{xy}$  and recall that  $\mathbb{E}_x \tau_x^+(1) = \frac{1}{\pi_x \nu_x}$ . From the renewal reward process, we obtain

$$\lim_{t \rightarrow \infty} \frac{N_t^{xy}}{t} = \frac{\mathbb{E}_x N^{xy}(1)}{\mathbb{E}_x \tau_x^+(1)} = \pi_x \nu_x p_{xy} = \pi_x Q_{xy}. \quad \square$$

**Lemma 1.12.** *For a stationary homogeneous Markov process  $X : \Omega \rightarrow \mathcal{X}^{\mathbb{R}}$ , probability flux balances across a cut  $A \subseteq \mathcal{X}$ , that is*

$$\sum_{y \notin A} \sum_{x \in A} \pi_x Q_{xy} = \sum_{x \in A} \sum_{y \notin A} \pi_y Q_{yx}.$$

*Proof.* From the row sum of generator matrix being zero, we get  $\sum_{y \in \mathcal{X}} Q_{xy} = 0$  for all  $x \in \mathcal{X}$ . In particular, we get  $\sum_{y \in \mathcal{X}} \sum_{x \in A} \pi_x Q_{xy} = 0$ . Further, the global balance condition is  $\pi Q = 0$ , i.e.  $\sum_{y \in \mathcal{X}} \pi_y Q_{yx} = 0$  for all  $x \in \mathcal{X}$ . In particular, we get  $\sum_{x \in A} \sum_{y \in \mathcal{X}} \pi_y Q_{yx} = 0$ . Further, we have the following identity from change of variables,  $\sum_{y \in A} \sum_{x \in A} \pi_x Q_{xy} = \sum_{y \in A} \sum_{x \in A} \pi_y Q_{yx}$ . Subtracting the second identity from the first, we get the result.  $\square$

**Corollary 1.13.** *For  $A = \{x\}$ , the above equation reduces to the full balance equation for state  $x$ , i.e.,*

$$\sum_{y \neq x} \pi_x Q_{xy} = \sum_{y \neq x} \pi_y Q_{yx}.$$

**Example 1.14.** We define two non-negative sequences birth and death rates denoted by  $\lambda \in \mathbb{R}_+^{\mathbb{Z}_+}$  and  $\mu \in \mathbb{R}_+^{\mathbb{N}}$ . A Markov process  $X : \Omega \rightarrow \mathbb{Z}_+^{\mathbb{R}_+}$  is called a *birth-death process* if its infinitesimal transition probabilities satisfy

$$P_{n,n+m}(h) = (1 - \lambda_n h - \mu_n h \mathbb{1}_{\{n \neq 0\}} - o(h)) \mathbb{1}_{\{m=0\}} + \lambda_n h \mathbb{1}_{\{m=1\}} + \mu_n h \mathbb{1}_{\{m=-1\}} \mathbb{1}_{\{n \neq 0\}} + o(h).$$

We say  $f(h) = o(h)$  if  $\lim_{h \rightarrow 0} \frac{f(h)}{h} = 0$ . In other words, a birth-death process is a CTMC with generator of the form

$$Q = \begin{pmatrix} -\lambda_0 & \lambda_0 & 0 & 0 & 0 & \dots \\ \mu_1 & -(\lambda_1 + \mu_1) & \lambda_1 & 0 & 0 & \dots \\ 0 & \mu_2 & -(\lambda_2 + \mu_2) & \lambda_2 & 0 & \dots \\ 0 & 0 & \mu_3 & -(\lambda_3 + \mu_3) & \lambda_3 & \dots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix}.$$

**Proposition 1.15.** *An ergodic birth-death process in steady-state is time-reversible.*

*Proof.* Since the process is stationary, the probability flux must balance across any cut of the form  $A = \{0, 1, 2, \dots, n\}$ , for  $n \in \mathbb{Z}_+$ . But, this is precisely the equation  $\pi_n \lambda_n = \pi_{n+1} \mu_{n+1}$  since there are no other transitions possible across the cut. So the process is time-reversible.  $\square$

In fact, the following, more general, statement can be proven using similar ideas.

**Proposition 1.16.** *Consider an irreducible ergodic CTMC  $X : \Omega \rightarrow \mathcal{X}^{\mathbb{R}}$  on a countable state space  $\mathcal{X}$  with generator matrix  $Q \in \mathbb{R}^{\mathcal{X} \times \mathcal{X}}$  having the following property. For any pair of states  $x \neq y \in \mathcal{X}$ , the transition graph has a unique path  $x = x_0 \rightarrow x_1 \rightarrow \dots \rightarrow x_{n(x,y)} = y$  and  $y = x_{n(x,y)} \rightarrow x_{n-1} \rightarrow \dots \rightarrow x_0 = x$  of distinct states. Then the CTMC in steady-state is time reversible.*

*Proof.* Let the stationary distribution of  $X$  be  $\pi \in \mathcal{M}(\mathcal{X})$ , such that  $\pi Q = 0$ . Let  $x \neq y \in \mathcal{X}$ , then either  $Q_{xy} = Q_{yx} = 0$  or  $Q_{xy} Q_{yx} > 0$ . In the former case, the detailed balance equation is satisfied trivially for the pair  $(x, y)$ . In the latter case, we define a set

$$A_x \triangleq \{z \in \mathcal{X} : z \text{ connected to } x \text{ via } y\}.$$

Clearly,  $x \in A_x$  and  $y \notin A_x$ , and  $Q_{zw} = Q_{wz} = 0$  for all  $w \in A_x \setminus \{x\}$  and  $z \in A_x^c \setminus \{y\}$ . If not, then there are two paths between  $x, y \in \mathcal{X}$  and that contradicts the hypothesis. From the probability flux balance across cuts, we obtain the detailed balance equation

$$\pi_x Q_{xy} = \pi_y Q_{yx}.$$

Since the choice of states  $x, y \in \mathcal{X}$  was arbitrary, the result follows.  $\square$

**Exercise 1.17.** Prove Corollary 1.4 and Corollary 1.9 from Theorem 1.3.