

E2 205 Error-Control Coding

Lecture 10

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1 Maximum Likelihood Decoding

Setting

Consider transmitting of a binary codeword over a binary input channel as in Fig 1. Also Consider an AWGN channel as in Fig 2. Each w_i is *iid*. The coding scheme employed is Binary Antipodal.

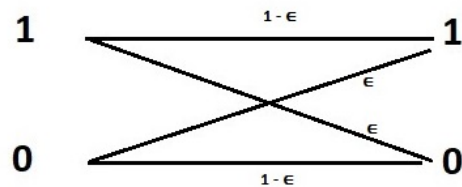


Figure 1: Binary Symmetric Channel

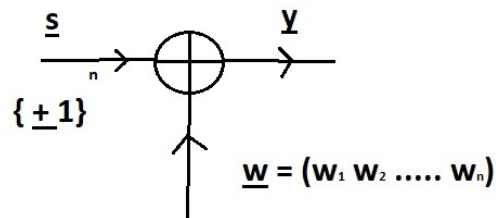


Figure 2: AWGN Channel

Let \mathcal{C} be a binary code and let $M = |\mathcal{C}|$. Let y^n be the space of received vectors. The role of decoder is to partition y^n into M regions, one for each code word as in Fig 3 below.

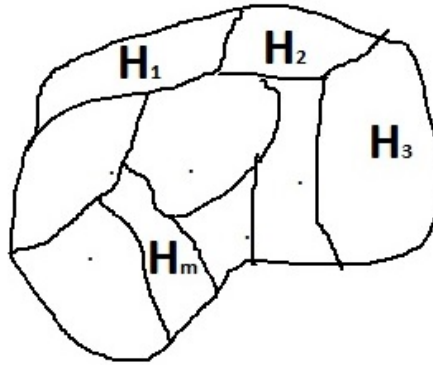


Figure 3: Received Vector Space Partitioning

If $\vec{y} \in H_i$, the decoder declares the estimated (decoded) codeword $\hat{c} = \vec{c}_i$ where

$$\mathcal{C} = \{\vec{c}_i : 1 \leq i \leq M\}. \quad (1)$$

Let ε denote the codeword error event i.e. event of decoding to an incorrect codeword. Then, ε^c denotes the correct decoding event.

$$P(\varepsilon^c) = \sum_{i=1}^n P(\vec{c}_i)P(\varepsilon^c|\vec{c}_i)$$

$$\begin{aligned}
P(\varepsilon^c) &= \sum_{i=1}^n P(\vec{c}_i) P(\vec{y} \in H_i | \vec{c}_i) \\
&= \sum_{i=1}^n P(\vec{c}_i) \int_{H_i} P(\vec{y} | \vec{c}_i) dy \\
&= \sum_{i=1}^n P(\vec{c}_i) \int_{y^n} P(\vec{y} | \vec{c}_i) \mathbb{1}_i(\vec{y}) dy, \text{ where } \mathbb{1}_i(\vec{y}) = \{1, \text{ if } \vec{y} \in H_i \text{ and } 0 \text{ elsewhere}\} \\
&= \int_{y^n} \left[\sum_{i=1}^n P(\vec{c}_i) P(\vec{y} | \vec{c}_i) \mathbb{1}_i(\vec{y}) dy \right]
\end{aligned}$$

Therefore, $P(\vec{c}_i) P(\vec{y} | \vec{c}_i)$ is the contribution (for a given \vec{y}) to the problem of correct decoding if $\vec{y} \in H_i$. It follows that, to minimise the $P(\varepsilon)$ given by $\vec{y} \in y^n$, we assign $\vec{y} \in H_i$ such that, $P(\vec{c}_i) P(\vec{y} | \vec{c}_i) \geq P(\vec{c}_j) P(\vec{y} | \vec{c}_j)$, $i \neq j$.

This is known as Minimum Probability of Error Decoding (MPE).

If $P(\vec{c}_i) = P(\vec{c}_j) = \frac{1}{M}$, i.e. if the codewords are equally likely, the above equation reduces to $P(\vec{y} | \vec{c}_i) \geq P(\vec{y} | \vec{c}_j)$, which is called as the Maximum Likelihood Decoding.

Lemma 1 *Over BSC as in Figure 1, MLD reduces to minimum distance decoding (MDD).*

Proof: Let $d_H(\vec{y}, \vec{c}_i) = d$.

$$P(\vec{y} | \vec{c}_i) = \varepsilon^d (1 - \varepsilon)^{n-d} = (1 - \varepsilon)^n \left(\frac{\varepsilon}{1-\varepsilon}\right)^d$$

$$\text{If } \varepsilon < 0.5, \frac{\varepsilon}{1-\varepsilon} < 1$$

$$\implies P(\vec{y} | \vec{c}_i) \text{ is maximized by minimizing } d_H(\vec{y}, \vec{c}_i)$$

In case of AWGN channel,

$$P(\vec{y} | \vec{c}_i) = \prod_{j=1}^n \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(\frac{-1}{2\sigma^2} (y_j - c_{ij})^2\right),$$

where c_{ij} is the j^{th} component of \vec{c}_i . Thus MLD reduces to minimum Euclidean distance decoding given by

$$d_E^2(y, c_i) = \sum_{i=1}^n (y_i - c_{ij})^2 \quad (2)$$

2 Syndrome Decoding(Slepian Wolf Decoding)

Consider BSC and let the code used be linear code. The rule followed in MLD is to find \vec{c}_i such that $d_H(\vec{y}, \vec{c}_i)$ is minimum.

$$d_H(\vec{y}, \vec{c}_i) = \{W_H(\vec{y} + \vec{c}_i) \mid \vec{c} \in \mathcal{C}\}$$

So, equivalently, we are looking for \vec{c}_i such that,

$$W_H(\vec{y} + \vec{c}_i) = \min \{W_H(\vec{y} + \vec{c}_j) \mid \vec{c}_j \in \mathcal{C}\} = \min_z \{W_H(\vec{z}) \mid \vec{z} \in \vec{y} + \mathcal{C}\}$$

Here, $\vec{y} + \mathcal{C}$ is a coset of code \mathcal{C} . Now having found such a \vec{z} , for some i , we have

$$\hat{c} = \vec{c}_i = \vec{y} + \vec{z}$$

Hence, the decoding algorithm is as follows

- (a) Given \vec{y} , form $\vec{y} + \mathcal{C}$
- (b) Look for least Hamming weight vector \vec{z} in $\vec{y} + \mathcal{C}$
- (c) $\hat{c} = \vec{y} + \vec{z}$

Lemma Let \mathcal{C} be a $[n, k]$ linear code and H be its p-c matrix. Then, there exists a one-to-one correspondence between the sets $\{\vec{y} + \mathcal{C}\}$ and \mathbb{F}_2^{n-k} , given by $H\vec{y} \in \mathbb{F}_2^{n-k}$.

Proof: Clearly collection of all $\vec{y}_i + \mathcal{C}$ is of size 2^{n-k} .

$$\begin{aligned} \text{If } \vec{y}_1 + \mathcal{C} &= \vec{y}'_1 + \mathcal{C} \\ \implies \vec{y}_1 + \vec{c}_1 &= \vec{y}'_1 + \vec{c}_2 \\ \implies H\vec{y}_1 + H\vec{c}_1 &= H\vec{y}'_1 + H\vec{c}_2 \\ \implies H\vec{y}_1 &= H\vec{y}'_1 \end{aligned}$$

It remains to show that the mapping is H.

$$Hy_1 = Hy_2 \implies H(y_1 + y_2) = 0$$

$$\begin{aligned} \implies y_1 + y_2 &\in \mathcal{C} \\ \implies y_1 &= y_2 + \vec{c}, \vec{c} \in \mathcal{C} \\ \implies y_1 + \mathcal{C} &= y_2 + \mathcal{C} \end{aligned}$$

For example consider $\mathcal{C}[n,k,d] = [4,2,2]$

$$G = H = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix}$$

i.e. a self dual code

let $\mathcal{C} = \{\vec{c}_1, \vec{c}_2, \vec{c}_3, \vec{c}_4\}$

$$c_1 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$c_2 = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}$$

$$c_3 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix}$$

$$c_4 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

Table 1: Standard Array Decoding

\vec{c}_1^T	\vec{c}_2^T	\vec{c}_3^T	\vec{c}_4^T	\vec{s}^T	
0 0 0 0	1 0 1 0	0 1 0 1	1 1 1 1	0 0	\mathcal{C}
0 0 0 1	1 0 1 1	0 1 0 0	1 1 1 0	0 1	$\mathcal{C} + 0 0 0 1$
0 0 1 0	1 0 0 0	0 1 1 1	1 1 0 1	1 0	$\mathcal{C} + 0 0 1 0$
0 0 1 1	1 0 0 1	0 1 1 0	1 1 0 0	1 1	$\mathcal{C} + 0 0 1 1$

The first column in the above table is known as the Coset Leader. Also, We have

$$2t_c + 1 \leq d_{min} = 2 \implies t_c = 0$$

$$\text{Syndrome } \vec{s} = H\vec{y}$$

Decoding Technique

Suppose

$$y = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}$$

$$Hy = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$e = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}$$

$$c = y + e = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix}$$

Clearly, only those error patterns corresponding to coset leaders (first column of Table 1) can be correctly decoded.

2.1 Performance of Standard Array Decoder

Let \vec{e} be the actual error pattern.

$$\begin{aligned} \therefore \vec{y} &= \vec{c} + \vec{e} \\ \vec{s} = H\vec{y} &= H(\vec{c} + \vec{e}) = H\vec{e} \end{aligned}$$

\therefore Syndrome associated with \vec{y} is same as that associated with \vec{e} .

Let \hat{e} be the coset leader associated with syndrome $\vec{s} = H\vec{e}$.

$$\hat{c} = \vec{y} + \hat{e} = \vec{c} + \vec{e} + \hat{e}$$

\implies Decoding is correct only if $\vec{e} = \hat{e}$ i.e. iff the error pattern is coset Leader.

3 Reed Muller Codes

Reed Muller Codes are based on Boolean Functions. A Boolean function f in binary multivariables is a mapping

$$f: \begin{bmatrix} X_1 \\ X_2 \\ \cdot \\ \cdot \\ X_m \end{bmatrix} \rightarrow \mathbb{F}_2$$

For example the truth table as follows is an example of Boolean Function.

Table 2: Truth Table for X_1, X_2 and X_3

X_1	$X_2 \ X_3 = 0 \ 0$	$X_2 \ X_3 = 0 \ 1$	$X_2 \ X_3 = 1 \ 1$	$X_2 \ X_3 = 1 \ 0$
0	0	1	1	0
1	1	1	1	1

Clearly, from Table 2, 2^{2^n} boolean functions are possible with n variables ($n = 3$ in Table 2). Thus there exists a one-to-one mapping from set of all boolean functions to the set of all truth tables. i.e. given a boolean function, the corresponding truth table can be deduced.

Every boolean function has a unique representation as a multivariate polynomial in n-binary variables over \mathbb{F}_2 by Lagrange Interpolation as

$$f(X_1, X_2, \dots, X_m) = \sum_{a_1} \sum_{a_2} \dots \sum_{a_m} f(a_1, a_2, \dots, a_m) \prod_{i=1}^m (X_i + a_i + 1)$$

This is called as the Reed Muller Canonical expansion of Boolean function. For example consider table 3 below.

Table 3: Truth Table for X_1, X_2 and X_3

X_1	$X_2 \ X_3 = 0 \ 0$	$X_2 \ X_3 = 0 \ 1$	$X_2 \ X_3 = 1 \ 1$	$X_2 \ X_3 = 1 \ 0$
0	0	1	0	0
1	0	0	1	0

$$g(X_1 X_2 X_3) = (X_1 + 1)(X_2 + 1)(X_3) + X_1 X_2 X_3 = X_3 + X_3 X_1 + X_3 X_2 + X_3 X_1 X_2 + X_1 X_2 X_3$$

$$\implies g(X_1 X_2 X_3) = X_3 + X_1 X_3 + X_2 X_3$$

Clearly, the degree of the monomial $X_{i_1} X_{i_2} X_{i_3} \dots X_{i_r}$ is r. The degree of a Boolean function is the largest degree of a monomial in its Reed Muller Canonical Expansion.

For $(X_1, X_2, \dots, X_m) \in \{0, 1\}^m$, we have $\sum_X f(X_1, X_2, \dots, X_m) = \sum_X (\sum_e a_e X^e) = \sum_e a_e (\sum_X X^e) = \{1, \text{ iff } a_{1111} = 1 \text{ and } 0, \text{ elsewhere}\}$.

For example, $\sum_{X_1 X_2 X_3} (X_3 + X_1 X_2 + X_2 X_3) = \sum_{X_1 X_2 X_3} X_3 + \sum_{X_1 X_2 X_3} X_1 X_2 + \sum_{X_1 X_2 X_3} X_2 X_3 = 4 + 2 + 2 = 0$.