

E9 211: Adaptive Signal Processing

Lecture 2: Linear Algebra



Outline

1. Definitions
2. Subspaces
3. Projection

- ▶ A N -dimensional vector is assumed to be a column vector:

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_N \end{bmatrix}$$

- ▶ Complex conjugate (Hermitian) transpose

$$\mathbf{x}^H = (\mathbf{x}^T)^* = [x_1^*, x_2^*, \dots, x_N^*]$$

- ▶ For a discrete-time signal $x(n)$, we will use the following vectors

$$\mathbf{x} = \begin{bmatrix} x(0) \\ x(1) \\ \vdots \\ x(N-1) \end{bmatrix} \quad \mathbf{x}_n = \begin{bmatrix} x(n) \\ x(n-1) \\ \vdots \\ x(n-N+1) \end{bmatrix}$$

Matrices

- ▶ An $N \times M$ matrix has N rows and M columns:

$$\mathbf{A} = [a_{ij}] = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1M} \\ a_{21} & a_{22} & \cdots & a_{2M} \\ \vdots & \vdots & & \vdots \\ a_{N1} & a_{N2} & \cdots & a_{NM} \end{bmatrix}$$

- ▶ Complex conjugate (Hermitian) transpose

$$\mathbf{A}^H = (\mathbf{A}^T)^* = (\mathbf{A}^*)^T$$

- ▶ Hermitian matrix

$$\mathbf{A} = \mathbf{A}^H$$

E.g.,

$$\mathbf{A} = \begin{bmatrix} 1 & 1+j \\ 1-j & 1 \end{bmatrix}, \quad \text{then} \quad \mathbf{A}^H = \begin{bmatrix} 1 & 1+j \\ 1-j & 1 \end{bmatrix} = \mathbf{A}$$

Vector norms: $\|\mathbf{x}\|_p = \left(\sum_{i=1}^N |x_i|^p\right)^{1/p}$, for $p = 1, 2, \dots$

- ▶ $\|\mathbf{x}\|_p \geq 0$ when $\mathbf{x} \neq \mathbf{0}$ and $\|\mathbf{x}\|_p = 0$ iff $\mathbf{x} = \mathbf{0}$
- ▶ $\|\alpha\mathbf{x}\|_p = \alpha\|\mathbf{x}\|_p$ for any scalar α
- ▶ $\|\mathbf{x} + \mathbf{y}\|_p \leq \|\mathbf{x}\|_p + \|\mathbf{y}\|_p$

Examples:

Euclidean (2-norm): $\|\mathbf{x}\|_2 = \left(\sum_{i=1}^N |x_i^* x_i|\right)^{1/2} = (\mathbf{x}^H \mathbf{x})^{1/2}$

1-norm: $\|\mathbf{x}\|_1 = \sum_{i=1}^N |x_i|$

∞ -norm: $\|\mathbf{x}\|_\infty = \max_i |x_i|$

Inner product:

$$\langle \mathbf{x}, \mathbf{y} \rangle = \mathbf{x}^H \mathbf{y} = \sum_{i=1}^N x_i^* y_i$$

- ▶ Two vectors are *orthogonal* if $\langle \mathbf{x}, \mathbf{y} \rangle = 0$; if the vectors have unit norm, then they are *orthonormal*
- ▶ Cauchy-Schwarz: $|\langle \mathbf{x}, \mathbf{y} \rangle| \leq \|\mathbf{x}\| \|\mathbf{y}\|$

$$\langle \mathbf{x}, \mathbf{y} \rangle = \|\mathbf{x}\| \|\mathbf{y}\| \cos \theta$$

θ is the angle between the two vectors. Since $|\cos \theta| \leq 1$, the above inequality follows.

- ▶ $2|\langle \mathbf{x}, \mathbf{y} \rangle| \leq \|\mathbf{x}\|^2 + \|\mathbf{y}\|^2$ as

$$\|\mathbf{x} \pm \mathbf{y}\|^2 = \|\mathbf{x}\|^2 + \|\mathbf{y}\|^2 \pm 2\langle \mathbf{x}, \mathbf{y} \rangle \geq 0$$

For $\mathbf{A} \in \mathbb{C}^{M \times N}$

- ▶ **2-norm** (spectral norm, operator norm):

$$\|\mathbf{A}\| := \max_{\mathbf{x}} \frac{\|\mathbf{A}\mathbf{x}\|}{\|\mathbf{x}\|} \quad \text{or} \quad \|\mathbf{A}\|^2 := \max_{\mathbf{x}} \frac{\mathbf{x}^H \mathbf{A}^H \mathbf{A} \mathbf{x}}{\mathbf{x}^H \mathbf{x}}$$

Largest magnification that can be obtained by applying \mathbf{A} to any vector

- ▶ **Forbenius norm**

$$\|\mathbf{A}\|_F := \left(\sum_{i=1}^M \sum_{j=1}^N |a_{ij}|^2 \right)^{1/2}$$

Represents energies in its entries

Linear independence, vector spaces, and basis vectors

Linear independence

- ▶ A collection of N vectors $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N$ is called *linearly independent* if

$$\alpha_1 \mathbf{x}_1 + \alpha_2 \mathbf{x}_2 + \dots + \alpha_N \mathbf{x}_N = \mathbf{0} \quad \Leftrightarrow \quad \alpha_1 = \alpha_2 = \dots = \alpha_N = 0$$

Rank

- ▶ The rank of \mathbf{A} is the number of independent columns or rows of \mathbf{A}

Prototype rank-1 matrix: $\mathbf{A} = \mathbf{a}\mathbf{b}^H$

Prototype rank-2 matrix: $\mathbf{A} = \mathbf{a}\mathbf{b}^H + \mathbf{c}\mathbf{d}^H$

- ▶ The ranks of \mathbf{A} , $\mathbf{A}\mathbf{A}^H$, and $\mathbf{A}^H\mathbf{A}$ are the same
- ▶ If \mathbf{A} is square and full rank, there is a unique inverse \mathbf{A}^{-1} such that

$$\mathbf{A}\mathbf{A}^{-1} = \mathbf{A}^{-1}\mathbf{A} = \mathbf{I} = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & & \vdots \\ 0 & 0 & \dots & 1 \end{bmatrix}$$

- ▶ An $N \times N$ matrix \mathbf{A} has rank N , then \mathbf{A} is invertible $\Leftrightarrow \det(\mathbf{A}) \neq 0$ **8**

Subspaces

- ▶ The space \mathcal{H} spanned by a collection of vectors $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N$

$$\mathcal{H} := \{\alpha_1 \mathbf{x}_1 + \alpha_2 \mathbf{x}_2 + \dots + \alpha_N \mathbf{x}_N \mid \alpha_i \in \mathbb{C}, \forall i\}$$

is called a *linear subspace*

- ▶ If the vectors are linearly independent they are called a *basis* for the subspace
- ▶ The number of basis vectors is called the *dimension* of the subspace
- ▶ If the vectors are orthogonal, then we have an *orthogonal basis*
- ▶ If the vectors are orthonormal, then we have an *orthonormal basis*

Fundamental subspaces of \mathbf{A}

- ▶ Range (column span) of $\mathbf{A} \in \mathbb{C}^{M \times N}$

$$\text{ran}(\mathbf{A}) = \{\mathbf{Ax} : \mathbf{x} \in \mathbb{C}^N\} \subset \mathbb{C}^M$$

The dimension of $\text{ran}(\mathbf{A})$ is rank of \mathbf{A} , denoted by $\rho(\mathbf{A})$

- ▶ Kernel (row null space) of $\mathbf{A} \in \mathbb{C}^{M \times N}$

$$\text{ker}(\mathbf{A}) = \{\mathbf{x} \in \mathbb{C}^N : \mathbf{Ax} = \mathbf{0}\} \subset \mathbb{C}^N$$

The dimension of $\text{ker}(\mathbf{A})$ is $N - \rho(\mathbf{A})$

- ▶ Four fundamental subspaces

$$\text{ran}(\mathbf{A}) \oplus \text{ker}(\mathbf{A}^H) = \mathbb{C}^M$$

$$\text{ran}(\mathbf{A}^H) \oplus \text{ker}(\mathbf{A}) = \mathbb{C}^N$$

direct sum: $\mathcal{H}_1 \oplus \mathcal{H}_2 = \{\mathbf{x}_1 + \mathbf{x}_2 | \mathbf{x}_1 \in \mathcal{H}_1, \mathbf{x}_2 \in \mathcal{H}_2\}$

Unitary and Isometry

- ▶ A square matrix \mathbf{U} is called *unitary* if $\mathbf{U}^H\mathbf{U} = \mathbf{I}$ and $\mathbf{U}\mathbf{U}^H = \mathbf{I}$
 - ▶ Examples are rotation or reflection matrices
 - ▶ $\|\mathbf{U}\| = 1$; its rows and columns are orthonormal
- ▶ A tall rectangular matrix $\hat{\mathbf{U}}$ is called an *isometry* if $\hat{\mathbf{U}}^H\mathbf{U} = \mathbf{I}$
 - ▶ Its columns are orthonormal basis of a subspace (not the complete space)
 - ▶ $\|\hat{\mathbf{U}}\| = 1$;
 - ▶ There is an orthogonal complement $\hat{\mathbf{U}}^\perp$ of $\hat{\mathbf{U}}$ such that $[\hat{\mathbf{U}} \quad \hat{\mathbf{U}}^\perp]$ is unitary

Projection

- ▶ A square matrix \mathbf{P} is a *projection* if $\mathbf{P}\mathbf{P} = \mathbf{P}$
- ▶ It is an orthogonal projection if $\mathbf{P}^H = \mathbf{P}$
 - ▶ The norm of an orthogonal projection is $\|\mathbf{P}\| = 1$
 - ▶ For an isometry $\hat{\mathbf{U}}$, the matrix $\mathbf{P} = \hat{\mathbf{U}}\hat{\mathbf{U}}^H$ is an orthogonal projection onto the space spanned by the columns of $\hat{\mathbf{U}}$.

- ▶ Suppose $\mathbf{U} = \left[\underbrace{\hat{\mathbf{U}}}_d \quad \underbrace{\hat{\mathbf{U}}^\perp}_{N-d} \right]$ is unitary. Then, from $\mathbf{U}\mathbf{U}^H = \mathbf{I}_N$:

$$\hat{\mathbf{U}}\hat{\mathbf{U}}^H + \hat{\mathbf{U}}^\perp(\hat{\mathbf{U}}^\perp)^H = \mathbf{I}_N, \quad \hat{\mathbf{U}}\hat{\mathbf{U}}^H = \mathbf{P}, \quad \hat{\mathbf{U}}^\perp(\hat{\mathbf{U}}^\perp)^H = \mathbf{P}^\perp = \mathbf{I}_N - \mathbf{P}$$

- ▶ Any vector $\mathbf{x} \in \mathbb{C}^N$ can be decomposed as $\mathbf{x} = \hat{\mathbf{x}} + \hat{\mathbf{x}}^\perp$ with $\hat{\mathbf{x}} \perp \hat{\mathbf{x}}^\perp$:

$$\hat{\mathbf{x}} = \mathbf{P}\mathbf{x} \in \text{ran}(\hat{\mathbf{U}}) \quad \hat{\mathbf{x}}^\perp = \mathbf{P}^\perp\mathbf{x} \in \text{ran}(\hat{\mathbf{U}}^\perp)$$

Projection onto the column span of a tall matrix \mathbf{A}

- ▶ Suppose \mathbf{A} has full column rank (i.e., $\mathbf{A}^H \mathbf{A}$ is invertible). Then,

$$\mathbf{P}_A := \mathbf{A}(\mathbf{A}^H \mathbf{A})^{-1} \mathbf{A}^H, \quad \mathbf{P}_A^\perp := \mathbf{I} - \mathbf{A}(\mathbf{A}^H \mathbf{A})^{-1} \mathbf{A}^H$$

are orthogonal projections onto $\text{ran}(\mathbf{A})$ and $\text{ker}(\mathbf{A}^H)$, respectively.

- ▶ To prove, verify that $\mathbf{P}^2 = \mathbf{P}$ and $\mathbf{P}^H = \mathbf{P}$, hence \mathbf{P} is an orthogonal projection.
- ▶ If $\mathbf{b} \in \text{ran}(\mathbf{A})$, then $\mathbf{b} = \mathbf{A}\mathbf{x}$ for some \mathbf{x} :

$$\mathbf{P}_A \mathbf{b} = \mathbf{A}(\mathbf{A}^H \mathbf{A})^{-1} \mathbf{A}^H \mathbf{A} \mathbf{x} = \mathbf{b}$$

so that \mathbf{b} is invariant under \mathbf{P}_A .

- ▶ If $\mathbf{b} \perp \text{ran}(\mathbf{A})$, then $\mathbf{b} \in \text{ker}(\mathbf{A}^H) \Leftrightarrow \mathbf{A}^H \mathbf{b} = \mathbf{0}$:

$$\mathbf{P}_A \mathbf{b} = \mathbf{A}(\mathbf{A}^H \mathbf{A})^{-1} \mathbf{A}^H \mathbf{b} = \mathbf{0}.$$