

- Empirical risk minimization
- Stochastic approximation of the gradient
 - unbiasedness
 - role of variance
- Lower bound $\underline{g}_t^\top (\underline{x}_t - \underline{x}^*)$?

Wed. 20th 18:00 - 19:00 hrs (TA Session)

Recall gradient descent:

$$\underline{x}_{t+1} = \underline{x}_t - \eta_t \underline{g}_t$$

$$\nabla f(\underline{x}_t)$$

$$; \underline{g}_t \in \partial f(\underline{x})$$

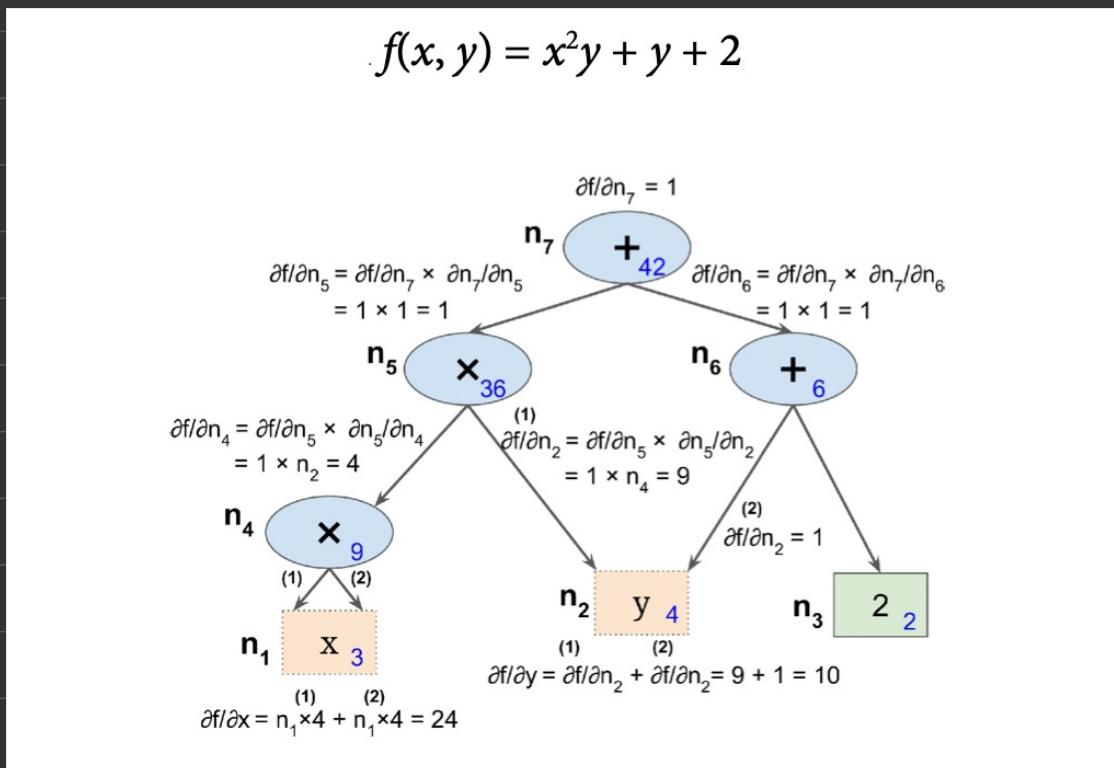
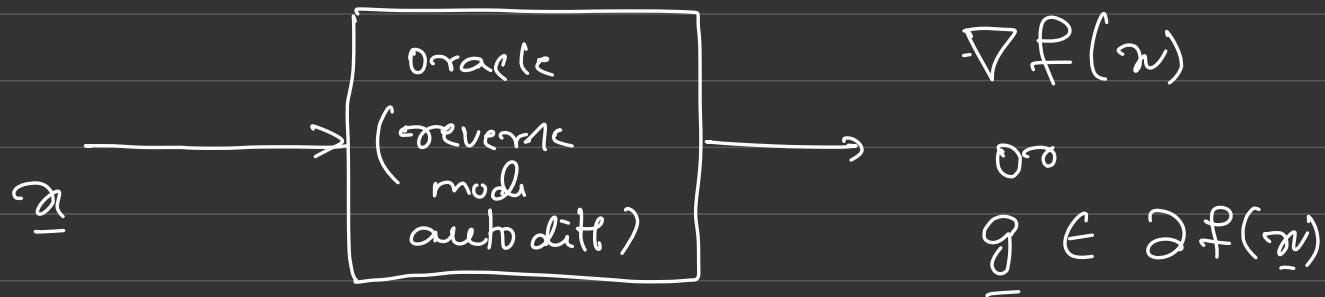
Motivation:

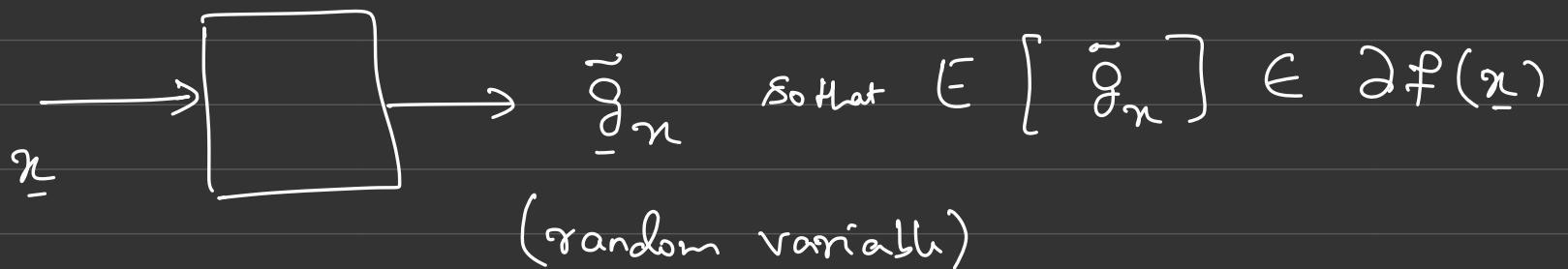
- \underline{g}_t may be expensive to compute
- complete gradient \underline{g}_t may not be available

So we use an Stochastic or approximate version of $\underline{g}_t \in \partial f(\underline{x})$

minimize $f(x)$

s.t. $x \in C$





Example:

① $\tilde{g}_n = \nabla f(\underline{x}) + \underline{w}$; \underline{w} in zero-mean noise

$$E[\tilde{g}_n] = E[\nabla f(\underline{x}) + \underline{w}] = \nabla f(\underline{x})$$

② Random coordinate descent:

$$\underline{x} \rightarrow$$
  $\rightarrow \tilde{g}_n = \begin{bmatrix} 0 \\ \vdots \\ \frac{\partial f}{\partial x_j} \\ \vdots \\ 0 \end{bmatrix} \cdot d ; \quad \underline{x} \in \mathbb{R}^d$

$$\nabla f(\underline{x}) = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \vdots \\ \frac{\partial f}{\partial x_d} \end{bmatrix}$$

$$E_j[\tilde{g}_n] = \sum_{i=1}^d d \cdot \begin{bmatrix} 0 \\ \vdots \\ \frac{\partial f}{\partial x_i} \\ \vdots \\ 0 \end{bmatrix} \cdot \frac{1}{d} = \nabla f(\underline{x})$$

③ Stochastic programming:

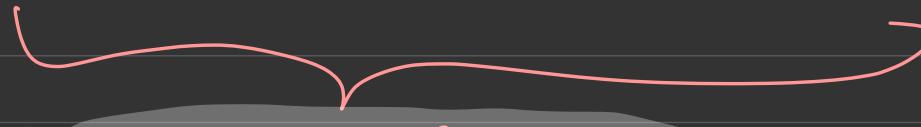
$$\underset{\underline{x} \in C}{\text{minimize}} \quad F(\underline{x}) = \underbrace{\mathbb{E} [f(\underline{x}; \xi)]}_{\begin{array}{l} \text{Expected risk} \\ \text{Population risk} \end{array}}$$

- ξ : Randomness in the problem
- If $f(\underline{x}; \xi)$ is convex for every ξ , then
 $F(\underline{x})$ is convex.

Empirical risk minimization:

Let $\{\underline{a}_i, y_i\}_{i=1}^n$ be n random data samples

ERM: minimize $\hat{F}(\underline{x}) = \frac{1}{n} \sum_{i=1}^n f(\underline{x}; \{\underline{a}_i, y_i\})$


Empirical risk

Regression problem: (more generally, any supervised learning)

$$f(\underline{x}; \{\underline{a}_i, y_i\}) = (\underline{a}_i^\top \underline{x} - y_i)^2$$

Prediction/hypothesis: $\underline{a}_i^\top \underline{x}$

minimize expected loss: draw $j \sim \text{unif}(1, 2, \dots, n)$, then

$$E_j [f(\underline{x}; \{\underline{a}_j, y_j\})] = \sum_{j=1}^n f(\underline{x}; \{\underline{a}_j, y_j\}) \cdot \frac{1}{n}$$

$$\underset{\underline{x} \in C}{\text{minimize}} \quad f(\underline{x}) = \frac{1}{n} \sum_{i=1}^n f_i(\underline{x})$$

ERM: n is the number of data points

Gradient Descent:

$$\begin{aligned}\underline{x}_{t+1} &= \underline{x}_t - \eta \nabla \left(\frac{1}{n} \sum_{i=1}^n f_i(\underline{x}_t) \right) \\ &= \underline{x}_t - \eta \cdot \frac{1}{n} \sum_{i=1}^n \nabla f_i(\underline{x}_t)\end{aligned}$$

When n is large, computing $\nabla f(\underline{x})$ is expensive (full pass over the data \rightarrow memory issues)

$$\underline{x} \xrightarrow{\hspace{1cm}} \boxed{\begin{array}{l} j \sim \text{unif}(1, \dots, n) \\ \text{oracle} \end{array}} \rightarrow \tilde{g}_{\underline{x}} = \nabla f_j(\underline{x})$$

$$E_j (\nabla f_j(\underline{x})) = \sum_{j=1}^n \nabla f_j(\underline{x}) \cdot \frac{1}{n} = \nabla f(\underline{x})$$

Stochastic gradient descent / Stochastic approximation:

$$\underline{x}_{t+1} = \underline{x}_t - \eta_t \tilde{g}(\underline{x}_t; \xi)$$

where $\tilde{g}(\underline{x}_t; \xi)$ is unbiased estimate

of $\nabla F(\underline{x}_t)$, i.e.,

$$E[\tilde{g}(\underline{x}_t; \xi)] = \nabla F(\underline{x}_t)$$

- Stochastic algorithm for finding a critical point \underline{x} that obeys $\nabla F(\underline{x}) = 0$
or for finding root of $\zeta(\underline{x}) = E[\tilde{g}(\underline{x}, \xi)]$

SGD for ERM

minimize \underline{x} $\hat{F}(\underline{x}) = \frac{1}{n} \sum_{i=1}^n F(x_i; \{x_i, y_i\})$

For $t = 0, 1, \dots$ do

choose i_t uniformly at random

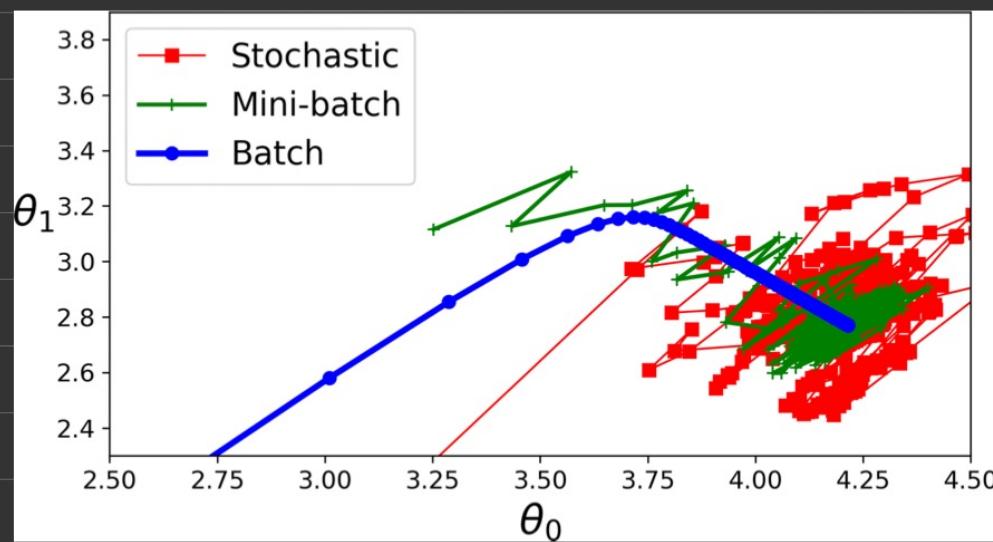
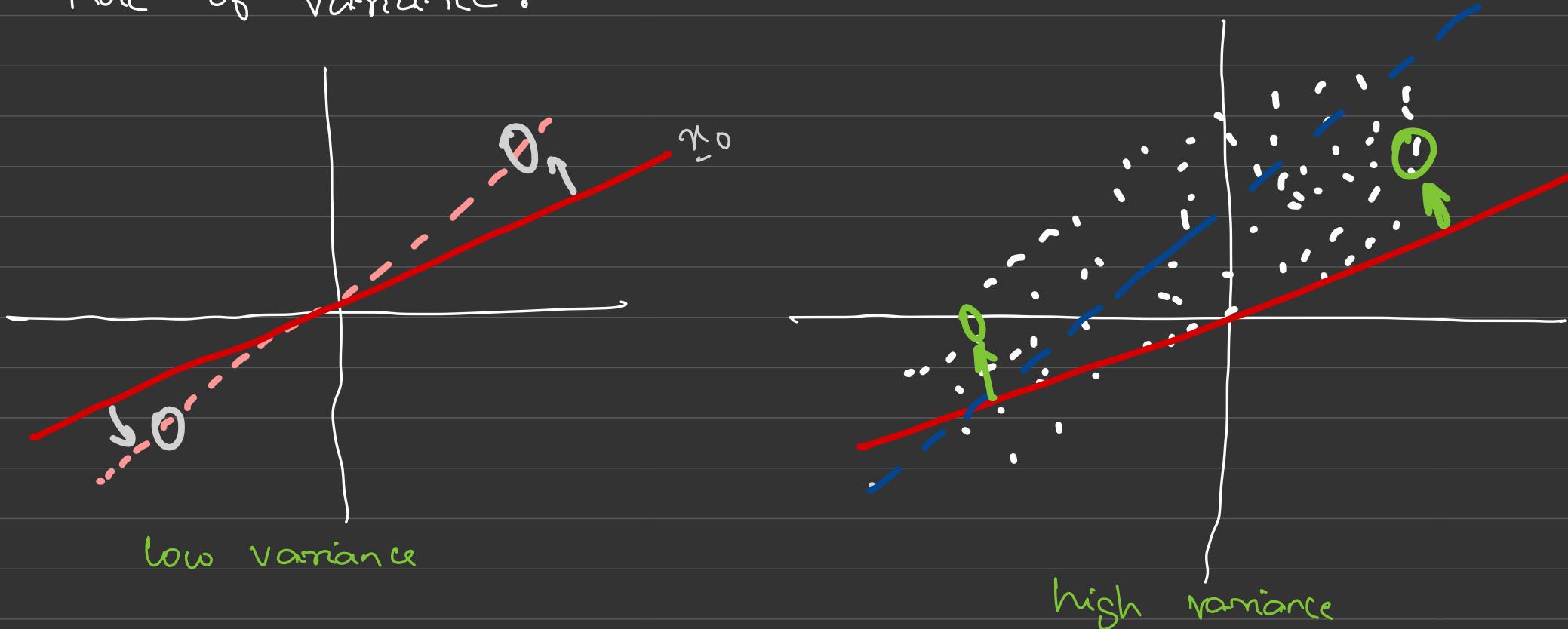
$$\underline{x}_{t+1} = \underline{x}_t - \gamma_t \nabla_{\underline{x}} f_{i_t} (\underline{x}; \{x_i, y_i\})$$

Pros:

+ Exploits data more
efficiently than
batch methods

+ Fast initial improvement
with low per-iteration cost
(data usually has a lot
of redundancy)

Role of variance :



Unbiasedness and the vanilla analysis:

Recall: In gradient descent, we could lower bound

$$\underline{g}_t^\top (\underline{x}_t - \underline{x}^*) \geq f(\underline{x}_t) - f(\underline{x}^*)$$

but now we cannot as $\tilde{\underline{g}}_t$ may be far from being the true gradient.

• So inequality $f(\underline{x}_t) - f(\underline{x}^*) \leq \tilde{\underline{g}}_t^\top (\underline{x} - \underline{x}^*)$

(from convexity) may not hold.

We have

$$\mathbb{E} [\underline{g}_t \mid \underline{x}_t = \underline{x}] = \frac{1}{n} \sum_{j=1}^n \nabla f_j(\underline{x}) = \nabla f(\underline{x})$$

Conditional expectation of \underline{g}_t
given the event $\{\underline{x} = \underline{x}_t\}$.

$$\text{if } \underline{x} \in \mathbb{R}^d$$

$$\Rightarrow \mathbb{E} \left[g_t^\top (\underline{x} - \underline{x}^*) \mid \underline{x}_t = \underline{x} \right] =$$

$$\mathbb{E} \left[g_t^\top \mid \underline{x}_t = \underline{x} \right] (\underline{x} - \underline{x}^*) = \nabla f^\top(\underline{x}) (\underline{x} - \underline{x}^*)$$

• $\{\underline{x}_t = \underline{x}\}$ can occur only for \underline{x} in finite set X

$$\mathbb{E} \left[g_t^\top (\underline{x}_t - \underline{x}^*) \right]$$

$$= \sum_{\underline{x} \in X} \mathbb{E} \left[g_t^\top (\underline{x} - \underline{x}^*) \mid \underline{x}_t = \underline{x} \right] \text{prob} (\underline{x}_t = \underline{x})$$

$$= \sum_{x \in X} \nabla f^\top(x) (\underline{x} - \underline{x}^*) \text{prob} (\underline{x}_t = \underline{x})$$

$$= \mathbb{E} \left[\nabla f^\top(\underline{x}_t) (\underline{x}_t - \underline{x}^*) \right]$$

$$\Rightarrow \mathbb{E} \left[\tilde{g}_t^\top (\underline{x}_t - \underline{x}^*) \right] = \mathbb{E} \left[\nabla f^\top(\underline{x}_t) (\underline{x}_t - \underline{x}^*) \right]$$

$$\geq \mathbb{E} \left[f(\underline{x}_t) - f(\underline{x}^*) \right]$$

So the lower bound holds in expectation.