

- lower bound on  $f^*$
- Duality : Lagrangian, dual function, dual problem
- Slater's conditions, strong duality
- KKT conditions.

$$\underset{x}{\text{minimize}} \quad f(x)$$

$$\text{s.t.} \quad \underline{x} \in C$$

Suppose we want to find a lower bound

$$B \leq f(x^*) \implies f^* \geq B$$

how can we do that?

Example:

①

$$\underset{x, y}{\text{minimize}} \quad x + y$$

$$\text{s.t.} \quad \begin{aligned} x + y &\geq 2 \\ x, y &\geq 0 \end{aligned}$$

$$\implies B = 2$$

②

$$\underset{x, y}{\text{minimize}} \quad x + 3y$$

$$\text{s.t.} \quad \begin{aligned} x + y &\geq 2 \\ x, y &\geq 0 \end{aligned}$$

$$\left. \begin{array}{l} x + y \geq 2 \\ + \quad 2y \geq 0 \\ \hline x + 3y \geq 2 \end{array} \right\} \implies B = 2$$

$$\begin{array}{l}
 \text{minimize} \\
 x, y
 \end{array}
 \quad
 \begin{array}{l}
 px + qy \\
 x + y \geq 2 \\
 x, y \geq 0
 \end{array}
 \quad
 \left.
 \begin{array}{l}
 \text{Lower bound:} \\
 a + b = p \\
 a + c = q \\
 a, b, c \geq 0
 \end{array}
 \right\}
 \begin{array}{l}
 a(x+y) + bx + cy \\
 \geq 2 \quad \geq 0 \quad \geq 0 \\
 B = 2a
 \end{array}$$

So the best lower bound is obtained by

$  \begin{array}{l}  \text{maximize} \\  a, b, c  \end{array}  \quad  2a  $
$  \begin{array}{l}  a + b = p \\  a + c = q \\  a, b, c \geq 0  \end{array}  $

This is called the dual problem (dual LP)

- Number of variables in the dual problem = no. of constraints in the primal problem.

# Lagrangian :

Standard form problem (not necessarily convex)

$$\begin{array}{ll} \underset{\underline{x}}{\text{minimize}} & f(\underline{x}) \\ \text{subject to} & h_i(\underline{x}) \leq 0 \quad i=1, \dots, m \end{array}$$

• Call  $f(\underline{x}^*) = p^*$

$$l_j(\underline{x}) = 0 \quad j=1, \dots, r$$

Define Lagrangian as

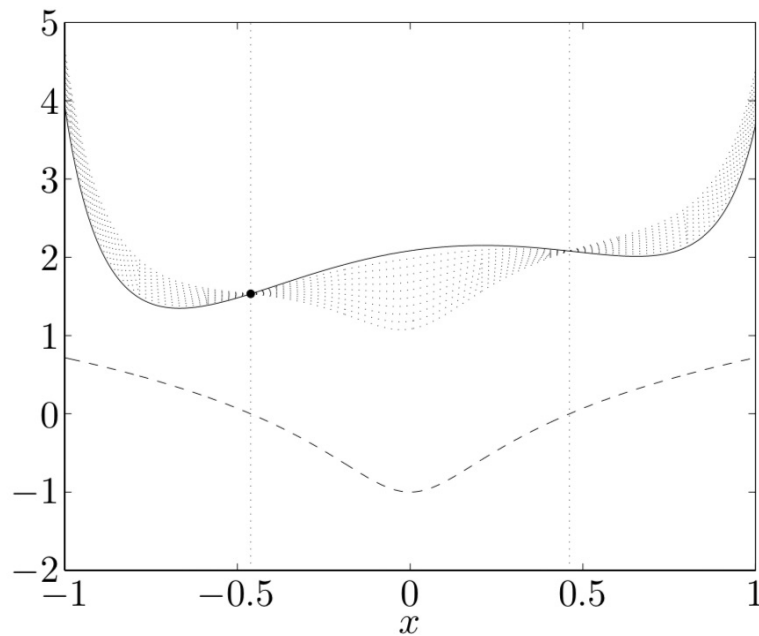
$$L(\underline{x}, \underline{u}, \underline{v}) = f(\underline{x}) + \sum_{i=1}^m \underbrace{u_i}_{\leq 0} h_i(\underline{x}) + \sum_{j=1}^r \underbrace{v_j}_{=0} l_j(\underline{x}) \quad \text{at feasible } \underline{x}$$

• New variables :  $\underline{u} \in \mathbb{R}^m$  and  $\underline{v} \in \mathbb{R}^r$

$$\underline{u} \geq 0 \quad (\text{else } L(\underline{x}, \underline{u}, \underline{v}) = -\infty)$$

- We have, for each feasible  $x$ :

$$f(x) \geq L(x, \underline{u}, \underline{v})$$



- Solid line is  $f$
- Dashed line is  $h$ , hence feasible set  $\approx [-0.46, 0.46]$
- Each dotted line shows  $L(x, u, v)$  for different choices of  $u \geq 0$

(From B & V page 217)

Lagrangian dual function:

Minimizing  $L(\underline{x}, \underline{u}, \underline{v})$  over all  $\underline{x}$  gives a lower bound on the primal optimal value  $f^*$

$$f^* \geq \underset{\underline{x} \in C}{\text{minimize}} L(\underline{x}, \underline{u}, \underline{v}) \geq \underbrace{\underset{\underline{x}}{\text{minimize}} L(\underline{x}, \underline{u}, \underline{v})}_{= g(\underline{u}, \underline{v})}$$

Lagrangian dual  
function

$$g(\underline{u}, \underline{v}) = \inf_{\underline{x} \in \text{dom}(f)} L(\underline{x}, \underline{u}, \underline{v})$$
$$= \min_{\underline{x} \in \text{dom}(f)} \left\{ \left( f(\underline{x}) + \sum_{i=1}^m u_i h_i(\underline{x}) + \sum_{i=1}^r v_i l_i(\underline{x}) \right) \right\}$$

- $g(\underline{u}, \underline{v})$  is concave (even when the primal is not convex)

$$g(\underline{u}, \underline{v}) = - \max_{\underline{x}} \left\{ -f(\underline{x}) - \sum_{i=1}^m u_i h_i(\underline{x}) - \sum_{i=1}^r v_i d_i(\underline{x}) \right\}$$

pointwise max. of convex functions  
in  $(\underline{u}, \underline{v})$

- lower bound property:  $\underline{u} \geq 0$ , then  $g(\underline{u}, \underline{v}) \leq p^*$

if  $\tilde{\underline{x}}$  is feasible and  $\underline{u} \geq 0$ , then

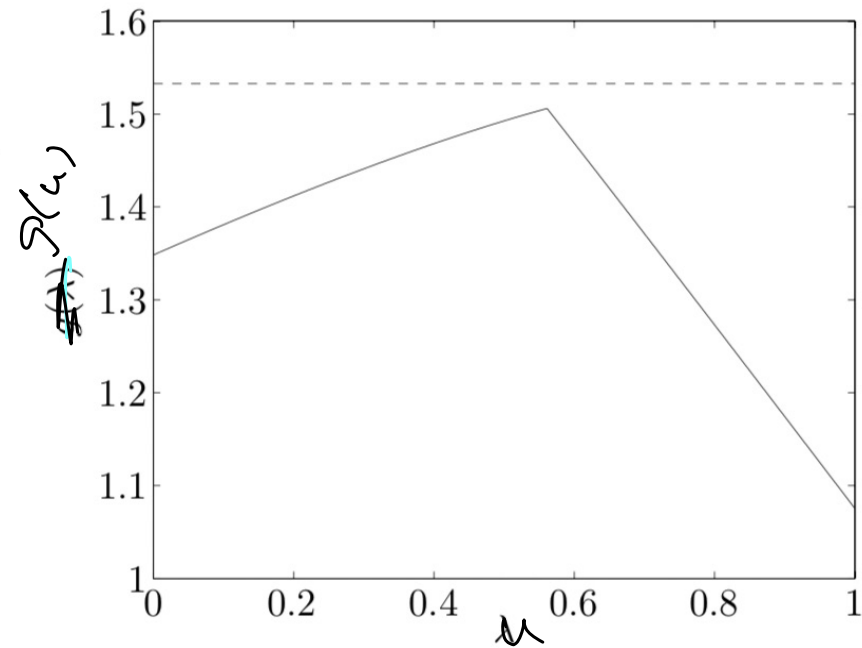
$$g(\underline{u}, \underline{v}) \leq f(\tilde{\underline{x}})$$

$$f(\tilde{\underline{x}}) \geq L(\tilde{\underline{x}}, \underline{u}, \underline{v}) \geq \inf_{\underline{x} \in \text{dom } f} L(\underline{x}, \underline{u}, \underline{v}) = g(\underline{u}, \underline{v})$$

minimize over all feasible  $\tilde{\underline{x}}$  gives  $p^* \geq g(\underline{u}, \underline{v})$ .

$u$  and  $v$  are dual feasible  
dual variables.

- Dashed horizontal line is  $f^*$
  - Dual variable  $\lambda$  is (our  $u$ )
  - Solid line shows  $g(\lambda)$
- (From B & V page 217)





# Lagrange dual problem:

$$p^* \geq g(\underline{u}, \underline{v}) \quad \text{for any } \underline{u} \geq 0 \text{ and } \underline{v}$$

Hence the best lower bound is obtained  
by solving the Lagrange dual problem

Conver  
optimization  
problem

$$\begin{aligned} & \text{maximize} && g(\underline{u}, \underline{v}) \\ & \text{s.t.} && \underline{u} \geq 0 \end{aligned}$$

$$g: \mathbb{R}^m \times \mathbb{R}^r \rightarrow \mathbb{R}$$

Weak duality:

$$p^* \geq g^*$$

$g^*$  is dual optimal value

Example: Quadratic program

$$\text{minimize} \quad \frac{1}{2} \underline{x}^T Q \underline{x} + \underline{c}^T \underline{x}$$

$$\text{s.t.} \quad A \underline{x} = b, \quad \underline{x} \geq 0$$

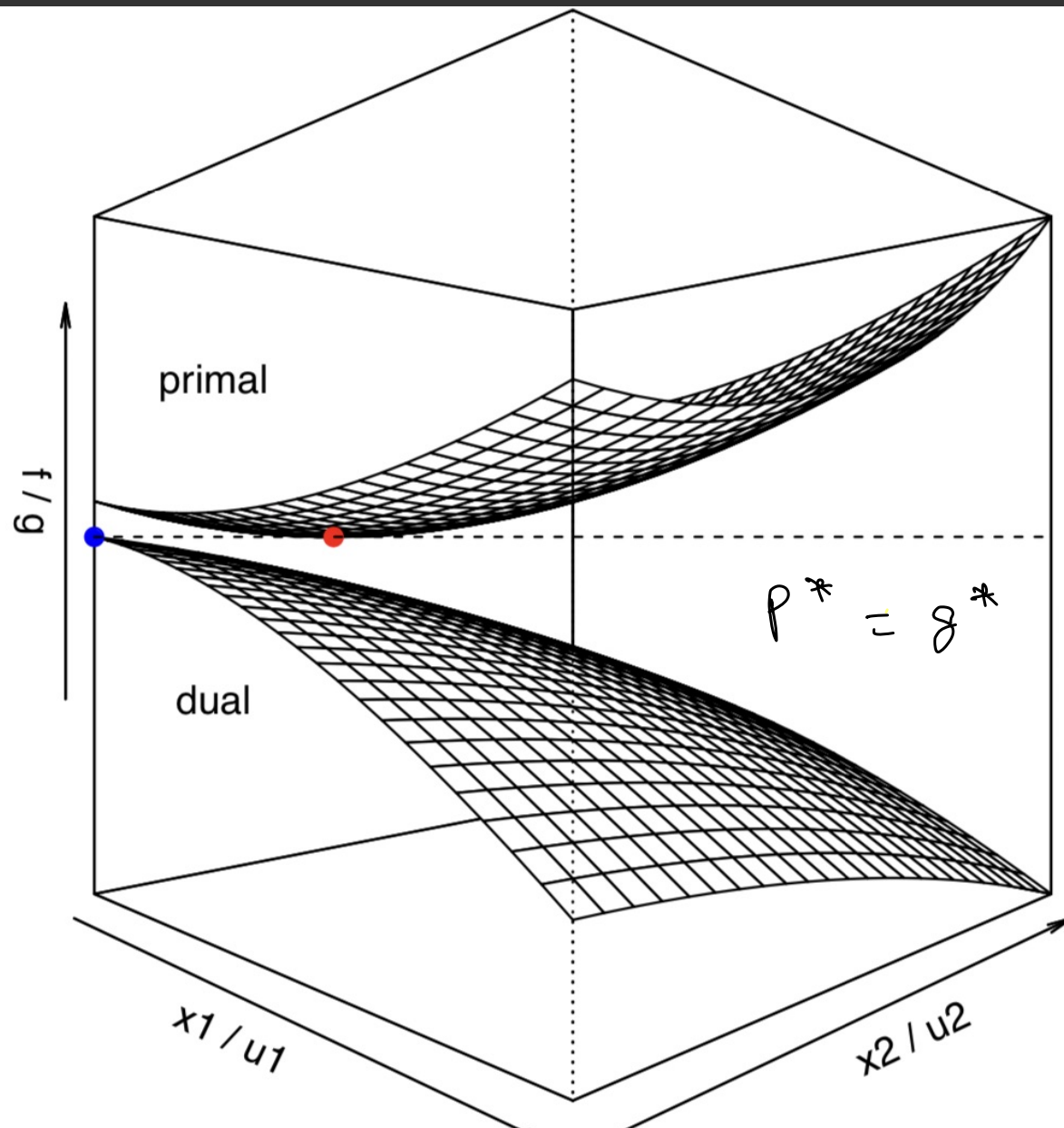
with  $Q \succ 0$

$$\bullet \quad L(\underline{x}, \underline{u}, \underline{v}) = \frac{1}{2} \underline{x}^T Q \underline{x} + \underline{c}^T \underline{x} - \underline{u}^T \underline{x} + \underline{v}^T (A \underline{x} - b)$$

$$\bullet \quad g(\underline{u}, \underline{v}) = \inf_{\underline{x}} L(\underline{x}, \underline{u}, \underline{v}) \\ = -\frac{1}{2} (\underline{c} - \underline{u} + A^T \underline{v})^T Q^{-1} (\underline{c} - \underline{u} + A^T \underline{v}) - b^T \underline{v}$$

$$\left. \begin{aligned} Q \underline{x} + \underline{c} - \underline{u} + A^T \underline{v} &= 0 \\ \underline{x} &= -Q^{-1} (\underline{c} - \underline{u} + A^T \underline{v}) \end{aligned} \right\}$$

# Quadratic in 2 variables



Strong duality:

$$p^* = g^*$$

Slater's conditions: if primal is a convex problem with at least one strictly feasible  $\underline{x} \in \mathbb{R}^n$

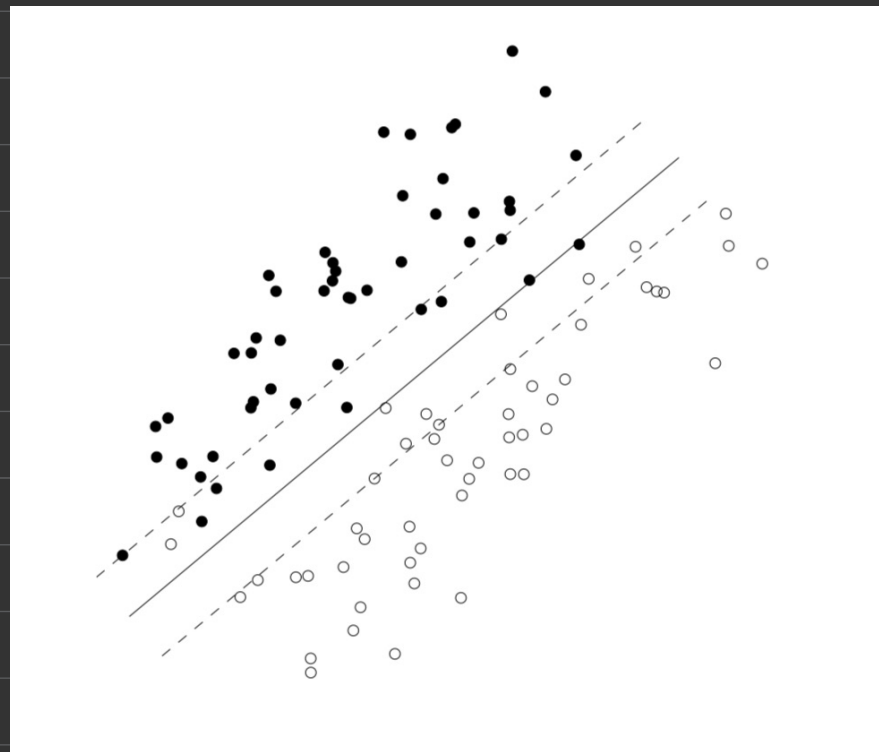
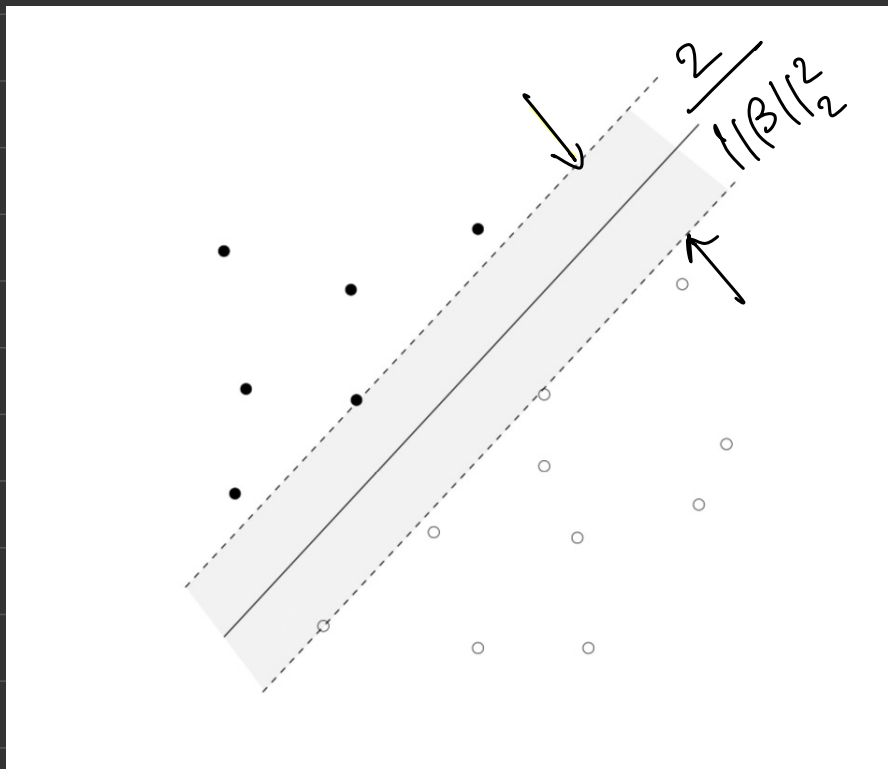
i.e.,

$$h_1(\underline{x}) < 0, \dots, h_m(\underline{x}) < 0$$

$$l_1(\underline{x}) = 0, \dots, l_r(\underline{x}) = 0$$

then strong duality holds.

Example: Support vector machine classifier



Given  $y \in \{1, -1\}^n$ ,  $X: n \times p$  with rows  $\{x_i\}$

minimize  $\frac{1}{2} \|\beta\|_2^2 + C \sum_{i=1}^n \xi_i$   
 $\beta, \beta_0, \xi_i$

s.t.  $\xi_i \geq 0$

$y_i (x_i^T \beta + \beta_0) \geq 1 - \xi_i \quad i=1, \dots, n$

Lagrangian:

$$L(\underline{\beta}, \beta_0, \underline{\xi}, \underline{v}, \underline{\omega}) = \frac{1}{2} \|\underline{\beta}\|^2 + C \sum_{i=1}^n \xi_i - \sum_{i=1}^n v_i \xi_i + \sum_{i=1}^n \omega_i (1 - \xi_i - y_i (\underline{x}_i^T \underline{\beta} + \beta_0))$$

Dual function:

$$g(\underline{v}, \underline{\omega}) = \begin{cases} -\frac{1}{2} \underline{\omega}^T \tilde{X} \tilde{X}^T \underline{\omega} + \underline{1}^T \underline{\omega} & \text{if } \underline{\omega} = C \underline{1} - \underline{v} \\ & \underline{\omega}^T \underline{y} = 0 \\ -\infty & \text{O. w.} \end{cases}$$

$$\tilde{X} = \text{diag}(\underline{y}) X$$

SVM dual: (eliminating slack variable  $\underline{v}$ ):

$$\underset{\underline{w}}{\text{maximize}} \quad -\frac{1}{2} \underline{w}^T \tilde{X} \tilde{X}^T \underline{w} + \underline{1}^T \underline{w}$$

$$0 \leq \underline{w} \leq c \underline{1}, \quad \underline{w}^T \underline{y} = 0$$

Slater's condition is satisfied, we have strong duality

$$\underline{\beta} = \tilde{X}^T \underline{w}$$

## Duality gap:

Given primal feasible  $\underline{x}$  and dual feasible  $\underline{u}, \underline{v}$ :

$$\underline{\text{duality gap}}: \quad f(\underline{x}) - g(\underline{u}, \underline{v})$$

We have

$$f(x) - f(\underline{x}^*) \leq f(\underline{x}) - g(\underline{u}, \underline{v})$$

if  $f(x) - g(x, v) = 0$ , then  $x$  is primal optimal (and  $\underline{u}$  &  $\underline{v}$  are dual optimal)



Karush - Kuhn - Tucker conditions:  
(KKT)

$$\underset{\underline{x}}{\text{minimize}} \quad f(\underline{x})$$

$$\text{s. to} \quad h_i(\underline{x}) \leq 0, \quad i=1, \dots, m$$
$$l_j(\underline{x}) = 0 \quad j=1, \dots, r$$

KKT conditions:

① Stationarity:  $\underline{0} \in \partial_{\underline{x}} \left( f(\underline{x}) + \sum_{i=1}^m u_i h_i(\underline{x}) + \sum_{j=1}^r v_j l_j(\underline{x}) \right)$

② Complementary Slackness:  $u_i h_i(\underline{x}) = 0 \quad i=1, \dots, m$

③ Primal feasibility:  $h_i(\underline{x}) \leq 0 ; l_j(\underline{x}) = 0 \quad \forall i, j$

④ Dual feasibility:  $u_i \geq 0 \quad \forall i$

For a problem with strong duality (i.e., Slater's condition holds):

$x^*$  and  $\underline{u}^*, \underline{v}^*$  are primal and dual solutions



$\underline{x}^*$  and  $\underline{u}^*, \underline{v}^*$  satisfy the KKT conditions.

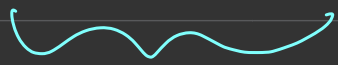
① if  $\underline{x}^*$  &  $\underline{u}^*, \underline{v}^*$  are primal and dual solutions  
with zero duality gap:

$$\begin{aligned} f(\underline{x}^*) &= g(\underline{u}^*, \underline{v}^*) \\ &= \min_{\underline{x}} \left\{ f(\underline{x}) + \sum_{i=1}^m u_i^* h_i(\underline{x}) + \sum_{j=1}^r v_j^* l_j(\underline{x}) \right\} \\ &\leq f(\underline{x}^*) + \sum_{i=1}^m u_i^* h_i(\underline{x}^*) + \sum_{j=1}^r v_j^* l_j(\underline{x}^*) \\ &\leq f(\underline{x}^*) \end{aligned}$$

Two inequalities hold with equality:

$$\Rightarrow \underline{x}^* \text{ minimizes } L(\underline{x}, \underline{u}^*, \underline{v}^*) \quad \left[ \text{Stationary condition} \right]$$

$$\Rightarrow u_i^* h_i(\underline{x}^*) = 0 \quad \text{or} \\ u_i^* > 0 \Rightarrow h_i(\underline{x}^*) = 0 ; \quad h_i(\underline{x}^*) < 0 \Rightarrow u_i^* = 0$$

  
 active constraint

[complementary  
 slackness]

② If there exists  $\underline{x}^*$  and  $\underline{u}^*, \underline{v}^*$  that satisfy the KKT condn.

$$g(\underline{u}^*, \underline{v}^*) = f(\underline{x}^*) + \sum_{i=1}^m u_i h_i(\underline{x}^*) + \sum_{j=1}^r v_j l_j(\underline{x}^*)$$

(Stationarity)

$$= f(\underline{x}^*)$$

(complementary slackness)

Thus duality gap is zero.

Example: minimize  $\underline{x}$   $\frac{1}{2} \underline{x}^T Q \underline{x} + \underline{c}^T \underline{x}$

s.t.  $A \underline{x} = \underline{b}$

KKT:  $\mathcal{L}(\underline{x}, \underline{v}) = \frac{1}{2} \underline{x}^T Q \underline{x} + \underline{c}^T \underline{x} + \underline{v}^T (A \underline{x} - \underline{b})$

$$A \underline{x}^* = \underline{b}$$

$$Q \underline{x} + \underline{c} + A^T \underline{v}^* = \underline{0}$$

$$\begin{bmatrix} Q & A^T \\ A & 0 \end{bmatrix} \begin{bmatrix} \underline{x}^* \\ \underline{v}^* \end{bmatrix} = \begin{bmatrix} -\underline{c} \\ \underline{b} \end{bmatrix}$$

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minimize  $\underline{x}$   $f(\underline{x}) \approx \left. \begin{array}{l} \frac{1}{2} \underline{x}_t^T Q \underline{x}_t + \underline{c}^T \underline{x}_t \\ A \underline{x} = \underline{b} \end{array} \right\}$

## Example: SVM

Given  $y \in \{1, -1\}^n$ ,  $X: n \times p$  with rows  $\{x_i\}$

$$\text{minimize} \quad \frac{1}{2} \|\beta\|_2^2 + C \sum_{i=1}^n \xi_i$$

$$\beta, \beta_0, \xi$$

s.t.

$$\xi_i \geq 0$$

$$y_i (x_i^T \beta + \beta_0) \geq 1 - \xi_i \quad i=1, \dots, n$$

Dual variables:  $\underline{v}$ ,  $\underline{w}$

$$0 = \sum_{i=1}^n w_i y_i; \quad \beta = \sum_{i=1}^n w_i y_i x_i, \quad \underline{w} = C \underline{1} - \underline{v}$$

Complementary slackness:

$$v_i \xi_i = 0; \quad w_i (1 - \xi_i - y_i (x_i^T \beta + \beta_0)) = 0$$

$$i=1, \dots, n$$

At optimality we have,

$$\underline{\beta} = \sum_{i=1}^n w_i y_i \underline{x}_i = \tilde{X}^T \underline{w}$$

and

$w_i \neq 0$  only if  $y_i (\underline{x}_i^T \underline{\beta} + \beta_0) = 1 - \xi_i$ .

Such points are called support points

