

# Lecture-20: Reversibility

## 1 Introduction

**Definition 1.1.** A stochastic process  $X : \Omega \rightarrow \mathcal{X}^{\mathbb{R}}$  is **time reversible** if the vector  $(X_{t_1}, \dots, X_{t_n})$  has the same distribution as  $(X_{\tau-t_1}, \dots, X_{\tau-t_n})$  for all finite positive integers  $n$ , time instants  $t_1 < t_2 < \dots < t_n$  and shifts  $\tau \in \mathbb{R}$ .

**Lemma 1.2.** A time reversible process is stationary.

*Proof.* Since  $X_t$  is time reversible, both  $(X_{t_1}, \dots, X_{t_n})$  and  $(X_{s+t_1}, \dots, X_{s+t_n})$  have the same distribution as  $(X_{-t_1}, \dots, X_{-t_n})$  for each  $n \in \mathbb{N}$  and  $t_1 < \dots < t_n$ , by taking  $\tau = 0$  and  $\tau = -s$  respectively.  $\square$

**Definition 1.3.** The space of distributions over countable state space  $\mathcal{X}$  is denoted by

$$\mathcal{M}(\mathcal{X}) \triangleq \left\{ \alpha \in [0, 1]^{\mathcal{X}} : \langle \mathbf{1}, \alpha \rangle = \sum_{x \in \mathcal{X}} \alpha_x = 1 \right\}.$$

**Remark 1.** Stationarity means  $P \left\{ \bigcap_{i \in [n]} X_{t_i} = x_i \right\} = P \left\{ \bigcap_{i \in [n]} X_{s+t_i} = x_i \right\}$  for all  $s$

**Theorem 1.4.** A stationary homogeneous Markov process  $X : \Omega \rightarrow \mathcal{X}^{\mathbb{R}}$  with countable state space  $\mathcal{X} \subseteq \mathbb{R}$  and probability transition kernel  $P : \mathbb{R}_+ \rightarrow [0, 1]^{\mathcal{X} \times \mathcal{X}}$  is time reversible iff there exists a probability distribution  $\pi \in \mathcal{P}(\mathcal{X})$ , that satisfy the detailed balanced conditions

$$\pi_x P_{xy}(t) = \pi_y P_{yx}(t) \text{ for all } x, y \in \mathcal{X} \text{ and times } t \in \mathbb{R}_+. \quad (1)$$

When such a distribution  $\pi$  exists, it is the equilibrium distribution of the process.

*Proof.* We assume that the process  $X$  is time reversible, and hence stationary. We denote the stationary distribution by  $\pi$ , and by time reversibility of  $X$ , we have

$$P_{\pi} \{X_{t_1} = x, X_{t_2} = y\} = P_{\pi} \{X_{t_2} = x, X_{t_1} = y\},$$

for  $\tau = t_2 + t_1$ . Hence, we obtain the detailed balanced conditions in Eq. (??). Conversely, let  $\pi$  be the distribution that satisfies the detailed balanced conditions in Eq. (??), then summing up both sides over  $y \in \mathcal{X}$ , we see that  $\pi$  is the equilibrium distribution.

Let  $(x_1, \dots, x_m) \in \mathcal{X}^m$ , then applying detailed balanced equations in Eq. (??) repeatedly, we can write

$$\pi(x_1) P_{x_1 x_2}(t_2 - t_1) \dots P_{x_{m-1} x_m}(t_m - t_{m-1}) = \pi(x_m) P_{x_m x_{m-1}}(t_m - t_{m-1}) \dots P_{x_2 x_1}(t_2 - t_1).$$

For the homogeneous stationary Markov process  $X$ , it follows that for all  $t_0 \in \mathbb{R}_+$

$$P_{\pi} \{X_{t_1} = x_1, \dots, X_{t_m} = x_m\} = P_{\pi} \{X_{t_0} = x_m, \dots, X_{t_0+t_m-t_1} = x_1\}.$$

Since  $m \in \mathbb{N}$  and  $t_0, t_1, \dots, t_m$  were arbitrary, the time reversibility follows.  $\square$

**Corollary 1.5.** A stationary homogeneous discrete time Markov chain  $X : \Omega \rightarrow \mathcal{X}^{\mathbb{Z}}$  with transition matrix  $P \in [0, 1]^{\mathcal{X} \times \mathcal{X}}$  is time reversible iff there exists a probability distribution  $\pi \in \mathcal{P}(\mathcal{X})$ , that satisfies the detailed balanced conditions

$$\pi_x P_{xy} = \pi_y P_{yx}, \quad x, y \in \mathcal{X}. \quad (2)$$

When such a distribution  $\pi$  exists, it is the equilibrium distribution of the process.

**Corollary 1.6.** A stationary homogeneous Markov process  $X : \Omega \rightarrow \mathcal{X}^{\mathbb{R}}$  and generator matrix  $Q \in \mathbb{R}^{\mathcal{X} \times \mathcal{X}}$  is time reversible iff there exists a probability distribution  $\pi \in \mathcal{P}(\mathcal{X})$ , that satisfies the detailed balanced conditions

$$\pi_x Q_{xy} = \pi_y Q_{yx}, \quad x, y \in \mathcal{X}. \quad (3)$$

When such a distribution  $\pi$  exists, it is the equilibrium distribution of the process.

**Example 1.7 (Random walks on edge-weighted graphs).** Consider an undirected graph  $G = (\mathcal{X}, E)$  with the vertex set  $\mathcal{X}$  and the edge set  $E = \{\{x, y\} : x, y \in \mathcal{X}\}$  being a subset of unordered pairs of elements from  $\mathcal{X}$ . We say that  $y$  is a neighbor of  $x$  (and  $x$  is a neighbor of  $y$ ), if  $e = \{x, y\} \in E$  and denote  $x \sim y$ . We assume a function  $w : E \rightarrow \mathbb{R}_+$ , such that  $w_e$  is a positive number associated with each edge  $e = \{x, y\} \in E$ . Let  $X_n \in \mathcal{X}$  denote the location of a particle on one of the graph vertices at the  $n$ th time-step. Consider the following random discrete time movement of a particle on this graph from one vertex to another. If the particle is currently at vertex  $x$  then it will next move to vertex  $y$  with probability

$$P_{xy}^g \triangleq P(\{X_{n+1} = y\} | \{X_n = x\}) = \frac{w_e}{\sum_{f:x \in f} w_f} \mathbb{1}_{\{e=\{x,y\}\}}.$$

The Markov chain  $X : \Omega \rightarrow \mathcal{X}^{\mathbb{N}}$  describing the sequence of vertices visited by the particle is a random walk on an undirected edge-weighted graph. Google's PageRank algorithm, to estimate the relative importance of webpages, is essentially a random walk on a graph!

**Proposition 1.8.** Consider an irreducible homogeneous Markov chain that describes the random walk on an edge weighted graph with a finite number of vertices. In steady state, this Markov chain is time reversible with stationary probability of being in a state  $x \in \mathcal{X}$  given by

$$\pi_x = \frac{\sum_{f:x \in f} w_f}{2 \sum_{g \in E} w_g}. \quad (4)$$

*Proof.* Using the definition of transition probabilities for this Markov chain and the given distribution  $\pi$  defined in (4), we notice that

$$\pi_x P_{xy}^g = \frac{w_e}{\sum_{f \in E} w_f} \mathbb{1}_{\{e=\{x,y\}\}}, \quad \pi_y P_{yx}^g = \frac{w_e}{\sum_{f \in E} w_f} \mathbb{1}_{\{e=\{x,y\}\}}.$$

Hence, the detailed balance equation for each pair of states  $x, y \in \mathcal{X}$  is satisfied, and the result follows.  $\square$

We can also show the following *dual* result.

**Lemma 1.9.** Let  $X : \Omega \rightarrow \mathcal{X}^{\mathbb{Z}^+}$  be a time reversible Markov chain on a finite state space  $\mathcal{X}$  and transition probability matrix  $P \in [0, 1]^{\mathcal{X} \times \mathcal{X}}$ . Then, there exists a random walk on a weighted, undirected graph  $G$  with the same transition probability matrix  $P$ .

*Proof.* We create a graph  $G = (\mathcal{X}, E)$ , where  $E = \{\{x, y\} : x, y \in \mathcal{X}, P_{xy} > 0\}$ . For the stationary distribution  $\pi : \mathcal{X} \rightarrow [0, 1]$  for the Markov chain  $X$ , we set the edge weights

$$w_{\{x,y\}} \triangleq \pi_x P_{xy} = \pi_y P_{yx},$$

With this choice of weights, it is easy to check that  $w_x = \sum_{f:x \in f} w_f = \pi_x$ , and the transition matrix associated with a random walk on this graph is exactly  $P$  with  $P_{xy}^g = \frac{w_{\{x,y\}}}{w_x} = P_{xy}$ .  $\square$

### Is every Markov chain time reversible?

1. If the process is not stationary, then no. To see this, we observe that

$$P\{X_{t_1} = x_1, X_{t_2} = x_2\} = \nu_{t_1}(x_1) P_{x_1 x_2}(t_2 - t_1), \quad P\{X_{\tau-t_2} = x_2, X_{\tau-t_1} = x_1\} = \nu_{\tau-t_2}(x_2) P_{x_2 x_1}(t_2 - t_1).$$

If the process is not stationary, the two probabilities can't be equal for all times  $\tau, t_1, t_2$  and states  $x_1, x_2 \in \mathcal{X}$ .

2. If the process is stationary, then it is still not true in general. Suppose we want to find a stationary distribution  $\alpha \in \mathcal{M}(\mathcal{X})$  that satisfies the detailed balance equations  $\alpha_x P_{xy} = \alpha_y P_{yx}$  for all states  $x, y \in \mathcal{X}$ . For any arbitrary Markov chain  $X$ , one may not end up getting any solution. To see this consider a state  $z \in \mathcal{X}$  such that  $P_{xy} P_{yz} > 0$ . Time reversibility condition implies that

$P_\alpha \{X_1 = x, X_2 = y, X_3 = z\} = P_\alpha \{X_1 = z, X_2 = y, X_3 = z\}$ , and hence

$$\frac{\alpha_x}{\alpha_z} = \frac{P_{zy}P_{yx}}{P_{xy}P_{yz}} \neq \frac{P_{zx}}{P_{xz}}.$$

Thus, we see that a necessary condition for time reversibility is  $P_{xy}P_{yz}P_{zx} = P_{xz}P_{zy}P_{yx}$  for all  $x, y, z \in \mathcal{X}$ .

**Theorem 1.10 (Kolmogorov's criterion for time reversibility of Markov chains).** *A stationary homogeneous Markov chain  $X : \Omega \rightarrow \mathcal{X}^{\mathbb{Z}}$  is time reversible if and only if starting in state  $x \in \mathcal{X}$ , any path back to state  $x$  has the same probability as the time reversed path, for all initial states  $x \in \mathcal{X}$ . That is, for all  $n \in \mathbb{N}$  and states  $(x_1, \dots, x_n) \in \mathcal{X}^n$*

$$P_{xx_1}P_{x_1x_2} \dots P_{x_nx} = P_{xx_n}P_{x_nx_{n-1}} \dots P_{x_1x}.$$

*Proof.* As detailed balance implies that  $P_{xx_1}P_{x_1x_2} \dots P_{x_nx} = P_{xx_n}P_{x_nx_{n-1}} \dots P_{x_1x}$ . Also, as detailed balance is necessary for time reversibility,  $P_{xx_1}P_{x_1x_2} \dots P_{x_nx} = P_{xx_n}P_{x_nx_{n-1}} \dots P_{x_1x}$  is necessary for time reversibility.

To see the sufficiency part, fix states  $x, y \in \mathcal{X}$ . For any non-negative integer  $n \in \mathbb{Z}_+$ , we compute

$$(P^{n+1})_{xy}P_{yx} = \sum_{x_1, x_2, \dots, x_n} P_{xx_1} \dots P_{x_ny}P_{yx} = \sum_{x_1, x_2, \dots, x_n} P_{xy}P_{yx_n} \dots P_{x_1x} = P_{xy}(P^{n+1})_{yx}.$$

Taking the limit  $n \rightarrow \infty$  and noticing that  $\lim_{n \rightarrow \infty} (P^n)_{xy} = \pi_y$  for all  $x, y \in \mathcal{X}$ , we get the desired result by appealing to Theorem ??.

## 1.1 Reversible Processes

**Definition 1.11.** Let  $X : \Omega \rightarrow \mathcal{X}^{\mathbb{R}}$  be a stationary homogeneous Markov process with stationary distribution  $\pi \in \mathcal{M}(\mathcal{X})$  and the generator matrix  $Q \in \mathbb{R}^{\mathcal{X} \times \mathcal{X}}$ . The **probability flux** from state  $x$  to state  $y$  is defined as  $\lim_{t \rightarrow \infty} \frac{N_t^{xy}}{N_t}$ , where  $N_t^{xy} = \sum_{n \in \mathbb{N}} \mathbb{1}_{\{S_n \leq t, X_n = y, X_{n-1} = x\}}$  and  $N_t = \sum_{n \in \mathbb{N}} \mathbb{1}_{\{S_n \leq t\}}$  respectively denote the total number of transitions from state  $x$  to state  $y$  and the total number of transition in time duration  $(0, t]$ .

**Lemma 1.12.** *The probability flux from state  $x$  to state  $y$  is*

$$\pi_x Q_{xy} = \lim_{t \rightarrow \infty} \frac{N_t^{xy}}{N_t}.$$

**Lemma 1.13.** *For a stationary homogeneous Markov process  $X : \Omega \rightarrow \mathcal{X}^{\mathbb{R}}$ , probability flux balances across a cut  $A \subseteq \mathcal{X}$ , that is*

$$\sum_{y \notin A} \sum_{x \in A} \pi_x Q_{xy} = \sum_{x \in A} \sum_{y \notin A} \pi_y Q_{yx}.$$

*Proof.* From global balance condition  $\pi Q = 0$ , we get  $\sum_{y \in A} \sum_{x \in \mathcal{X}} \pi_x Q_{xy} = \sum_{x \in A} \sum_{y \in \mathcal{X}} \pi_y Q_{yx} = 0$ . Further, we have the following identity  $\sum_{y \in A} \sum_{x \in A} \pi_x Q_{xy} = \sum_{y \in A} \sum_{x \in A} \pi_y Q_{yx}$ . Subtracting the second identity from the first, we get the result.

**Corollary 1.14.** *For  $A = \{x\}$ , the above equation reduces to the full balance equation for state  $x$ , i.e.,*

$$\sum_{y \neq x} \pi_x Q_{xy} = \sum_{y \neq x} \pi_y Q_{yx}.$$

**Example 1.15.** We define two non-negative sequences birth and death rates denoted by  $\lambda \in \mathbb{R}_+^{\mathbb{Z}^+}$  and  $\mu \in \mathbb{R}_+^{\mathbb{N}}$ . A Markov process  $X : \Omega \rightarrow \mathbb{Z}_+^{\mathbb{R}^+}$  is called a *birth-death process* if its infinitesimal transition probabilities satisfy

$$P_{n, n+m}(h) = (1 - \lambda_n h - \mu_n h \mathbb{1}_{\{n \neq 0\}} - o(h)) \mathbb{1}_{\{m=0\}} + \lambda_n h \mathbb{1}_{\{m=1\}} + \mu_n h \mathbb{1}_{\{m=-1\}} \mathbb{1}_{\{n \neq 0\}} + o(h).$$

We say  $f(h) = o(h)$  if  $\lim_{h \rightarrow 0} f(h)/h = 0$ . In other words, a birth-death process is any CTMC with generator of the form

$$Q = \begin{pmatrix} -\lambda_0 & \lambda_0 & 0 & 0 & 0 & \dots \\ \mu_1 & -(\lambda_1 + \mu_1) & \lambda_1 & 0 & 0 & \dots \\ 0 & \mu_2 & -(\lambda_2 + \mu_2) & \lambda_2 & 0 & \dots \\ 0 & 0 & \mu_3 & -(\lambda_3 + \mu_3) & \lambda_3 & \dots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix}.$$

**Proposition 1.16.** *An ergodic birth-death process in steady-state is time-reversible.*

*Proof.* Since the process is stationary, the probability flux must balance across any cut of the form  $A = \{0, 1, 2, \dots, n\}$ , for  $n \in \mathbb{Z}_+$ . But, this is precisely the equation  $\pi_n \lambda_n = \pi_{n+1} \mu_{n+1}$  since there are no other transitions possible across the cut. So the process is time-reversible.  $\square$

In fact, the following, more general, statement can be proven using similar ideas.

**Proposition 1.17.** *Consider an ergodic CTMC  $X : \Omega \rightarrow \mathcal{X}^{\mathbb{R}}$  on a countable state space  $\mathcal{X}$  with generator matrix  $Q \in \mathbb{R}^{\mathcal{X} \times \mathcal{X}}$  having the following property. For any pair of states  $x \neq y \in \mathcal{X}$ , there is a unique path  $x = x_0 \rightarrow x_1 \rightarrow \dots \rightarrow x_n(x,y) = y$  of distinct states having positive probability. Then the CTMC in steady-state is time reversible.*

*Proof.* Let the stationary distribution of  $X$  be  $\pi \in \mathcal{M}(\mathcal{X})$ , such that  $\pi Q = 0$ . For a finite  $n \in \mathbb{N}$ , increasing time instants  $t_1 < \dots < t_n$ , and states  $x, x_1, \dots, x_{n-1}, y \in \mathcal{X}$ , we compute the probability

$$P_\pi \{X_{t_0} = x, X_{t_1} = x_1, \dots, X_{t_n} = y\} = \pi_x P_{xx_1}(t_1 - t_0) \dots P_{x_{n-1}x_n}(t_n - t_{n-1}).$$

For the same  $n \in \mathbb{N}$ , increasing time instants  $t_1 < \dots < t_n$ , and states  $x, x_1, \dots, x_{n-1}, y \in \mathcal{X}$ , and shift  $\tau \in \mathbb{R}$ , we compute the probability

$$P_\pi \{X_{\tau-t_n} = y, X_{\tau-t_{n-1}} = x_{n-1}, \dots, X_{\tau-t_0} = x\} = \pi_y P_{yx_{n-1}}(t_n - t_{n-1}) \dots P_{x_1x}(t_1 - t_0).$$

We can write LHS as

$$\pi$$

$\square$