E9 211: Adaptive Signal Processing

Newton's Method



- 1. Newton's Method
- 2. Stability condition
- 3. Convergence rate

Newton's method

Let us consider the quadratic cost function

$$J(\mathbf{w}) = J_0 + (\mathbf{w} - \mathbf{w}_0)^{\mathrm{H}} \mathbf{R}_x(\mathbf{w} - \mathbf{w}_0)$$

and an iterative algorithm where the update equation is given by

$$\mathbf{w}^{(k+1)} = \mathbf{w}^{(k)} + \mu \mathbf{p}$$

• Let us recall that a necessary condition for $J(\mathbf{w}^{(k+1)}) < J(\mathbf{w}^{(k)})$ is to choose the descent direction \mathbf{p} such that

$$\operatorname{Re}[\nabla J(\mathbf{w}^{(k)})^{\mathrm{H}}\mathbf{p}] < 0$$

This can be obtained by choosing

$$\mathbf{p} = -\mathbf{B}
abla J(\mathbf{w}^{(k)})$$
 for any $\mathbf{B} > \mathbf{0}$

- For the steepest descent, we simply chose $\mathbf{B} = \mathbf{I}$.
- ▶ Instead, we can choose $\mathbf{B} = [\nabla^2 J(\mathbf{w}^{(k)})]^{-1}$ where $\nabla^2 J(\mathbf{w}^{(k)})$ is the *Hessian* matrix of the cost function $J(\mathbf{w})$ evaluated at $\mathbf{w} = \mathbf{w}^{(k)}$.
- ► This leads to the Newton's method.
- Update equation for the Newton's method is given by

$$\mathbf{w}^{(k+1)} = \mathbf{w}^{(k)} - \mu [\nabla^2 J(\mathbf{w}^{(k)})]^{-1} \nabla J(\mathbf{w}^{(k)})$$

Newton's method

► For the quadratic cost function

$$J(\mathbf{w}) = J_0 + (\mathbf{w} - \mathbf{w}_0)^{\mathrm{H}} \mathbf{R}_x(\mathbf{w} - \mathbf{w}_0),$$

we have

$$abla J(\mathbf{w}^{(k)}) = \mathbf{R}_x \mathbf{w}^{(k)} - \mathbf{r}_{xy}$$
 and $abla^2 J(\mathbf{w}^{(k)}) = \mathbf{R}_x$

Newton's method update equation is given by

$$\mathbf{w}^{(k+1)} = \mathbf{w}^{(k)} - \mu \mathbf{R}_x^{-1} (\mathbf{R}_x \mathbf{w}^{(k)} - \mathbf{r}_{xy})$$
$$= \mathbf{w}^{(k)} - \mu \mathbf{R}_x^{-1} \mathbf{R}_x \mathbf{w}^{(k)} + \mu \mathbf{R}_x^{-1} \mathbf{r}_{xy}$$
$$= \mathbf{w}^{(k)} - \mu \mathbf{w}^{(k)} + \mu \mathbf{w}_0$$

Newton's method - stability

▶ Let us define the weight error $e^{(k)} = w^{(k)} - w_0$. Then,

$$\mathbf{w}^{(k+1)} = \mathbf{w}^{(k)} - \mu(\mathbf{w}^{(k)} - \mu\mathbf{w}_0)$$
$$\mathbf{w}_0 = \mathbf{w}_0$$
$$\mathbf{e}^{(k+1)} = \mathbf{e}^{(k)} - \mu\mathbf{e}^{(k)}$$

We obtain the first-order matrix difference equation as

$$\mathbf{e}^{(k+1)} = (\mathbf{I} - \mu \mathbf{I})\mathbf{e}^{(k)}$$
$$= (\mathbf{I} - \mu \mathbf{I})^{(k+1)}\mathbf{e}^{(0)}$$
$$= (1 - \mu)^{(k+1)}\mathbf{e}^{(0)}$$

which is stable if $(1-\mu)^{(k)} \to 0$.

Newton's method - stability

 \blacktriangleright The iterations will converge to optimum (i.e., $\mathbf{w}^{(k)}
ightarrow \mathbf{w}_0$) if

$$||\mathbf{e}^{(k)}|| \to 0 \implies |1-\mu| < 1.$$

This means that the Newton's method will converge if

$$-1 < 1 - \mu < 1 \implies 0 < \mu < 2$$

- Unlike the SGD, the choice of step size µ for the convergence of Newton's method is not depending on the eigen values of R_x.
- ln other words, the choice of step size μ to ensure convergence, does not depend on data.
- ► Special case : Newton's method converges in 1 iteration for quadratic cost functions if we choose µ = 1.

- All entries of $e^{(k)}$ converge at the same rate.
- ► The time constant can be computed as

$$|1-\mu|^{\tau} = rac{1}{e} \implies \tau = rac{-1}{\ln|1-\mu|} \approx rac{1}{\mu}$$
 (For small μ)

Time constant is indepnedent of data.